

Decision Procedures for Concurrent Skiplists

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EPFL, Lausanne, 16 September 2010

Why do we want a decision procedure

- ▶ Imperative programs

P

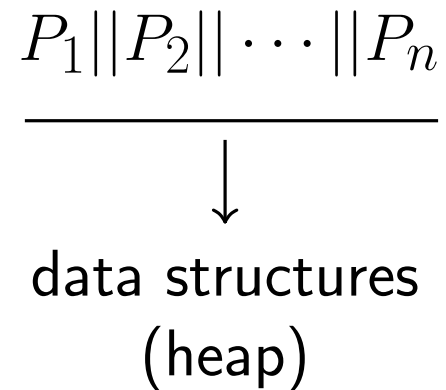
Why do we want a decision procedure

- ▶ Imperative programs
- ▶ Concurrent data-structures

$$P_1 || P_2 || \cdots || P_n$$

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Why do we want a decision procedure

- ▶ Imperative programs
- ▶ Concurrent data-structures
- ▶ Temporal properties (safety, liveness)

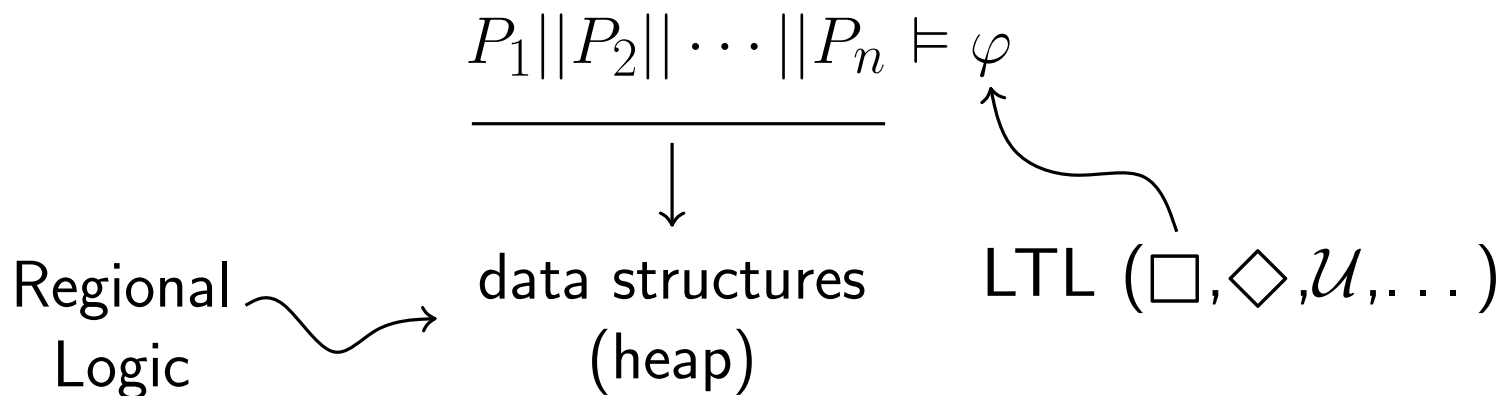
$$P_1 || P_2 || \cdots || P_n \models \varphi$$



data structures
(heap)

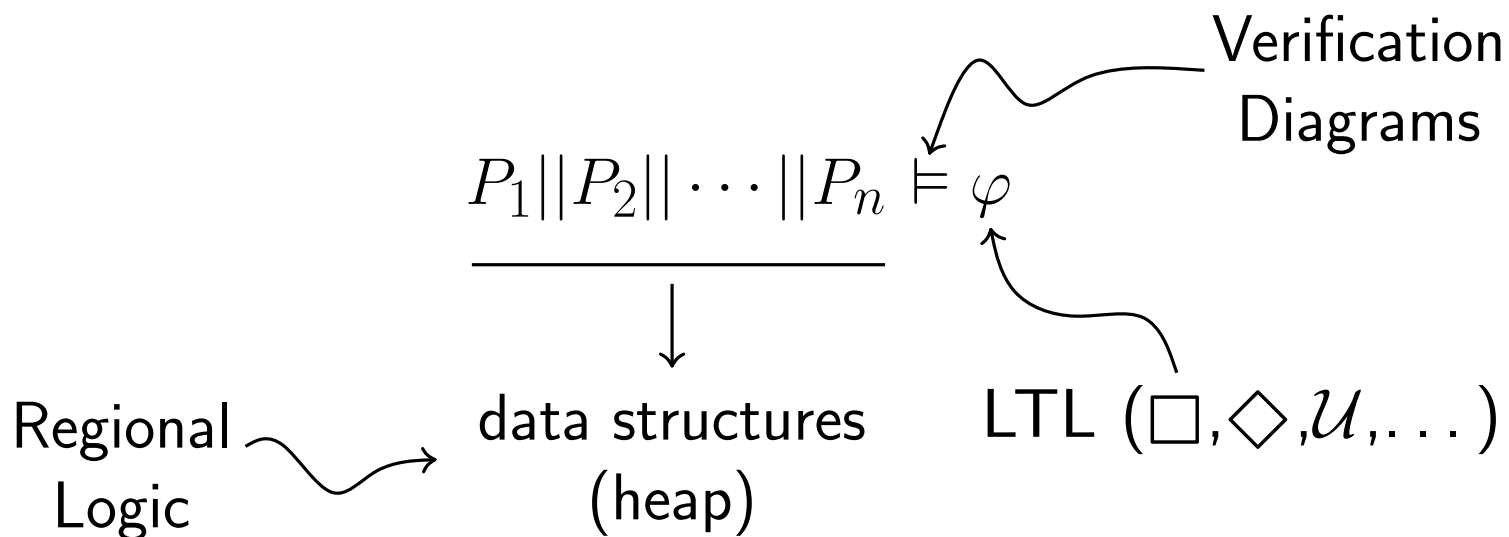
Why do we want a decision procedure

- ▶ Imperative programs
- ▶ Concurrent data-structures
- ▶ Temporal properties (safety, liveness)
- ▶ Formal verification



Why do we want a decision procedure

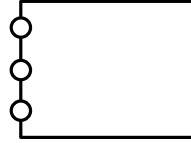
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Verification of Concurrent Data-structures

Main Idea

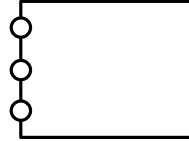
Concurrent DataStructure



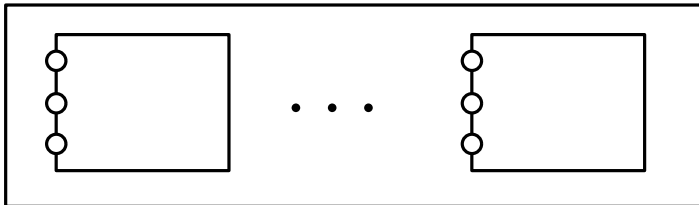
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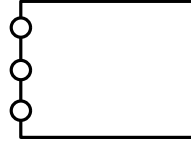
Most General Client



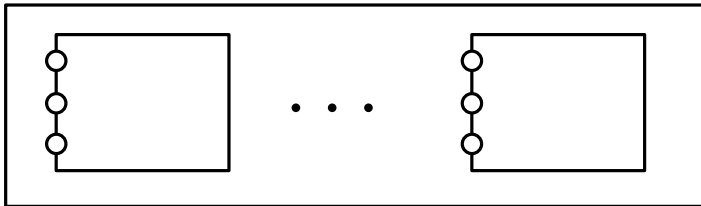
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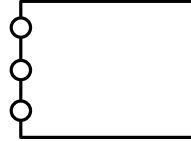


$$P[N] : P(1) || \dots || P(N)$$

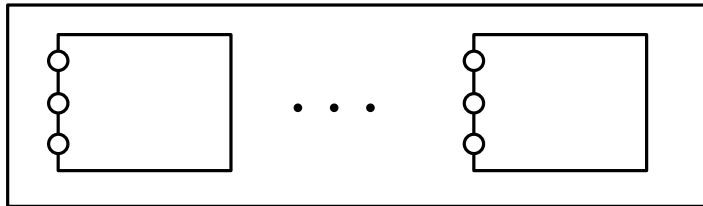
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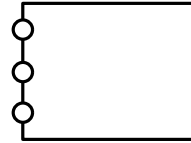
+

ghost variables

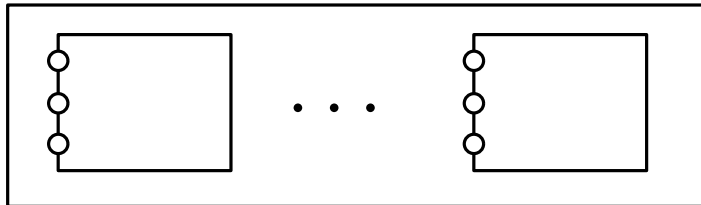
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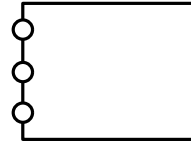
Property

$\varphi^{(k)}$

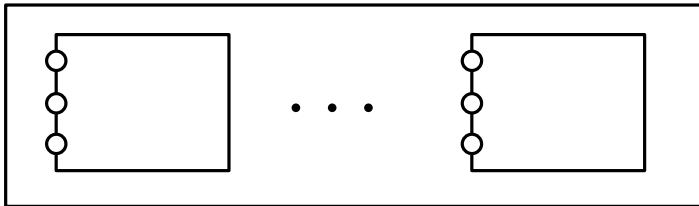
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Diagram

\mathcal{D}

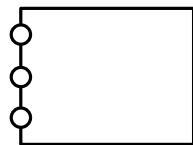
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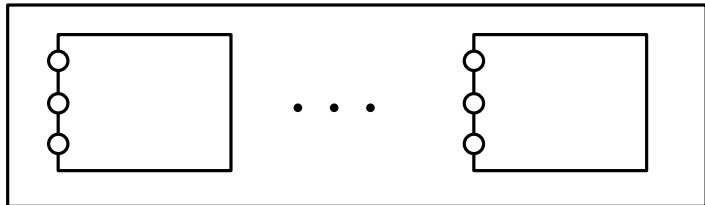
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Diagram

\models

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Verification Conditions:

- ▶ Initiation
- ▶ Consecution
- ▶ Acceptance
- ▶ Fairness

Property

\models

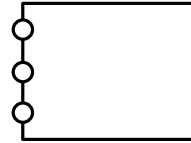
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Satisfaction
(Model Checking)

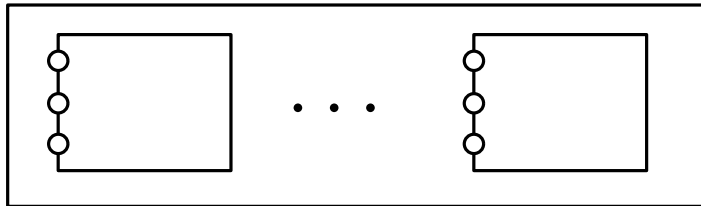
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Decision Procedures

