

# Modelling MAC-Layer Communications in Wireless Systems

## (Extended Abstract)

Andrea Cerone<sup>1</sup>, Matthew Hennessy<sup>1</sup> and Massimo Merro<sup>2</sup>

<sup>1</sup>School of Statistics and Computer Science, Trinity College Dublin

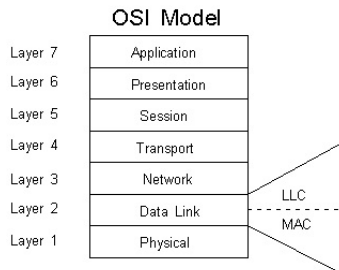
<sup>2</sup>Dipartimento di Informatica, Università di Verona



COORDINATION 2013 - June 4th, Florence

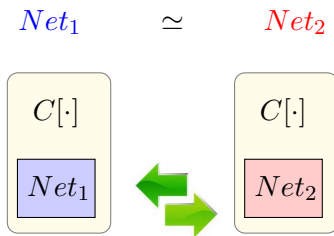
- Calculus of Collision-prone Communicating Processes (CCCP)
- Contextual Equivalence
- Coinductive Characterisation

- **Calculus of Collision-prone Communicating Processes (CCCP)**  
Modelling Networks at the MAC-sublayer of the ISO/OSI reference model
- Contextual Equivalence
- Coinductive Characterisation



Issues: Collisions, Failures of Synchronisations

- Calculus of Collision-prone Communicating Processes (CCCP)
- **Contextual Equivalence**  
Interchange two equivalent networks in a larger one without affecting the overall behaviour
- Coinductive Characterisation



- Calculus of Collision-prone Communicating Processes (CCCP)
- Contextual Equivalence
- **Coinductive Characterisation**  
Determining if two networks are equivalent without having to quantify over contexts

Bisimulation ( $\approx$ ) based proof principle

- Soundness:  
 $Net_1 \approx Net_2$  implies  
 $Net_1 \simeq Net_2$
- Completeness<sup>\*</sup>:  
 $Net_1 \simeq Net_2$  implies  
 $Net_1 \approx Net_2$

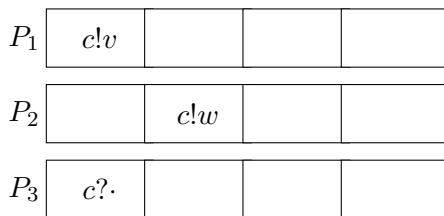
\* Holds for all networks satisfying a natural requirement

# Features of CCCP

- *Broadcast Communication*  
Transmitted messages can be received by multiple stations
- *Discrete Time*  
Activities happen within time slots  
Transmission of messages can require several time slots
- *Collision-prone Communication*  
Error in Reception caused by collisions  
or by missed synchronisations

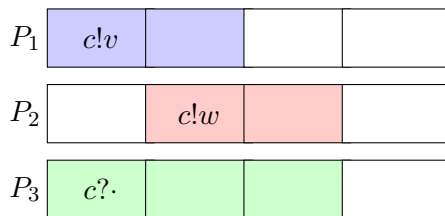
# Features of CCCP

- *Broadcast Communication*  
Transmitted messages can be received by multiple stations
- *Discrete Time*  
Activities happen within time slots  
Transmission of messages can require several time slots
- *Collision-prone Communication*  
Error in Reception caused by collisions  
or by missed synchronisations



# Features of CCCP

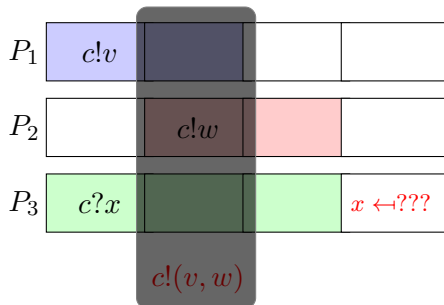
- *Broadcast Communication*  
Transmitted messages can be received by multiple stations
- *Discrete Time*  
Activities happen within time slots  
Transmission of messages can require several time slots
- *Collision-prone Communication*  
Error in Reception caused by collisions  
or by missed synchronisations





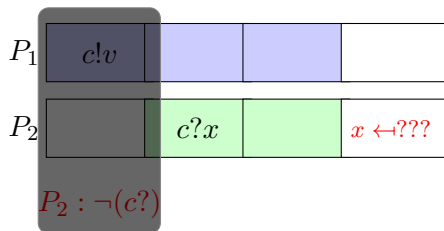
# Features of CCCP

- *Broadcast Communication*  
Transmitted messages can be received by multiple stations
- *Discrete Time*  
Activities happen within time slots  
Transmission of messages can require several time slots
- *Collision-prone Communication*  
**Error in Reception caused by collisions**  
or by missed synchronisations



# Features of CCCP

- *Broadcast Communication*  
Transmitted messages can be received by multiple stations
- *Discrete Time*  
Activities happen within time slots  
Transmission of messages can require several time slots
- *Collision-prone Communication*  
Error in Reception caused by collisions  
or by missed synchronisations



- Channel environment: keeps track of transmission related information  
 $\Gamma \vdash c : (time, val)$
- System term: contains the code executed by stations  
 $W = P_1 \mid \cdots \mid P_n$
- Evolution of a network:  
 $\Gamma_1 \triangleright W_1 \rightarrow \Gamma_2 \triangleright W_2$

- Channel environment: keeps track of transmission related information

$$\Gamma \vdash c : (time, val)$$

- System term: contains the code executed by stations

$$W = P_1 \mid \dots \mid P_n$$

- Evolution of a network:

$$\Gamma_1 \triangleright W_1 \rightarrow \Gamma_2 \triangleright W_2$$

Constructs:

- Output  $c!\langle v \rangle.P$
- Time-out Input  $[c?(x).P]Q$
- Active Receiver  $[c \leftarrow x]P$
- Exposure Check  $[\exp(c)]P, Q$
- Standard Constructs

- Channel environment: keeps track of transmission related information

$$\Gamma \vdash c : (time, val)$$

- System term: contains the code executed by stations

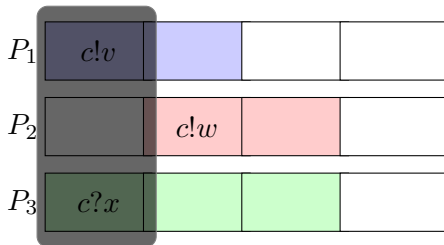
$$W = P_1 \mid \cdots \mid P_n$$

- Evolution of a network:

$$\Gamma_1 \triangleright W_1 \rightarrow \Gamma_2 \triangleright W_2$$

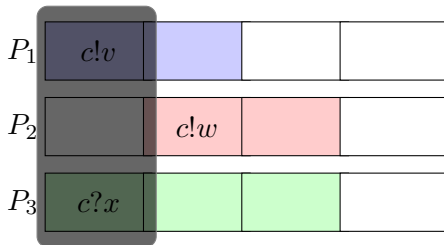
- $\rightarrow_i$ : Instantaneous reduction (within a time slot)
- $\rightarrow_\sigma$ : Passage of time

# Example: Collisions



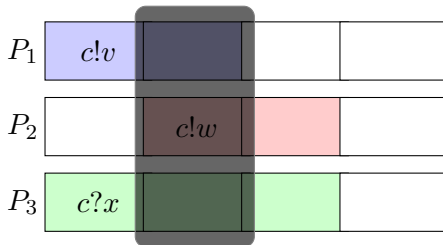
- $\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.c!\langle w \rangle.\text{nil} \mid [c?(x).P]\text{nil} \quad \rightarrow_i$
  - $\Gamma_1 \triangleright \sigma^2.\text{nil} \mid \sigma.c!\langle w \rangle.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$
  - $\Gamma_2 \triangleright \sigma.\text{nil} \mid c!\langle w \rangle.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_i$
  - $\Gamma_3 \triangleright \sigma.\text{nil} \mid \sigma^2.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$
  - $\Gamma_4 \triangleright \text{nil} \mid \sigma.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$
  - $\Gamma_0 \triangleright \text{nil} \mid \text{nil} \mid \{\text{err}/x\}P$
- |                                       |
|---------------------------------------|
| $\Gamma_0 \vdash c : (0, -)$          |
| $\Gamma_1 \vdash c : (2, v)$          |
| $\Gamma_2 \vdash c : (1, v)$          |
| $\Gamma_3 \vdash c : (2, \text{err})$ |
| $\Gamma_4 \vdash c : (1, \text{err})$ |
| $\Gamma_0 \vdash c : (0, -)$          |

# Example: Collisions



- $\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.c!\langle w \rangle.\text{nil} \mid [c?(x).P]\text{nil} \quad \rightarrow_i$
  - $\Gamma_1 \triangleright \sigma^2.\text{nil} \mid \sigma.c!\langle w \rangle.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$
  - $\Gamma_2 \triangleright \sigma.\text{nil} \mid c!\langle w \rangle.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_i$
  - $\Gamma_3 \triangleright \sigma.\text{nil} \mid \sigma^2.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$
  - $\Gamma_4 \triangleright \text{nil} \mid \sigma.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$
  - $\Gamma_0 \triangleright \text{nil} \mid \text{nil} \mid \{\text{err}/x\}P$
- |                                       |
|---------------------------------------|
| $\Gamma_0 \vdash c : (0, -)$          |
| $\Gamma_1 \vdash c : (2, v)$          |
| $\Gamma_2 \vdash c : (1, v)$          |
| $\Gamma_3 \vdash c : (2, \text{err})$ |
| $\Gamma_4 \vdash c : (1, \text{err})$ |
| $\Gamma_0 \vdash c : (0, -)$          |