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and if $(n_1, n_2) \notin P \cup R$:

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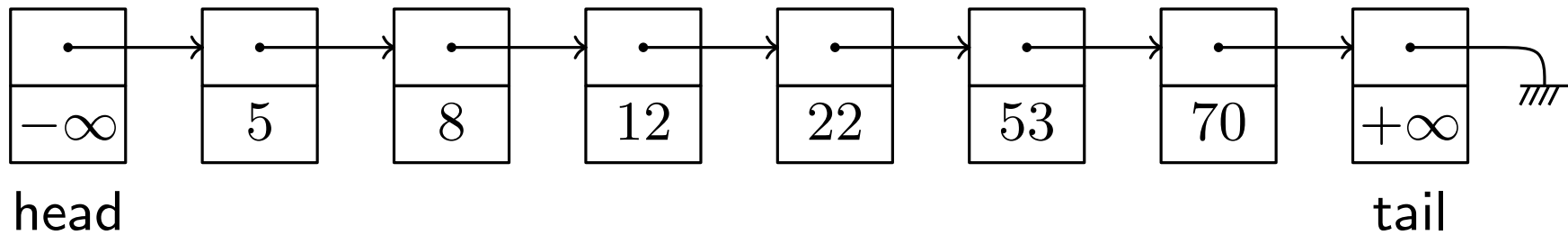
Concurrent Lock-Coupling Skiplists

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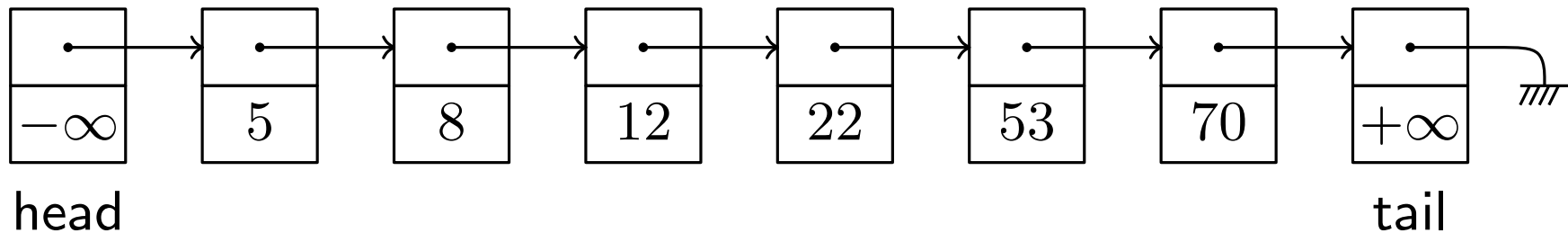
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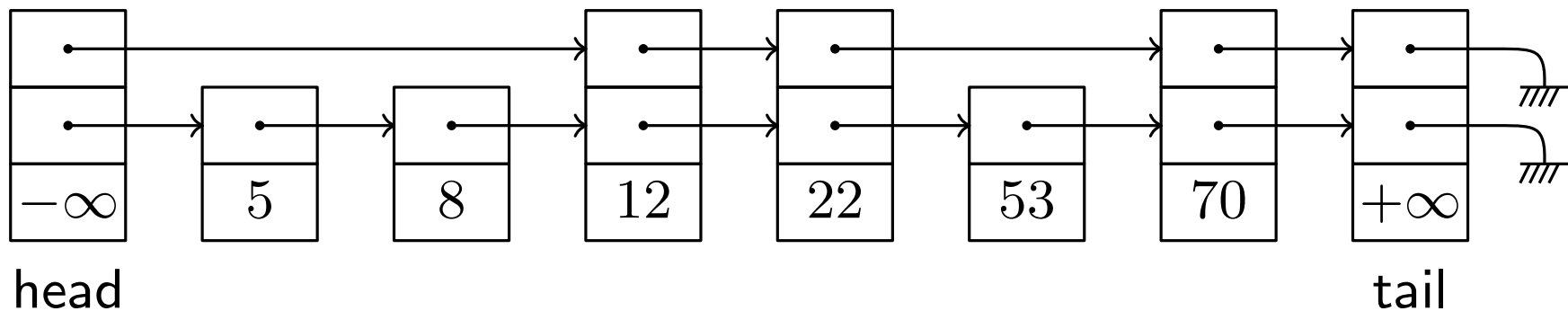
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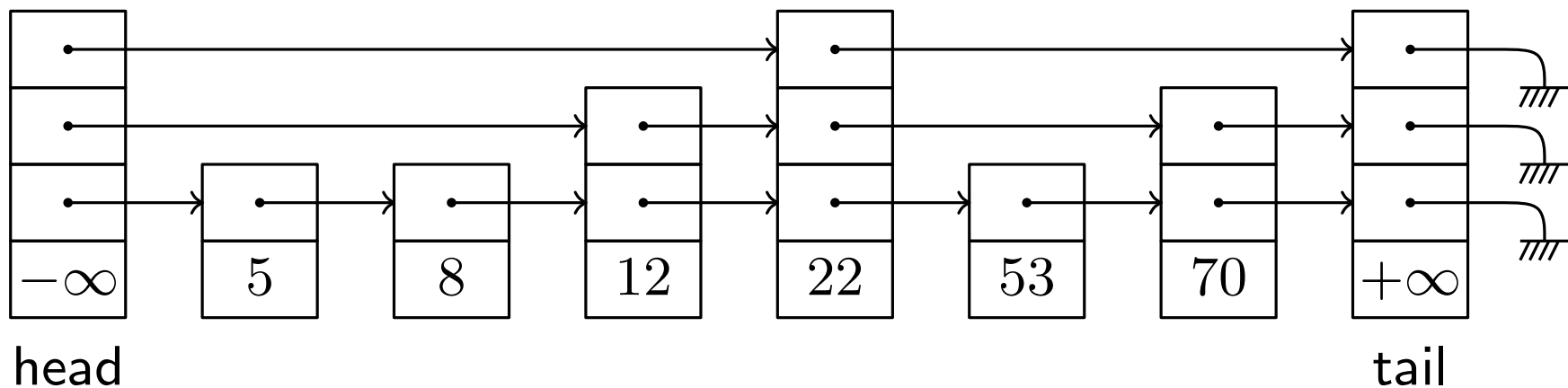