# Example: Collisions



$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.c!\langle w \rangle.\text{nil} \mid [c?(x).P]\text{nil} \quad \rightarrow_i$

$\Gamma_1 \triangleright \sigma^2.\text{nil} \mid \sigma.c!\langle w \rangle.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$

●  $\Gamma_2 \triangleright \sigma.\text{nil} \mid c!\langle w \rangle.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_i$

$\Gamma_3 \triangleright \sigma.\text{nil} \mid \sigma^2.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$

$\Gamma_4 \triangleright \text{nil} \mid \sigma.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$

$\Gamma_0 \triangleright \text{nil} \mid \text{nil} \mid \{\text{err}/x\}P$

$\Gamma_0 \vdash c : (0, -)$

$\Gamma_1 \vdash c : (2, v)$

$\Gamma_2 \vdash c : (1, v)$

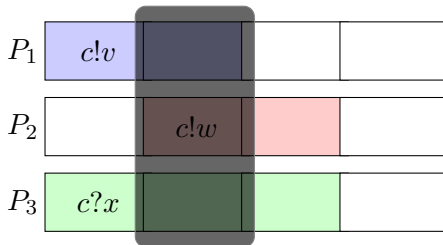
$\Gamma_3 \vdash c : (2, \text{err})$

$\Gamma_4 \vdash c : (1, \text{err})$

$\Gamma_0 \vdash c : (0, -)$



# Example: Collisions



$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.c!\langle w \rangle.\text{nil} \mid [c?(x).P]\text{nil} \quad \rightarrow_i$

$\Gamma_1 \triangleright \sigma^2.\text{nil} \mid \sigma.c!\langle w \rangle.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$

$\Gamma_2 \triangleright \sigma.\text{nil} \mid c!\langle w \rangle.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_i$

●  $\Gamma_3 \triangleright \sigma.\text{nil} \mid \sigma^2.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$

$\Gamma_4 \triangleright \text{nil} \mid \sigma.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$

$\Gamma_0 \triangleright \text{nil} \mid \text{nil} \mid \{\text{err}/x\}P$

$\Gamma_0 \vdash c : (0, -)$

$\Gamma_1 \vdash c : (2, v)$

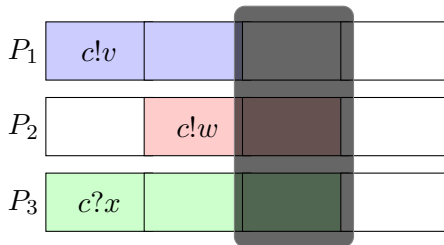
$\Gamma_2 \vdash c : (1, v)$

$\Gamma_3 \vdash c : (2, \text{err})$

$\Gamma_4 \vdash c : (1, \text{err})$

$\Gamma_0 \vdash c : (0, -)$

# Example: Collisions



$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.c!\langle w \rangle.\text{nil} \mid [c?(x).P]\text{nil} \quad \rightarrow_i$

$\Gamma_1 \triangleright \sigma^2.\text{nil} \mid \sigma.c!\langle w \rangle.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$

$\Gamma_2 \triangleright \sigma.\text{nil} \mid c!\langle w \rangle.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_i$

$\Gamma_3 \triangleright \sigma.\text{nil} \mid \sigma^2.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$

●  $\Gamma_4 \triangleright \text{nil} \mid \sigma.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$

$\Gamma_0 \triangleright \text{nil} \mid \text{nil} \mid \{\text{err}/x\}P$

$\Gamma_0 \vdash c : (0, -)$

$\Gamma_1 \vdash c : (2, v)$

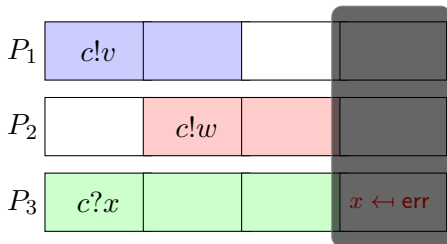
$\Gamma_2 \vdash c : (1, v)$

$\Gamma_3 \vdash c : (2, \text{err})$

$\Gamma_4 \vdash c : (1, \text{err})$

$\Gamma_0 \vdash c : (0, -)$

# Example: Collisions



$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.c!\langle w \rangle.\text{nil} \mid [c?(x).P]\text{nil} \quad \rightarrow_i$

$\Gamma_1 \triangleright \sigma^2.\text{nil} \mid \sigma.c!\langle w \rangle.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$

$\Gamma_2 \triangleright \sigma.\text{nil} \mid c!\langle w \rangle.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_i$

$\Gamma_3 \triangleright \sigma.\text{nil} \mid \sigma^2.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$