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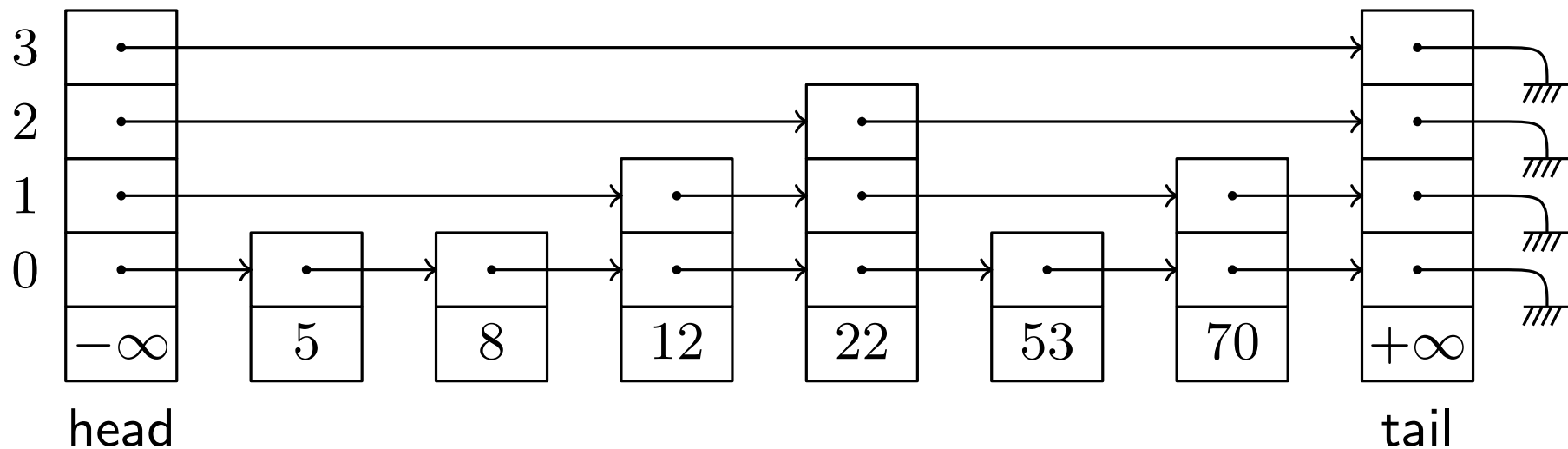
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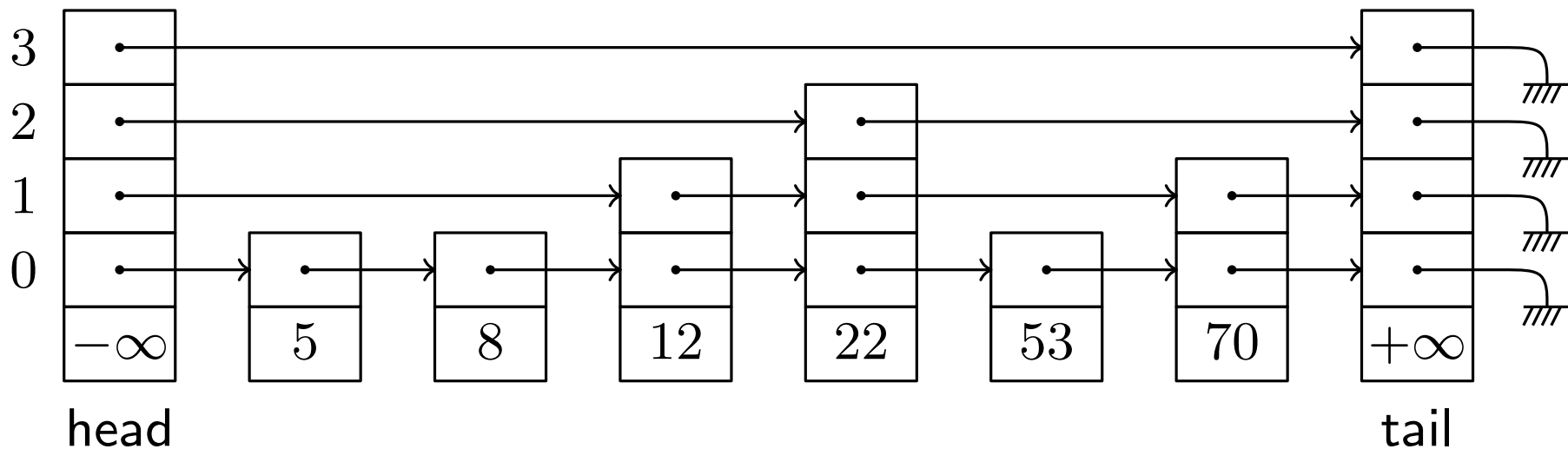
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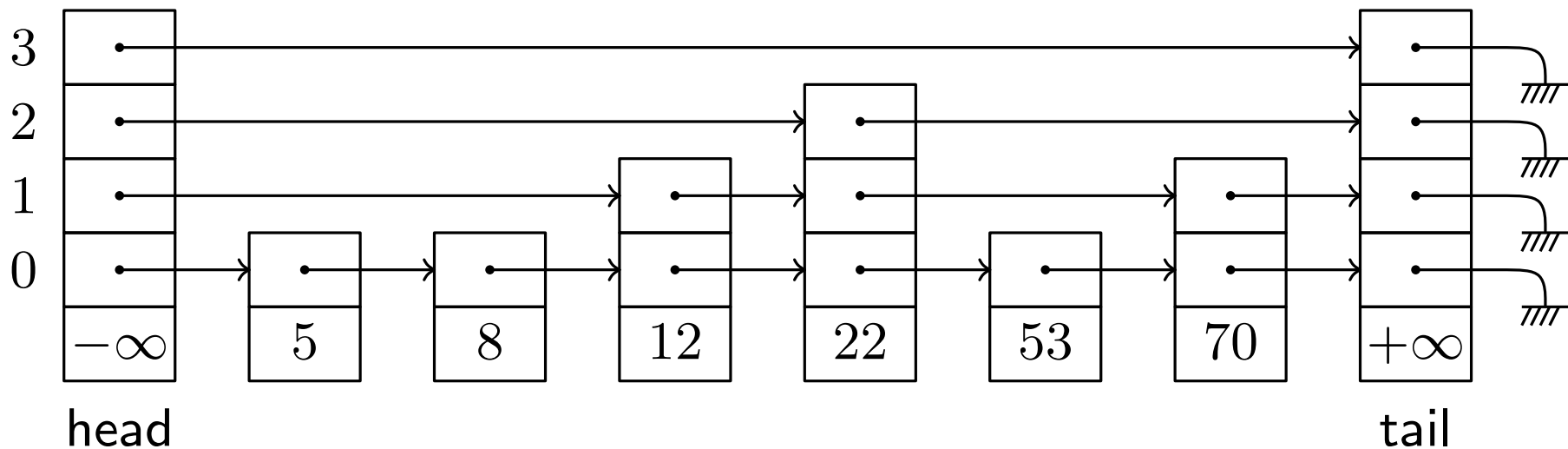
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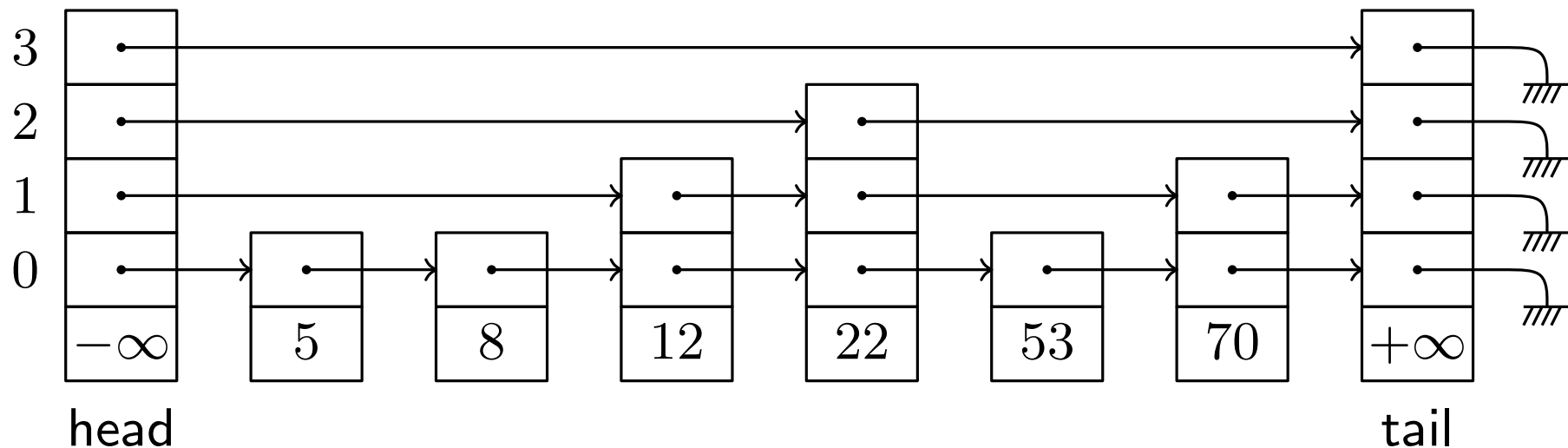
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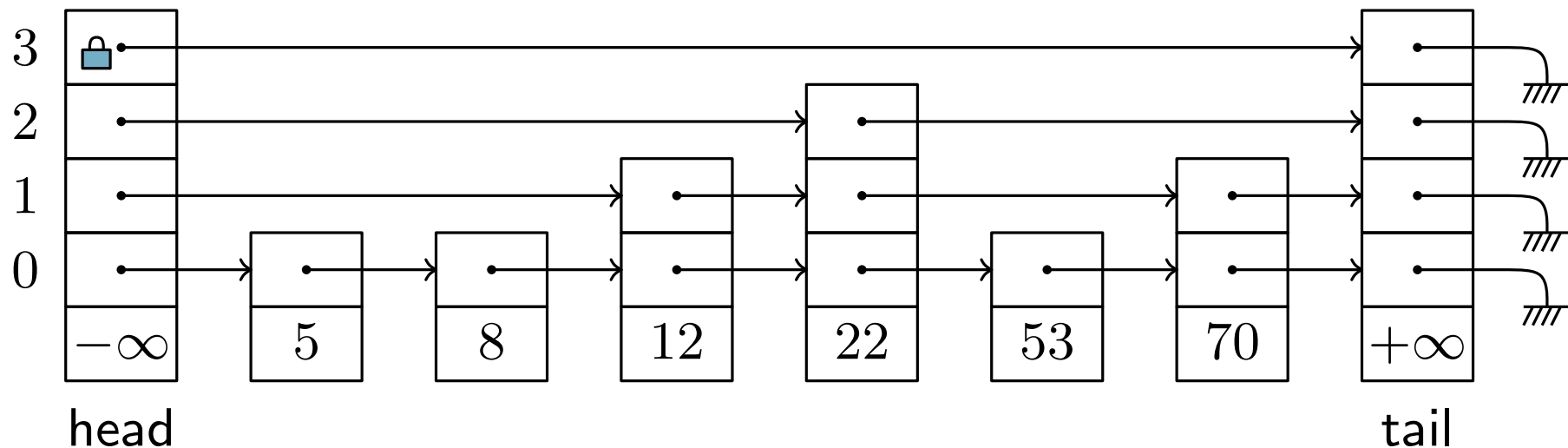
insert(60) with height 1



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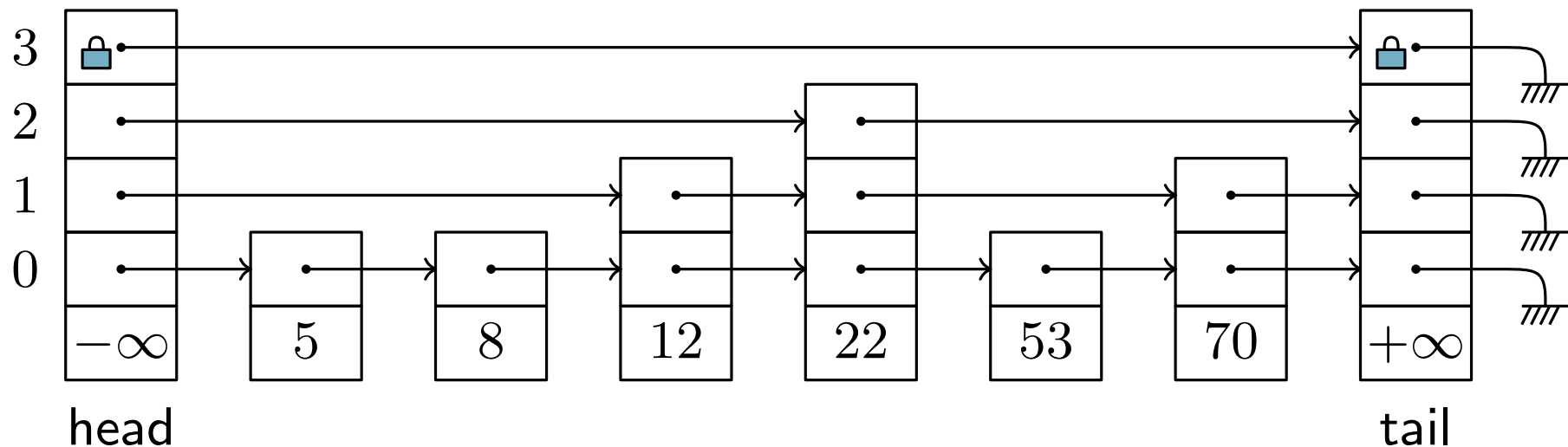
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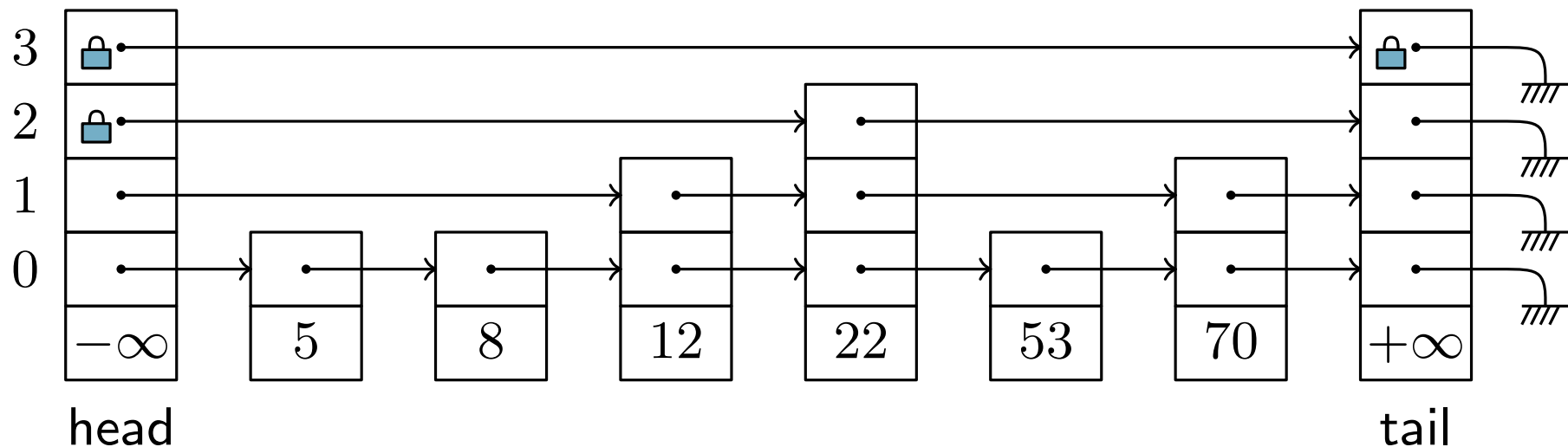
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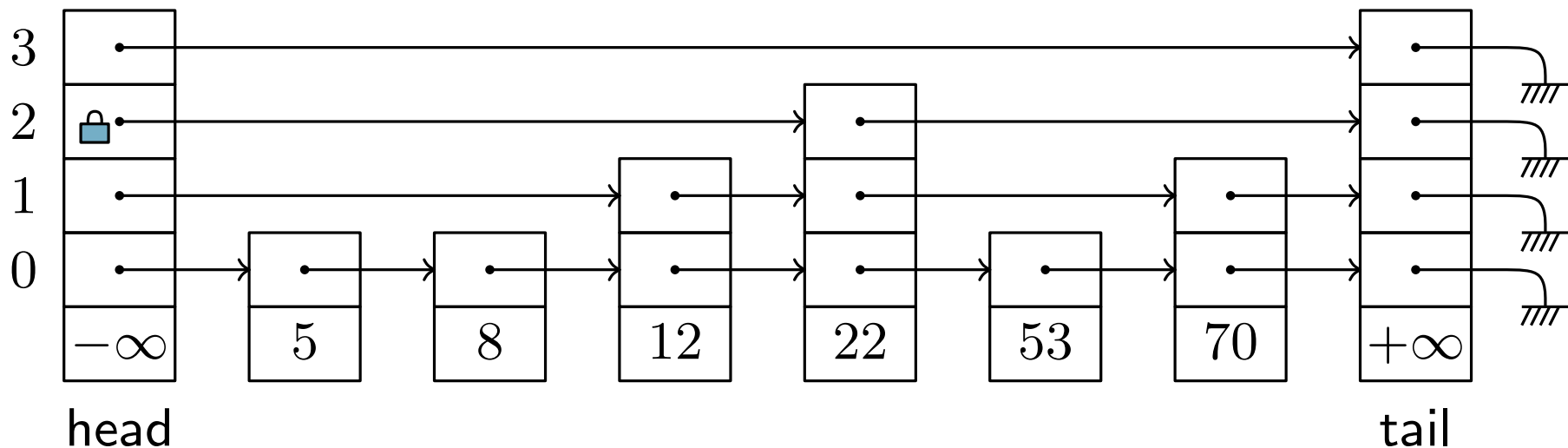
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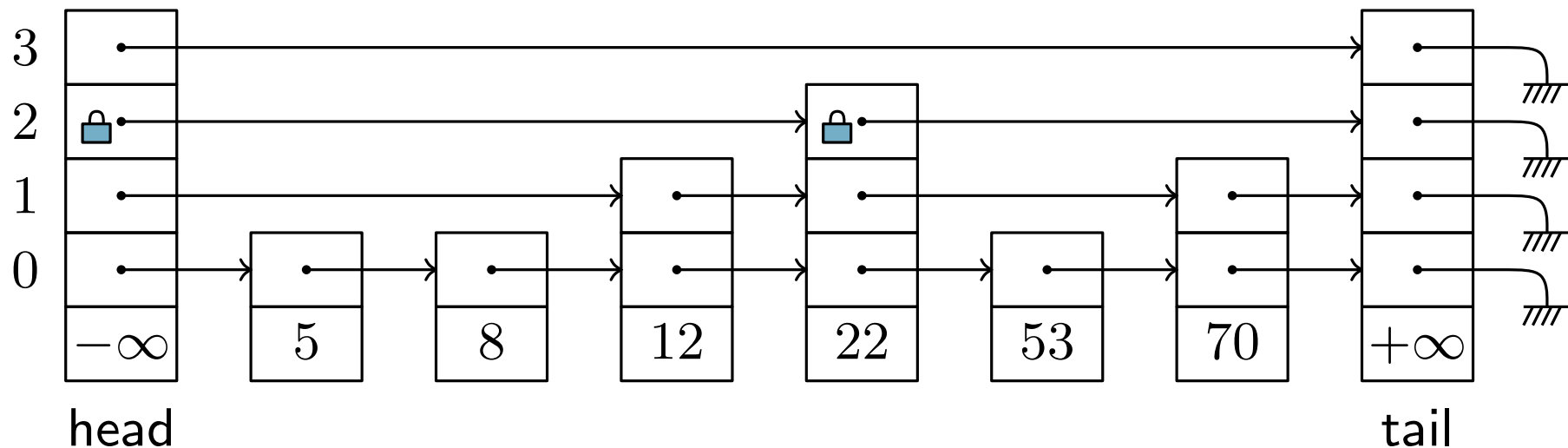
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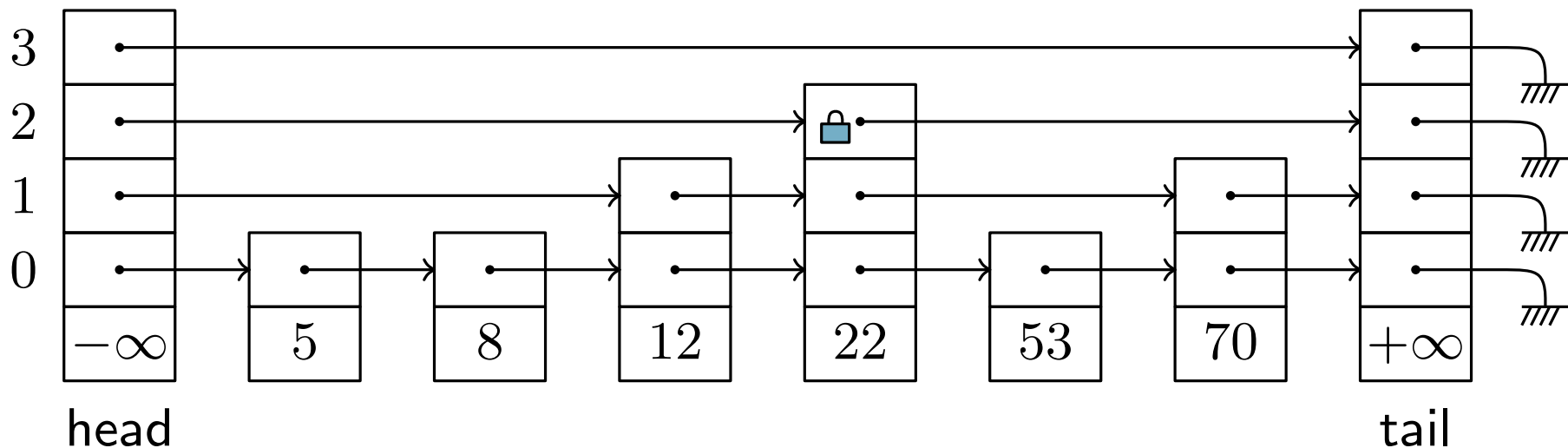
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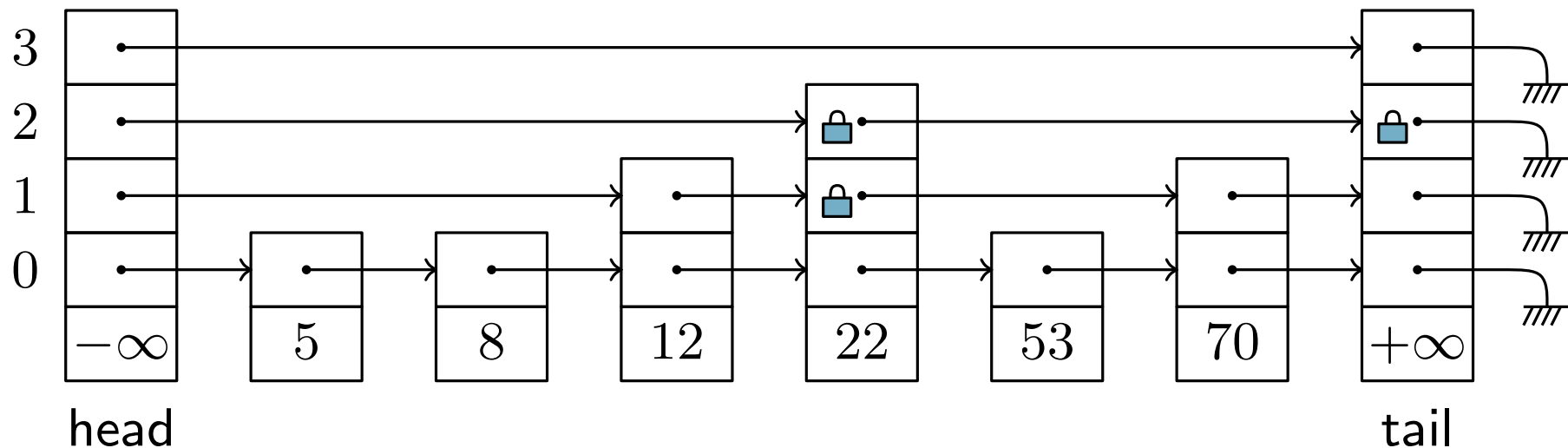