$\Gamma_4 \triangleright \text{nil} \mid \sigma.\text{nil} \mid [c \leftarrow x].P \quad \rightarrow_\sigma$

●  $\Gamma_0 \triangleright \text{nil} \mid \text{nil} \mid \{\text{err}/x\}P$

$\Gamma_0 \vdash c : (0, -)$

$\Gamma_1 \vdash c : (2, v)$

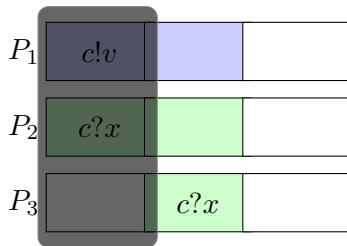
$\Gamma_2 \vdash c : (1, v)$

$\Gamma_3 \vdash c : (2, \text{err})$

$\Gamma_4 \vdash c : (1, \text{err})$

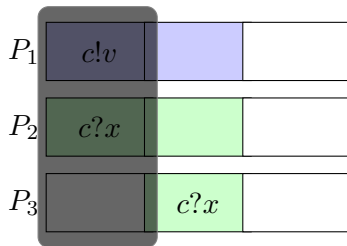
$\Gamma_0 \vdash c : (0, -)$

# Example: Failure of Synchronisation



- $\bullet$   $\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [c?(x).P]\text{nil} \mid \sigma.[c?(x).Q]\text{nil}$   $\rightarrow_i$
  - $\Gamma_1 \triangleright \sigma^2.\text{nil} \mid [c \leftarrow x].P \mid \sigma.[c?(x).Q]\text{nil}$   $\rightarrow_\sigma$
  - $\Gamma_2 \triangleright \sigma.\text{nil} \mid [c \leftarrow x].P \mid [c?(x).Q]\text{nil}$   $\rightarrow_i$
  - $\Gamma_2 \triangleright \sigma.\text{nil} \mid [c \leftarrow x].P \mid [c \leftarrow x].\{\text{err}/x\}Q$   $\rightarrow_\sigma$
  - $\Gamma_0 \triangleright \text{nil} \mid \{v/x\}P \mid \{\text{err}/x\}Q$
- $\left\| \begin{array}{l} \Gamma_0 \vdash c : (0, -) \\ \Gamma_1 \vdash c : (2, v) \\ \Gamma_2 \vdash c : (1, v) \\ \Gamma_2 \vdash c : (1, v) \\ \Gamma_0 \vdash c : (0, -) \end{array} \right.$

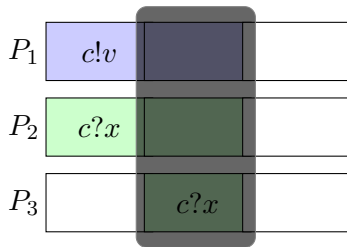
# Example: Failure of Synchronisation



- $\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [c?(x).P]\text{nil} \mid \sigma.[c?(x).Q]\text{nil} \quad \rightarrow_i$
- $\Gamma_1 \triangleright \sigma^2.\text{nil} \mid [c \leftarrow x].P \mid \sigma.[c?(x).Q]\text{nil} \quad \rightarrow_\sigma$
- $\Gamma_2 \triangleright \sigma.\text{nil} \mid [c \leftarrow x].P \mid [c?(x).Q]\text{nil} \quad \rightarrow_i$
- $\Gamma_2 \triangleright \sigma.\text{nil} \mid [c \leftarrow x].P \mid [c \leftarrow x].\{\text{err}/x\}Q \quad \rightarrow_\sigma$
- $\Gamma_0 \triangleright \text{nil} \mid \{v/x\}P \mid \{\text{err}/x\}Q$

$\Gamma_0 \vdash c : (0, -)$   
 $\Gamma_1 \vdash c : (2, v)$   
 $\Gamma_2 \vdash c : (1, v)$   
 $\Gamma_2 \vdash c : (1, v)$   
 $\Gamma_0 \vdash c : (0, -)$

# Example: Failure of Synchronisation



$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [c?(x).P]\text{nil} \mid \sigma.[c?(x).Q]\text{nil} \quad \rightarrow_i$

$\Gamma_1 \triangleright \sigma^2.\text{nil} \mid [c \leftarrow x].P \mid \sigma.[c?(x).Q]\text{nil} \quad \rightarrow_\sigma$

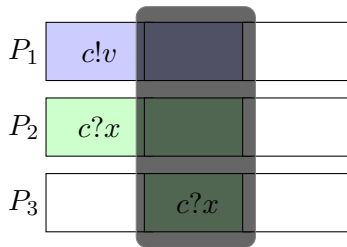
●  $\Gamma_2 \triangleright \sigma.\text{nil} \mid [c \leftarrow x].P \mid [c?(x).Q]\text{nil} \quad \rightarrow_i$

$\Gamma_2 \triangleright \sigma.\text{nil} \mid [c \leftarrow x].P \mid [c \leftarrow x].\{\text{err}/x\}Q \quad \rightarrow_\sigma$

$\Gamma_0 \triangleright \text{nil} \mid \{v/x\}P \mid \{\text{err}/x\}Q$

$\left\| \begin{array}{l} \Gamma_0 \vdash c : (0, -) \\ \Gamma_1 \vdash c : (2, v) \\ \Gamma_2 \vdash c : (1, v) \\ \Gamma_2 \vdash c : (1, v) \\ \Gamma_0 \vdash c : (0, -) \end{array} \right.$

# Example: Failure of Synchronisation



$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [c?(x).P]\text{nil} \mid \sigma.[c?(x).Q]\text{nil} \quad \rightarrow_i$

$\Gamma_1 \triangleright \sigma^2.\text{nil} \mid [c \leftarrow x].P \mid \sigma.[c?(x).Q]\text{nil} \quad \rightarrow_\sigma$

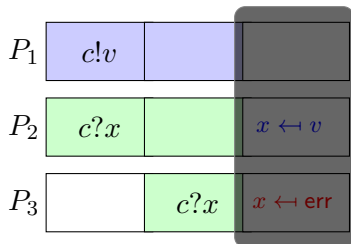
$\Gamma_2 \triangleright \sigma.\text{nil} \mid [c \leftarrow x].P \mid [c?(x).Q]\text{nil} \quad \rightarrow_i$

●  $\Gamma_2 \triangleright \sigma.\text{nil} \mid [c \leftarrow x].P \mid [c \leftarrow x].\{\text{err}/x\}Q \quad \rightarrow_\sigma$

$\Gamma_0 \triangleright \text{nil} \mid \{v/x\}P \mid \{\text{err}/x\}Q$

$\Gamma_0 \vdash c : (0, -)$   
 $\Gamma_1 \vdash c : (2, v)$   
 $\Gamma_2 \vdash c : (1, v)$   
 $\Gamma_2 \vdash c : (1, v)$   
 $\Gamma_0 \vdash c : (0, -)$

# Example: Failure of Synchronisation



$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [c?(x).P]\text{nil} \mid \sigma.[c?(x).Q]\text{nil} \quad \rightarrow_i$

$\Gamma_1 \triangleright \sigma^2.\text{nil} \mid [c \leftarrow x].P \mid \sigma.[c?(x).Q]\text{nil} \quad \rightarrow_\sigma$

$\Gamma_2 \triangleright \sigma.\text{nil} \mid [c \leftarrow x].P \mid [c?(x).Q]\text{nil} \quad \rightarrow_i$

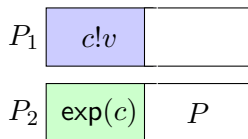
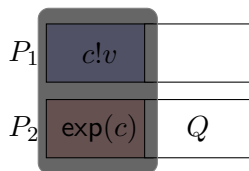
$\Gamma_2 \triangleright \sigma.\text{nil} \mid [c \leftarrow x].P \mid [c \leftarrow x].\{\text{err}/x\}Q \quad \rightarrow_\sigma$

●  $\Gamma_0 \triangleright \text{nil} \mid \{v/x\}P \mid \{\text{err}/x\}Q$

$\Gamma_0 \vdash c : (0, -)$   
 $\Gamma_1 \vdash c : (2, v)$   
 $\Gamma_2 \vdash c : (1, v)$   
 $\Gamma_2 \vdash c : (1, v)$   
 $\Gamma_0 \vdash c : (0, -)$



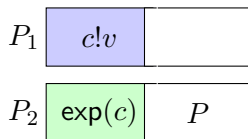
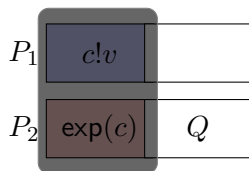
$$\Gamma_0 \vdash c : (0, -) \quad \Gamma_1 \vdash c : (1, v)$$



- $\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \xrightarrow{i}$
- $\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.Q \xrightarrow{i}$
- $\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.Q \xrightarrow{\sigma}$
- $\Gamma_0 \triangleright \text{nil} \mid Q$
- $\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \xrightarrow{i}$
- $\Gamma_1 \triangleright \sigma.\text{nil} \mid [\text{exp}(c)]P, Q \xrightarrow{i}$
- $\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.P \xrightarrow{\sigma}$
- $\Gamma_0 \triangleright \text{nil} \mid P$