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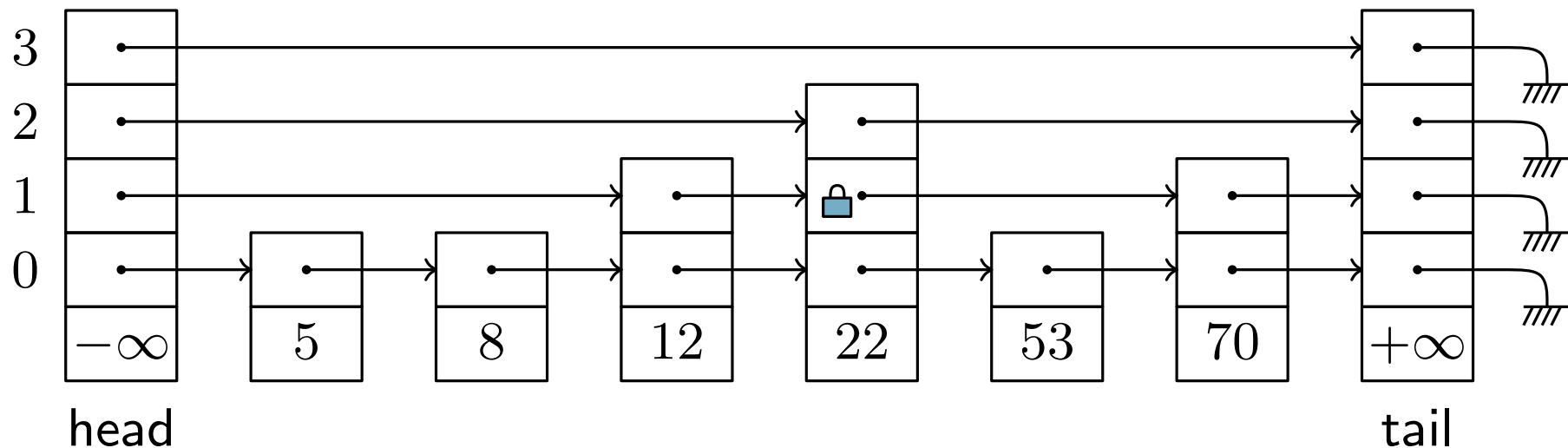
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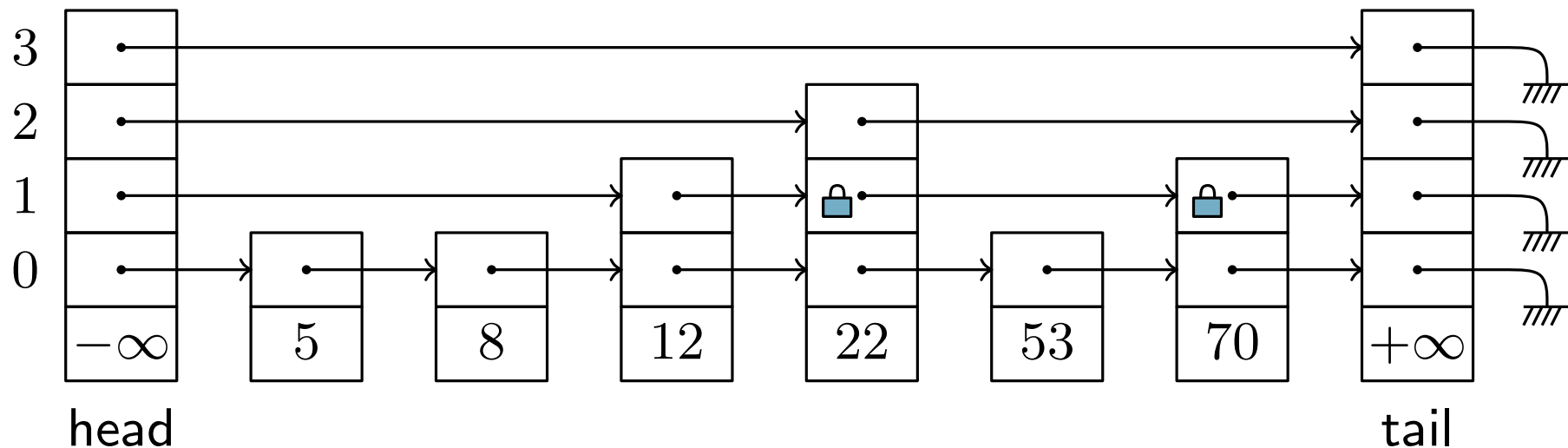
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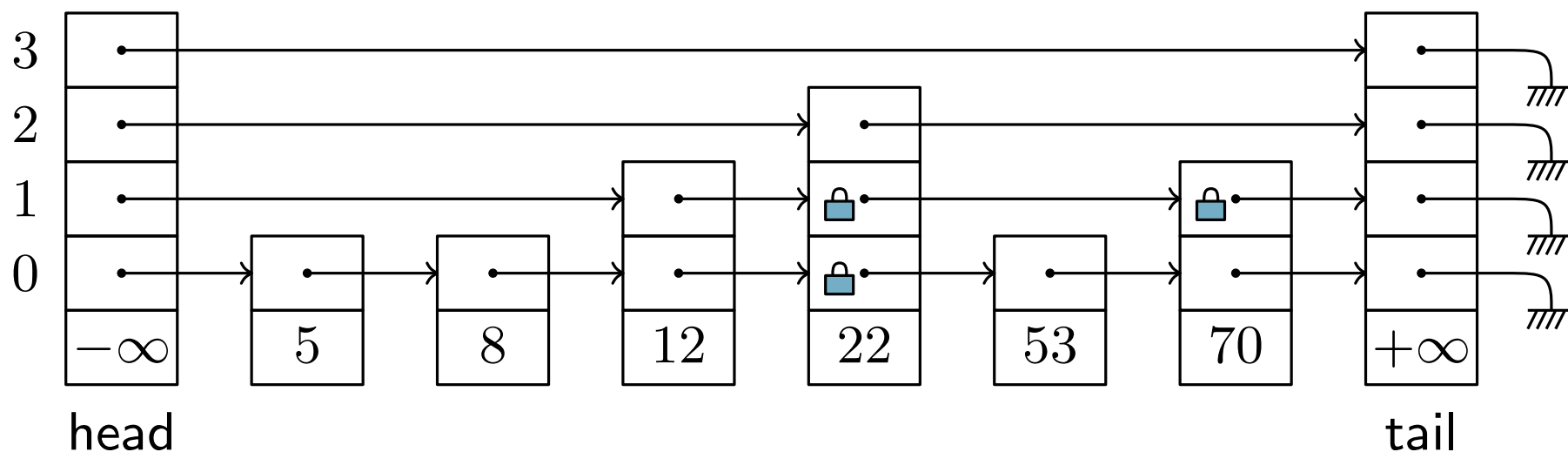
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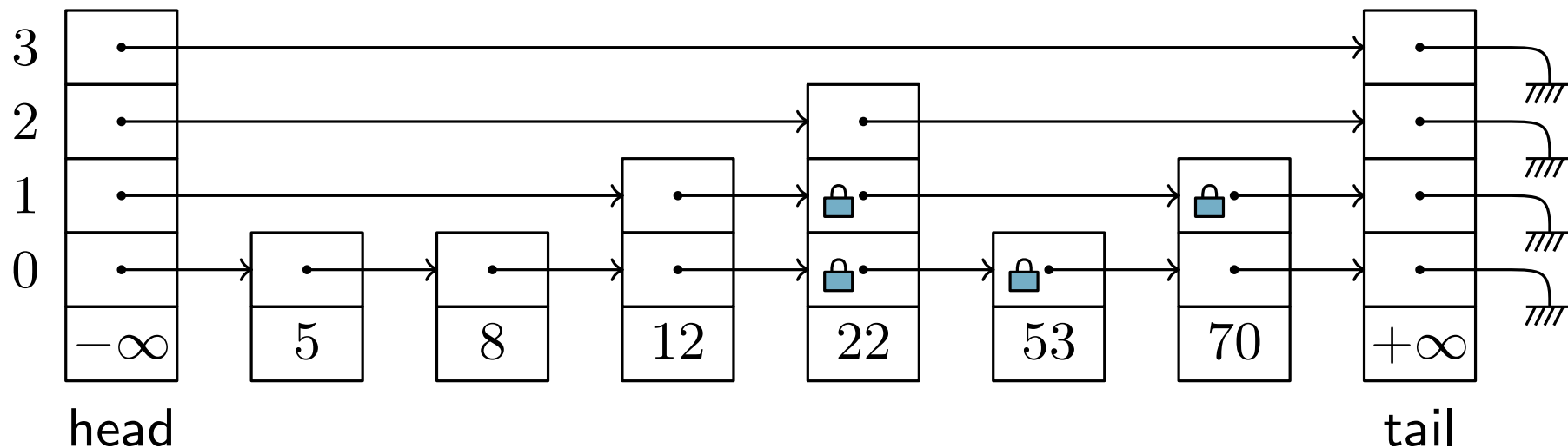
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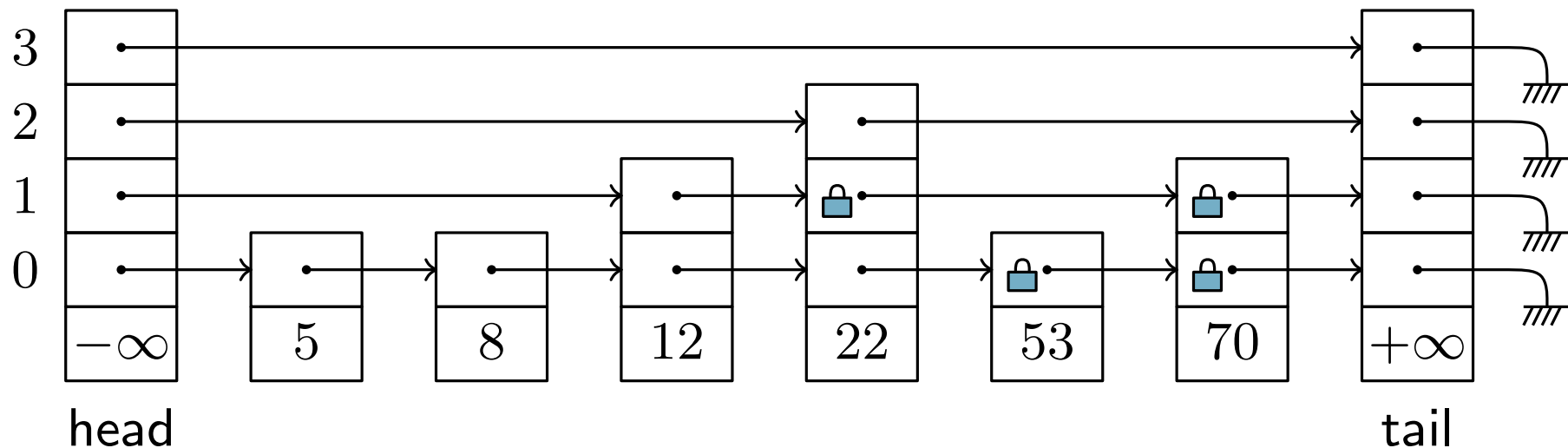
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Verification Conditions Examples