# Exposure Check

$$\Gamma_0 \vdash c : (0, -) \quad \Gamma_1 \vdash c : (1, v)$$



$$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \quad \rightarrow_i$$

●  $\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.Q \quad \rightarrow_i$

$$\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.Q \quad \rightarrow_\sigma$$

$$\Gamma_0 \triangleright \text{nil} \mid Q$$

$$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \quad \rightarrow_i$$

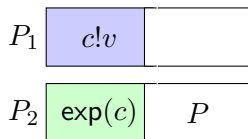
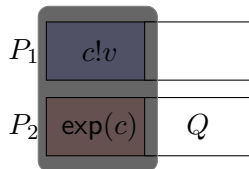
$$\Gamma_1 \triangleright \sigma.\text{nil} \mid [\text{exp}(c)]P, Q \quad \rightarrow_i$$

$$\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.P \quad \rightarrow_\sigma$$

$$\Gamma_0 \triangleright \text{nil} \mid P$$

# Exposure Check

$$\Gamma_0 \vdash c : (0, -) \quad \Gamma_1 \vdash c : (1, v)$$



$$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \quad \rightarrow_i$$

$$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.Q \quad \rightarrow_i$$

$$\bullet \quad \Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.Q \quad \rightarrow_\sigma$$

$$\Gamma_0 \triangleright \text{nil} \mid Q$$

$$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \quad \rightarrow_i$$

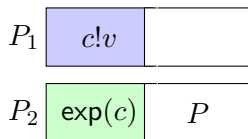
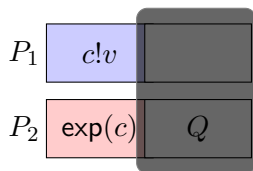
$$\Gamma_1 \triangleright \sigma.\text{nil} \mid [\text{exp}(c)]P, Q \quad \rightarrow_i$$

$$\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.P \quad \rightarrow_\sigma$$

$$\Gamma_0 \triangleright \text{nil} \mid P$$

# Exposure Check

$$\Gamma_0 \vdash c : (0, -) \quad \Gamma_1 \vdash c : (1, v)$$



$$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \quad \rightarrow_i$$

$$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.Q \quad \rightarrow_i$$

$$\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.Q \quad \rightarrow_\sigma$$

●  $\Gamma_0 \triangleright \text{nil} \mid Q$

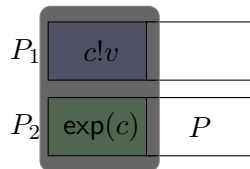
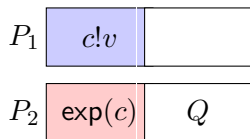
$$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \quad \rightarrow_i$$

$$\Gamma_1 \triangleright \sigma.\text{nil} \mid [\text{exp}(c)]P, Q \quad \rightarrow_i$$

$$\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.P \quad \rightarrow_\sigma$$

$$\Gamma_0 \triangleright \text{nil} \mid P$$

$$\Gamma_0 \vdash c : (0, -) \quad \Gamma_1 \vdash c : (1, v)$$

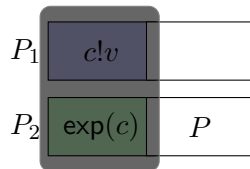
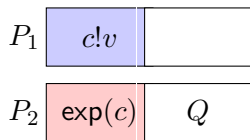


$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \xrightarrow{i}$   
 $\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.Q \xrightarrow{i}$   
 $\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.Q \xrightarrow{\sigma}$   
 $\Gamma_0 \triangleright \text{nil} \mid Q$

●  $\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \xrightarrow{i}$   
 $\Gamma_1 \triangleright \sigma.\text{nil} \mid [\text{exp}(c)]P, Q \xrightarrow{i}$   
 $\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.P \xrightarrow{\sigma}$   
 $\Gamma_0 \triangleright \text{nil} \mid P$

# Exposure Check

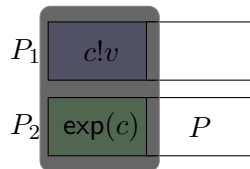
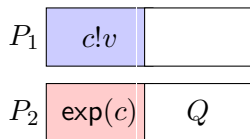
$$\Gamma_0 \vdash c : (0, -) \quad \Gamma_1 \vdash c : (1, v)$$



$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \xrightarrow{i}$   
 $\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.Q \xrightarrow{i}$   
 $\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.Q \xrightarrow{\sigma}$   
 $\Gamma_0 \triangleright \text{nil} \mid Q$

$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \xrightarrow{i}$   
 $\Gamma_1 \triangleright \sigma.\text{nil} \mid [\text{exp}(c)]P, Q \xrightarrow{i}$   
 $\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.P \xrightarrow{\sigma}$   
 $\Gamma_0 \triangleright \text{nil} \mid P$

$$\Gamma_0 \vdash c : (0, -) \quad \Gamma_1 \vdash c : (1, v)$$

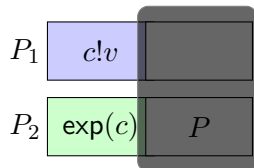
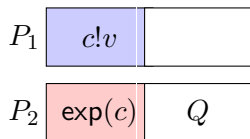