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- ▶ Preservation of skiplistness shape

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$$\begin{aligned} \text{SkipList}_3(sl : \text{SkipList}) \hat{=} & \\ & \text{OList}_0(h, sl.\text{head}, sl.r_0) \wedge \\ & \text{OList}_1(h, sl.\text{head}, sl.r_1) \wedge \\ & \text{OList}_2(h, sl.\text{head}, sl.r_2) \wedge \\ & \pi_1(sl.r_3) \subseteq \pi_1(sl.r_2) \subseteq \pi_1(sl.r_1) \wedge \\ & sl.\text{last}.\text{next}_0 = \text{null} \wedge sl.\text{last}.\text{next}_1 = \text{null} \wedge \\ & sl.\text{last}.\text{next}_2 = \text{null} \wedge \\ & \text{SubPath}(\text{getp}_1(h, sl.\text{head}, sl.\text{last}), \text{getp}_0(h, sl.\text{head}, sl.\text{last})) \wedge \\ & \text{SubPath}(\text{getp}_2(h, sl.\text{head}, sl.\text{last}), \text{getp}_1(h, sl.\text{head}, sl.\text{last})) \end{aligned}$$

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- ▶ Program transitions

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- ▶ Program transitions

$$\begin{aligned} & \text{SkipList}_3(sl) \wedge \text{at_insert}_{31} \wedge 0 \leq i \leq 2 \wedge \\ & x.\text{val} = v \wedge \text{update}[i].\text{val} < v \wedge \\ & \text{update}[i].\text{next}[i].\text{val} > v \wedge x.\text{next}[i] = \text{update}[i].\text{next}[i] \wedge \\ & m_r = \{(\text{update}[i], i), (x.\text{next}[i], i)\} \cup m_{i+1..2} \wedge \text{update}[i].\text{locks}[i] = t \wedge \\ & \text{update}[i].\text{next}[i].\text{locks}[i] = t \wedge (j < i \rightarrow (x, i) \in sl.r_j) \wedge \\ & \text{update}'[i].\text{next}[i] := x \wedge sl'.r_i := sl.r_i \cup \{(x, i)\} \rightarrow \\ & \quad \text{SkipList}_3(sl') \wedge \text{at}'_{\text{insert}}_{32} \wedge \text{update}'[i].\text{key} < k \wedge \\ & \quad \text{update}'[i].\text{next}[i].\text{next}[i].\text{key} > k \wedge \\ & \quad x'.\text{next}[i] = \text{update}'[i].\text{next}[i].\text{next}[i] \wedge \\ & \quad \text{update}'[i].\text{next}[i] = x' \wedge \\ & \quad m'_r = \{(\text{update}'[i], i), (x'.\text{next}[i], i)\} \cup m'_{i+1..2} \wedge \\ & \quad \text{update}'[i].\text{locks}[i] = t \wedge \text{update}'[i].\text{next}[i].\text{next}[i].\text{locks}[i] = t \end{aligned}$$

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- ▶ Description of order in lists and sub-paths

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$$TSL_K = T_{\text{addr}}$$

$$\Sigma_{\text{addr}} = \{\text{addr}\}, \emptyset, \emptyset$$

Theory of Concurrent Skiplists of Height K (TSL_K)

- ▶ Union of theories

$$TSL_K = T_{\text{addr}} \oplus T_{\text{elem}}$$

$$\Sigma_{\text{elem}} = \{\text{elem}\}, \emptyset, \emptyset$$

Theory of Concurrent Skiplists of Height K (TSL_K)

► Union of theories

$$TSL_K = T_{\text{addr}} \oplus T_{\text{elem}} \oplus T_{\text{cell}}$$

$$\Sigma_{\text{cell}} = \left\{ \begin{array}{l} \{ \text{cell, elem, ord, addr, thid} \} \\ \begin{array}{l} \textit{error} \quad : \quad \text{cell} \\ \textit{mkcell} \quad : \quad \text{elem} \times \text{ord} \times \text{addr}^K \times \text{thid}^K \rightarrow \text{cell} \\ \textit{..data} \quad : \quad \text{cell} \rightarrow \text{elem} \\ \textit{..key} \quad : \quad \text{cell} \rightarrow \text{ord} \\ \textit{..next}[-] \quad : \quad \text{cell} \times \text{level}_K \rightarrow \text{addr} \\ \textit{..lockid}[-] \quad : \quad \text{cell} \times \text{level}_K \rightarrow \text{thid} \\ \textit{..lock}[-] \quad : \quad \text{cell} \times \text{level}_K \rightarrow \text{thid} \rightarrow \text{cell} \\ \textit{..unlock}[-] \quad : \quad \text{cell} \times \text{level}_K \rightarrow \text{cell} \end{array} \end{array} \right\}$$

\emptyset

Theory of Concurrent Skiplists of Height K (TSL_K)

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$$TSL_K = T_{\text{addr}} \oplus T_{\text{elem}} \oplus T_{\text{cell}} \oplus T_{\text{mem}}$$

$$\Sigma_{\text{mem}} = \left. \begin{array}{l} \{\text{mem, addr, cell}\} \\ \left\{ \begin{array}{l} \text{null} : \text{addr} \\ -[-] : \text{mem} \times \text{addr} \rightarrow \text{cell} \\ \text{upd} : \text{mem} \times \text{addr} \times \text{cell} \rightarrow \text{mem} \end{array} \right\} \\ \emptyset \end{array} \right\}$$

Theory of Concurrent Skiplists of Height K (TSL_K)

► Union of theories

$$TSL_K = T_{\text{addr}} \oplus T_{\text{elem}} \oplus T_{\text{cell}} \oplus T_{\text{mem}} \oplus T_{\text{Reachability}}$$

$$\Sigma_{\text{Reachability}} = \left\{ \begin{array}{l} \{\text{mem, addr, path}\} \\ \left\{ \begin{array}{l} \epsilon \quad : \quad \text{path} \\ [-] \quad : \quad \text{addr} \rightarrow \text{path} \end{array} \right\} \\ \left\{ \begin{array}{l} \text{append} \quad : \quad \text{path} \times \text{path} \times \text{path} \\ \text{reach}_K \quad : \quad \text{mem} \times \text{addr} \times \text{addr} \times \text{level}_K \times \text{path} \end{array} \right\} \end{array} \right\}$$

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► Union of theories

$$TSL_K = T_{\text{addr}} \oplus T_{\text{elem}} \oplus T_{\text{cell}} \oplus T_{\text{mem}} \oplus T_{\text{Reachability}} \oplus T_{\text{set}}$$

$$\Sigma_{\text{set}} = \left. \begin{array}{l} \{ \text{addr, set} \} \\ \left\{ \begin{array}{l} \emptyset \quad : \quad \text{set} \\ \{-\} \quad : \quad \text{addr} \rightarrow \text{set} \\ \cup, \cap, \setminus \quad : \quad \text{set} \times \text{set} \rightarrow \text{set} \end{array} \right\} \\ \left\{ \begin{array}{l} \in \quad : \quad \text{addr} \times \text{set} \\ \subseteq \quad : \quad \text{set} \times \text{set} \end{array} \right\} \end{array} \right\}$$

Theory of Concurrent Skiplists of Height K (TSL_K)

► Union of theories

$$TSL_K = T_{\text{addr}} \oplus T_{\text{elem}} \oplus T_{\text{cell}} \oplus T_{\text{mem}} \oplus T_{\text{Reachability}} \oplus T_{\text{set}} \oplus T_{\text{setth}}$$

$$\Sigma_{\text{setth}} = \left\{ \begin{array}{l} \{\text{thid}, \text{setth}\} \\ \left\{ \begin{array}{l} \emptyset_T \quad : \quad \text{setth} \\ \{-\}_T \quad : \quad \text{thid} \rightarrow \text{setth} \\ \cup_T, \cap_T, \setminus_T \quad : \quad \text{setth} \times \text{setth} \rightarrow \text{setth} \end{array} \right\} \\ \left\{ \begin{array}{l} \in_T \quad : \quad \text{thid} \times \text{setth} \\ \subseteq_T \quad : \quad \text{setth} \times \text{setth} \end{array} \right\} \end{array} \right\}$$

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$$\Sigma_{\text{setth}} = \{\text{thid}\}, \emptyset, \emptyset$$

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$$\Sigma_{\text{mrgn}} = \left\{ \begin{array}{l} \{\text{mrgn}, \text{addr}, \text{level}_K\} \\ \mathbf{emp}_{\text{mr}} : \text{mrgn} \\ \langle -, - \rangle_{\text{mr}} : \text{addr} \times \text{level}_K \rightarrow \text{mrgn} \\ \cup_{\text{mr}}, \cap_{\text{mr}}, -_{\text{mr}} : \text{mrgn} \times \text{mrgn} \rightarrow \text{mrgn} \\ \left\{ \begin{array}{l} \in_{\text{mr}} : \text{addr} \times \text{level}_K \times \text{mrgn} \\ \subseteq_{\text{mr}} : \text{mrgn} \times \text{mrgn} \\ \#_{\text{mr}} : \text{mrgn} \times \text{mrgn} \end{array} \right\} \end{array} \right\}$$

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$$\Sigma_{\text{ord}} = \left\{ \begin{array}{l} \{ \text{ord} \} \\ \left\{ \begin{array}{l} 0 \\ +\infty \end{array} : \text{ord} \right\} \\ \{ \perp : \text{ord} \times \text{ord} \} \end{array} \right\}$$

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$$\Sigma_{\text{level}_K} = \left\{ \begin{array}{l} \{ \text{level}_K \} \\ \eta_1 : \text{level} \\ \vdots \\ \eta_K : \text{level} \end{array} \right\}$$

\emptyset

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$$\Sigma_{\text{Bridge}} = \left. \begin{array}{l} \{ \text{mem, addr, set, path} \} \\ \left\{ \begin{array}{l} \textit{path2set} \quad : \quad \text{path} \rightarrow \text{set} \\ \textit{addr2set}_K \quad : \quad \text{mem} \times \text{addr} \times \text{level}_K \rightarrow \text{set} \\ \textit{getp}_K \quad : \quad \text{mem} \times \text{addr} \times \text{addr} \times \text{level}_K \rightarrow \text{path} \\ \textit{firstlocked}_K \quad : \quad \text{mem} \times \text{path} \times \text{level}_K \rightarrow \text{addr} \end{array} \right\} \\ \left\{ \textit{ordList} \quad : \quad \text{mem} \times \text{path} \right\} \end{array} \right\}$$

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- ▶ We want to use Nelson-Oppen

Theory of Concurrent Skiplists of Height K (TSL_K)

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 - ▶ Decision procedure

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- ▶ We want to use Nelson-Oppen
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 - ▶ Decision procedure
- ▶ Problem

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- ▶ We want to use Nelson-Oppen
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 - ▶ No decision procedure for reachability

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- ▶ We want to use Nelson-Oppen
 - ▶ Stable infinite
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 - ▶ Decision procedure
- ▶ Problem
 - ▶ No decision procedure for reachability
 - ▶ Eliminate bridge functions and predicates, preserving satisfiability

Small Model Property

Small Model Property

Given a theory T with $\Sigma = (S, F, P)$ and $S_0 \subseteq S$

T has SMP with respect to S_0 , if for every T -satisfiable QF Σ -formula φ exists T -interpretation \mathcal{A} satisfying φ s.t. \mathcal{A}_σ is finite, for every $\sigma \in S_0$

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- ▶ Proof that exists a TSL_K -interpretation \mathcal{A}
 - ▶ Bounded on K and Γ .
 - ▶ With finite number of elements in addr , elem , thid , ord and level_K .