$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \xrightarrow{i}$   
 $\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.Q \xrightarrow{i}$   
 $\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.Q \xrightarrow{\sigma}$   
 $\Gamma_0 \triangleright \text{nil} \mid Q$

$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \xrightarrow{i}$   
 $\Gamma_1 \triangleright \sigma.\text{nil} \mid [\text{exp}(c)]P, Q \xrightarrow{i}$   
 $\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.P \xrightarrow{\sigma}$   
 $\Gamma_0 \triangleright \text{nil} \mid P$

# Exposure Check

$$\Gamma_0 \vdash c : (0, -) \quad \Gamma_1 \vdash c : (1, v)$$



$$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \quad \rightarrow_i$$

$$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid \sigma.Q \quad \rightarrow_i$$

$$\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.Q \quad \rightarrow_\sigma$$

$$\Gamma_0 \triangleright \text{nil} \mid Q$$

$$\Gamma_0 \triangleright c!\langle v \rangle.\text{nil} \mid [\text{exp}(c)]P, Q \quad \rightarrow_i$$

$$\Gamma_1 \triangleright \sigma.\text{nil} \mid [\text{exp}(c)]P, Q \quad \rightarrow_i$$

$$\Gamma_1 \triangleright \sigma.\text{nil} \mid \sigma.P \quad \rightarrow_\sigma$$

$$\Gamma_0 \triangleright \text{nil} \mid P$$





## Reduction Barbed Congruence

$\Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2$  if they have the same **observables** under all possible evolutions in all possible contexts

- Standard notion of observable: the ability to output on a channel  $c$
- Observables in CCCP: a channel  $c$  being exposed to a transmission

## Observables

$\Gamma \triangleright W \downarrow_c$  if  $\Gamma \vdash c : (n, v), n > 0$

$\Gamma \triangleright W \Downarrow_c$  if  $\Gamma \triangleright W \rightarrow^* \Gamma' \triangleright W' \downarrow_c$

## Reduction Barbed Congruence

$\Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2$  if they have the same **observables** under all possible evolutions in all possible contexts

Reduction barbed congruence: largest symmetric relation which is

- Barb Preserving
- Reduction Closed
- Contextual

## Reduction Barbed Congruence

$\Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2$  if they have the same **observables** under all possible evolutions in all possible contexts

Reduction barbed congruence: largest symmetric relation which is

- **Barb Preserving**
- Reduction Closed
- Contextual

$$\Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2 \\ \Gamma_1 \triangleright W_1 \Downarrow_c \text{ implies } \Gamma_2 \triangleright W_2 \Downarrow_c$$

## Reduction Barbed Congruence

$\Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2$  if they have the same **observables** under all possible evolutions in all possible contexts

Reduction barbed congruence: largest symmetric relation which is

- Barb Preserving
- **Reduction Closed**
- Contextual

$$\begin{array}{l} \Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2 \\ \Gamma_1 \triangleright W_1 \rightarrow^* \Gamma'_1 \triangleright W'_1 \text{ implies} \\ \Gamma_2 \triangleright W_2 \rightarrow^* \Gamma'_2 \triangleright W'_2 \text{ such that} \\ \Gamma'_1 \triangleright W'_1 \simeq \Gamma'_2 \triangleright W'_2 \end{array}$$

## Reduction Barbed Congruence

$\Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2$  if they have the same **observables** under all possible evolutions in all possible contexts

Reduction barbed congruence: largest symmetric relation which is

- Barb Preserving
- Reduction Closed
- **Contextual**

$$\begin{aligned} & \Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2 \\ \Gamma_1 \triangleright W_1 \mid W & \simeq \Gamma_2 \triangleright W_2 \mid W \end{aligned}$$

Proving  $\Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2$  directly is difficult (**contextuality**).

Strategy: Give a coinductive characterisation based on the activities of systems observable by some context

Extensional Semantics:

- internal activities:  $\xrightarrow{\tau} = \rightarrow_i$
- Time:  $\xrightarrow{\sigma} = \rightarrow_\sigma$
- Input:  $\xrightarrow{c?v}$
- Idleness:  $\xrightarrow{\iota(c)}$
- Delivery:  $\xrightarrow{\gamma(c,v)}$

Proving  $\Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2$  directly is difficult (**contextuality**).

Strategy: Give a coinductive characterisation based on the activities of systems observable by some context

Extensional Semantics:

- internal activities:  $\xrightarrow{\tau} = \rightarrow_i$
- Time:  $\xrightarrow{\sigma} = \rightarrow_\sigma$
- Input:  $\xrightarrow{c?v}$
- **Idleness**:  $\xrightarrow{\iota(c)}$
- Delivery:  $\xrightarrow{\gamma(c,v)}$

Detecting channel  $c$  to be idle

$$\frac{\Gamma \vdash c : (0, v)}{\Gamma \triangleright W \xrightarrow{\iota(c)} \Gamma \triangleright W}$$

Proving  $\Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2$  directly is difficult (**contextuality**).