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Γ is also T -satisfiable in \mathcal{A}

- ▶ TSL_K enjoys the small model property

A Decision Procedure for TSL_K

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$$\text{TSL}_K = \cdots \oplus T_{\text{Reachability}} \oplus \cdots \oplus \textit{bridge functions and predicates}$$

A Decision Procedure for TSL_K

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$$T_{\text{Base}} = T_{\text{addr}} \oplus T_{\text{elem}} \oplus T_{\text{cell}} \oplus T_{\text{mem}} \oplus T_{\text{fseq}} \oplus T_{\text{set}} \oplus T_{\text{seth}} \oplus T_{\text{thid}} \oplus T_{\text{mrgn}} \oplus T_{\text{ord}} \oplus T_{\text{level}_K}$$

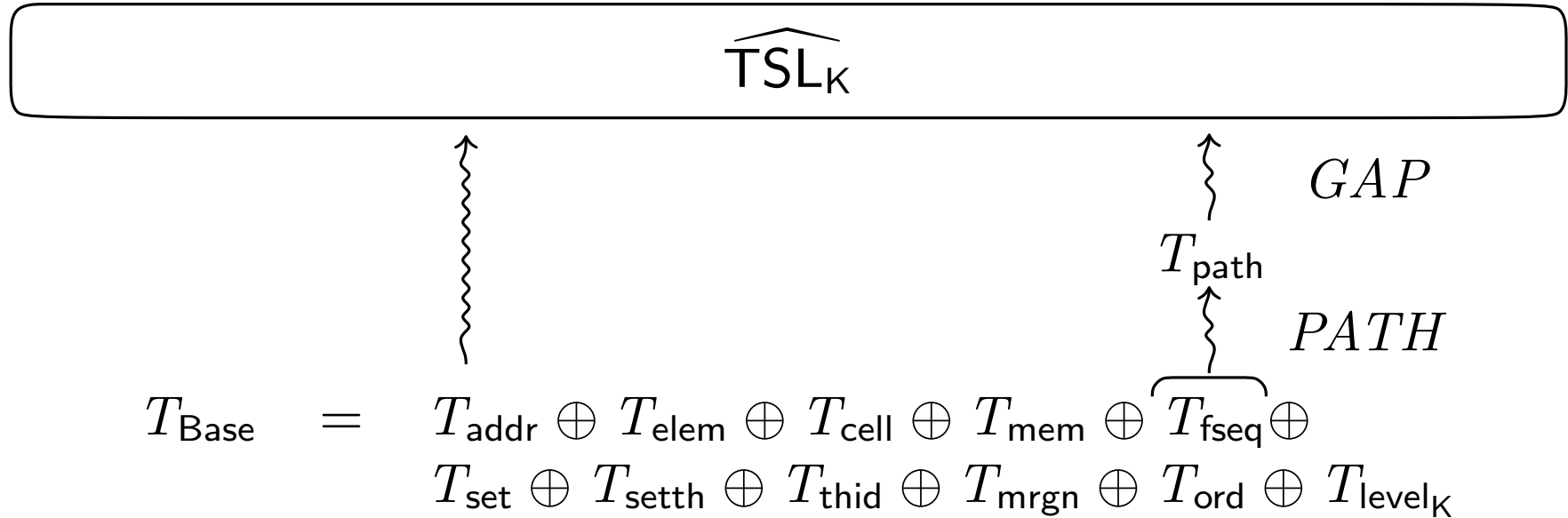
A Decision Procedure for TSL_K

$$TSL_K = \dots \oplus T_{\text{Reachability}} \oplus \dots \oplus \textit{bridge functions and predicates}$$

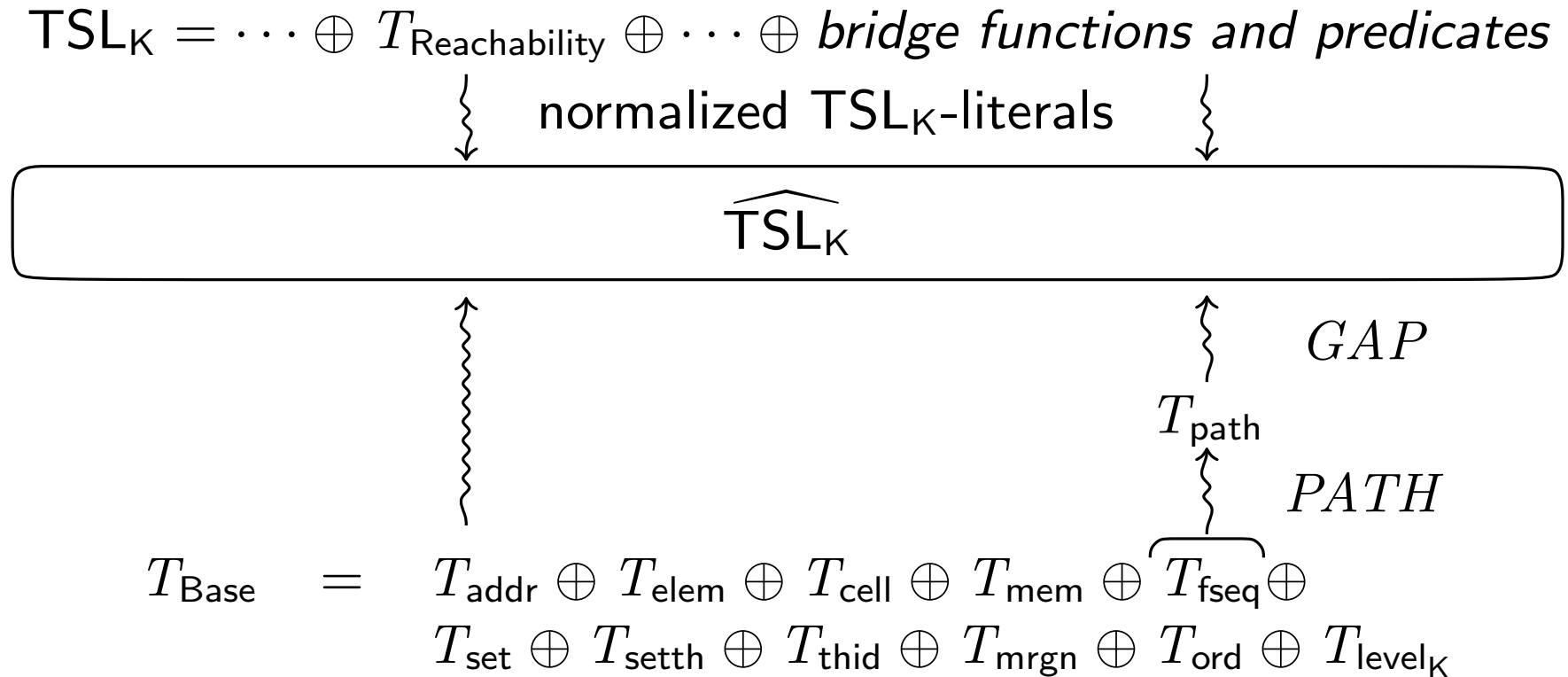
$$T_{\text{Base}} = T_{\text{addr}} \oplus T_{\text{elem}} \oplus T_{\text{cell}} \oplus T_{\text{mem}} \oplus \overbrace{T_{\text{fseq}} \oplus T_{\text{set}} \oplus T_{\text{setth}} \oplus T_{\text{thid}} \oplus T_{\text{mrgn}} \oplus T_{\text{ord}} \oplus T_{\text{level}_K}}^{T_{\text{path}} \textit{ PATH}}$$

A Decision Procedure for TSL_K

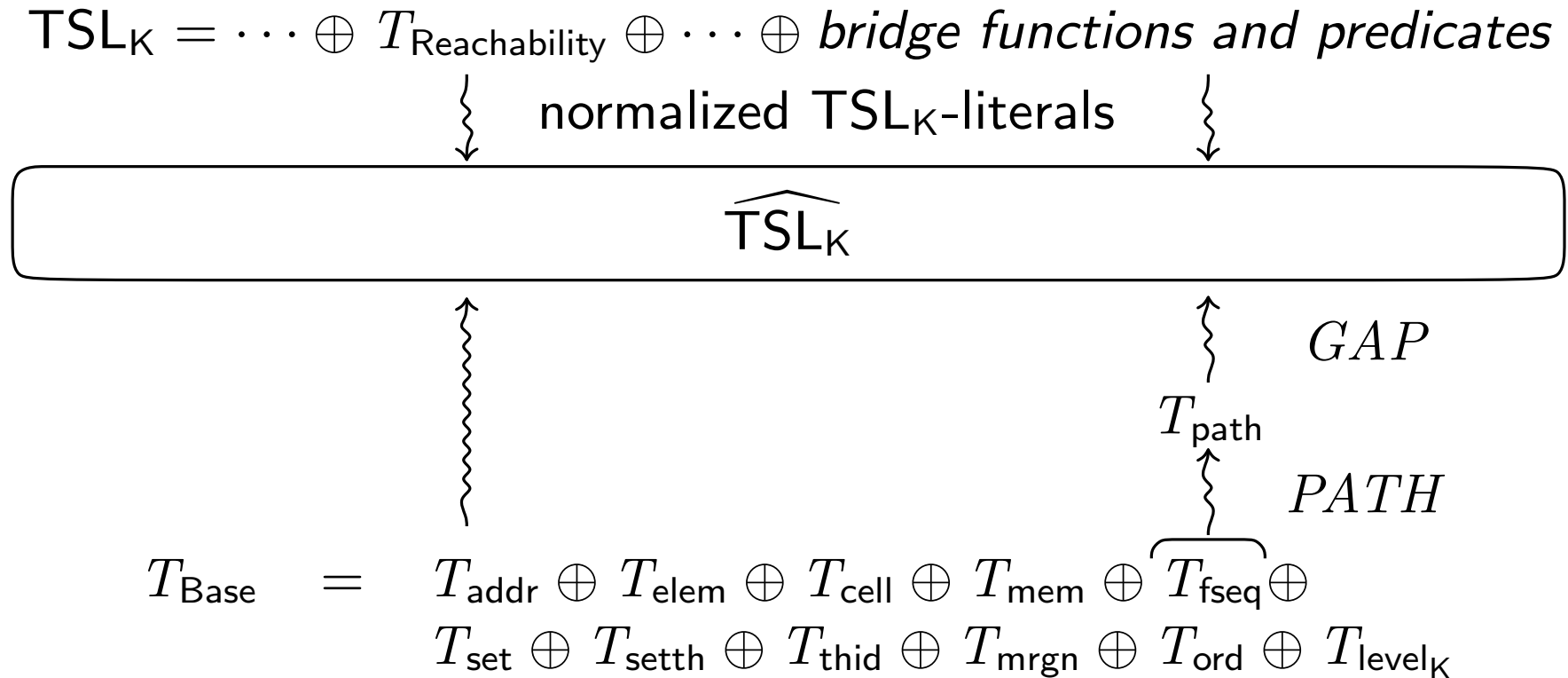
$$TSL_K = \dots \oplus T_{\text{Reachability}} \oplus \dots \oplus \text{bridge functions and predicates}$$