Strategy: Give a coinductive characterisation based on the activities of systems observable by some context

Extensional Semantics:

- internal activities:  $\xrightarrow{\tau} = \rightarrow_i$
- Time:  $\xrightarrow{\sigma} = \rightarrow_\sigma$
- Input:  $\xrightarrow{c?v}$
- Idleness:  $\xrightarrow{\iota(c)}$
- **Delivery:**  $\xrightarrow{\gamma(c,v)}$

Detecting the delivery of value  $v$   
along channel  $c$

$$\frac{\Gamma \triangleright W \rightarrow_\sigma \Gamma' \triangleright W' \quad \Gamma \vdash c : (1, v)}{\Gamma \triangleright W \xrightarrow{\gamma(c,v)} \Gamma' \triangleright W'}$$



Proving  $\Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2$  directly is difficult (**contextuality**).

Strategy: Give a coinductive characterisation based on the activities of systems observable by some context

Extensional Semantics:

- internal activities:  $\xrightarrow{\tau} = \rightarrow_i$
- Time:  $\xrightarrow{\sigma} = \rightarrow_\sigma$
- Input:  $\xrightarrow{c?v}$
- Idleness:  $\xrightarrow{\iota(c)}$
- Delivery:  $\xrightarrow{\gamma(c,v)}$

**Weak variant**  $\xrightarrow{\alpha}$ : Abstracting from internal activities

Bisimulation: largest symmetric relation  $\approx$  such that  $\Gamma_1 \triangleright W_1 \approx \Gamma_2 \triangleright W_2$  and  $\Gamma_1 \triangleright W_1 \xrightarrow{\alpha} \Gamma'_1 \triangleright W'_1$  implies  $\Gamma_2 \triangleright W_2 \xrightarrow{\alpha} \Gamma'_2 \triangleright W'_2$  with  $\Gamma'_1 \triangleright W'_1 \approx \Gamma'_2 \triangleright W'_2$

## Theorem (Soundness)

$$\Gamma_1 \triangleright W_1 \approx \Gamma_2 \triangleright W_2 \quad \text{implies} \quad \Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2$$

**Remark:**  $\iota^{(c)}$  and  $\gamma^{(c,v)}$  actions necessary for achieving soundness

Is the opposite implication to soundness true?

**Idea:** provide a distinguishing test  $W_\alpha$  for each extensional action  $\xrightarrow{\alpha}$

Is the opposite implication to soundness true?

**Idea:** provide a distinguishing test  $W_\alpha$  for each extensional action  $\stackrel{\alpha}{\Rightarrow}$   
Several time slots are required to detect whether the action  $\stackrel{\alpha}{\Rightarrow}$  has been performed

**But some systems do not allow time to pass!**

$$\Gamma \triangleright [c \leftarrow x].P \not\triangleright_\sigma \text{ if } \Gamma \vdash c : (0, -)$$

# Well-Timedness

Is the opposite implication to soundness true?

**Idea:** provide a distinguishing test  $W_\alpha$  for each extensional action  $\xrightarrow{\alpha}$   
Several time slots are required to detect whether the action  $\xrightarrow{\alpha}$  has been performed

But some systems do not allow time to pass!

$$\Gamma \triangleright [c \leftarrow x].P \not\triangleright_\sigma \text{ if } \Gamma \vdash c : (0, -)$$

## Well-Timedness

$$\Gamma \triangleright W \rightarrow^* \Gamma_1 \triangleright W_1 \quad \text{implies} \quad \Gamma_1 \triangleright W_1 \rightarrow^* \Gamma_2 \triangleright W_2 \rightarrow_\sigma$$

- Natural Requirement
- Can be checked syntactically

Is the opposite implication to soundness true?

## Theorem (Soundness)

$$\begin{aligned} \Gamma_1 \triangleright W_1 \approx \Gamma_2 \triangleright W_2 \\ \text{implies} \\ \Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2 \end{aligned}$$

Is the opposite implication to soundness true?

## Theorem (Soundness)

$$\begin{aligned} \Gamma_1 \triangleright W_1 \approx \Gamma_2 \triangleright W_2 \\ \text{implies} \\ \Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2 \end{aligned}$$

For Well-Timed systems:

## Theorem (Completeness)

$$\begin{aligned} \Gamma_1 \triangleright W_1 \simeq \Gamma_2 \triangleright W_2 \\ \text{implies} \\ \Gamma_1 \triangleright W_1 \approx \Gamma_2 \triangleright W_2 \end{aligned}$$

- ① Collision-prone Timed Process Calculus
- ② Barbed Congruence
- ③ Identification of the activities that can be observed
- ④ Full abstraction (for systems satisfying a natural requirement)  
result achieved for the first time



Thank you