A Decision Procedure for TSL_K

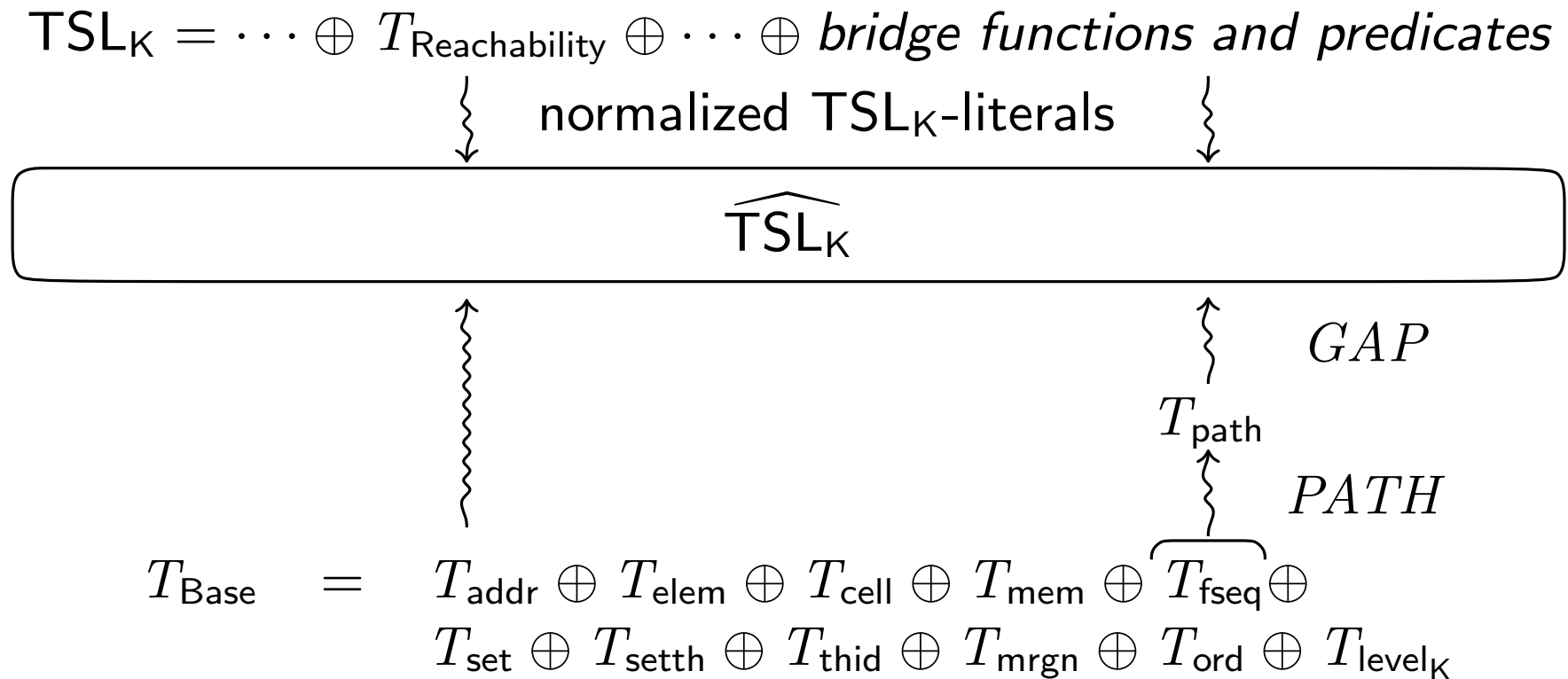


A Decision Procedure for TSL_K



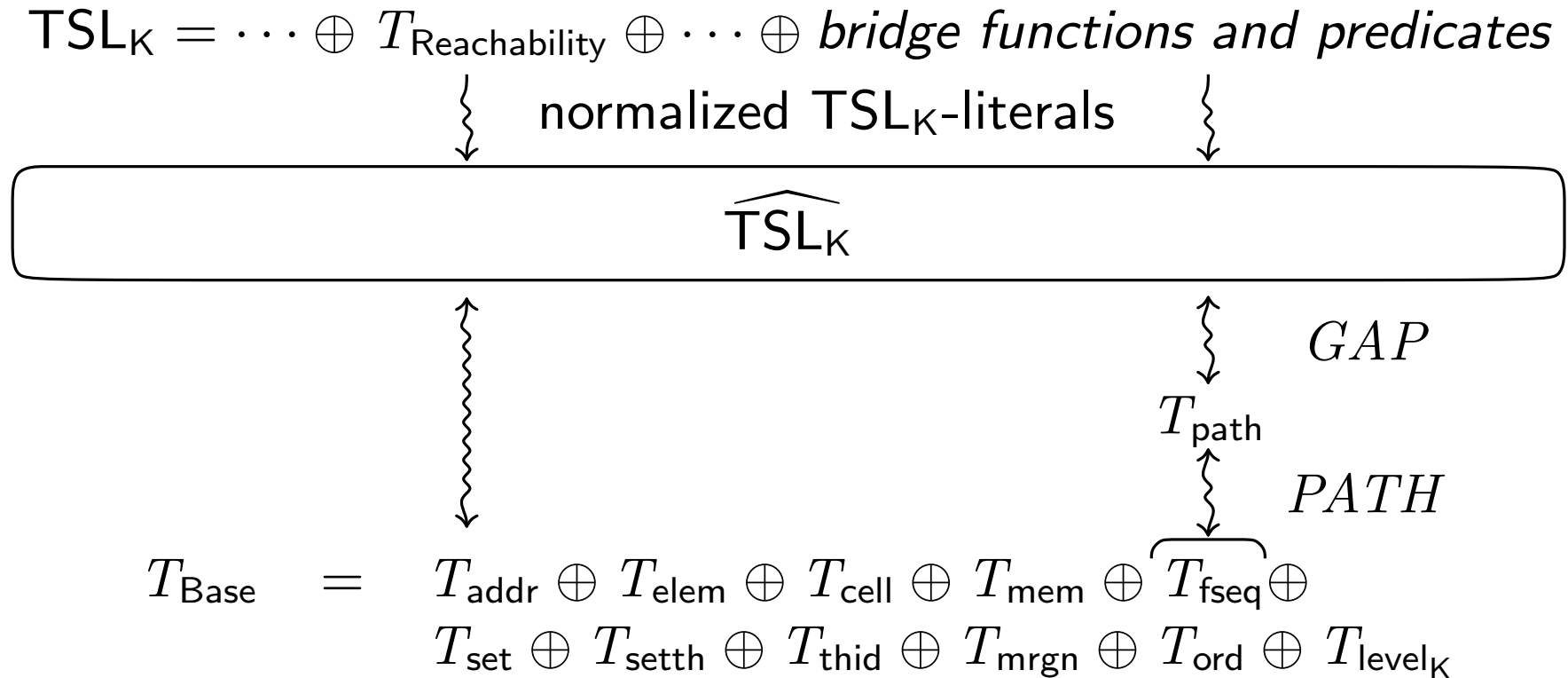
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A Decision Procedure for TSL_K



- ▶ By SMP it is always possible to enumerate all finitely many ground terms
- ▶ Unfolding of definitions in $PATH$ and GAP

A Decision Procedure for TSL_K



- ▶ By SMP it is always possible to enumerate all finitely many ground terms
- ▶ Unfolding of definitions in *PATH* and *GAP*

Conclusions

- ▶ A method to verify Concurrent Datastructures
- ▶ Thanks to Decision Procedures, automatic verification for
 - ▶ Concurrent Single Linked Lists
 - ▶ Concurrent Skiplists
- ▶ Future work
 - ▶ Other concurrent datastructures (trees, graphs...)
 - ▶ Implementation
- ▶ Many possible collaborations:
 - ▶ Decision procedures as combinations
 - ▶ Use of STM

Small Model Property

Let Γ be a conjunction of normalized TSL_K -literals. Let $\bar{e} = |V_{\text{elem}}(\Gamma)|$, $\bar{a} = |V_{\text{addr}}(\Gamma)|$, $\bar{m} = |V_{\text{mem}}(\Gamma)|$, $\bar{p} = |V_{\text{path}}(\Gamma)|$, $\bar{t} = |V_{\text{thid}}(\Gamma)|$ and $\bar{o} = |V_{\text{ord}}(\Gamma)|$. Then the following are equivalent:

- ▶ Γ is TSL_K -satisfiable;
- ▶ Γ is true in a TSL_K interpretation \mathcal{A} such that

$$|\mathcal{A}_{\text{addr}}| \leq \bar{a} + 1 + \bar{m} \bar{a} + \bar{p}^2 + \bar{p}^3 + (\mathbf{K} + 2)\bar{m}\bar{p}$$

$$|\mathcal{A}_{\text{elem}}| \leq \bar{e} + \bar{m} |\mathcal{A}_{\text{addr}}|$$

$$|\mathcal{A}_{\text{thid}}| \leq \bar{k} + \mathbf{K}\bar{m} |\mathcal{A}_{\text{addr}}| + 1$$

$$|\mathcal{A}_{\text{level}_K}| \leq \mathbf{K}$$

$$|\mathcal{A}_{\text{ord}}| \leq \bar{o} + \bar{m} |\mathcal{A}_{\text{addr}}|$$

Small Model Property

$$L = \{\eta_i \mid 1 \leq i \leq K\}$$

$$O = V_{\text{ord}}^{\mathcal{B}} \cup \{m^{\mathcal{B}}(v).key^{\mathcal{B}} \mid m \in V_{\text{mem}} \text{ and } v \in X\}$$

$$\begin{aligned} X = & V_{\text{addr}}^{\mathcal{B}} \cup \{null^{\mathcal{B}}\} \cup \\ & \{m^{\mathcal{B}}(v^{\mathcal{B}}).next^{\mathcal{B}} \mid m \in V_{\text{mem}} \text{ and } v \in V_{\text{addr}}\} \cup \\ & \{v \in \delta(p^{\mathcal{B}}, q^{\mathcal{B}}) \mid \text{the literal } p \neq q \text{ is in } \Gamma\} \cup \\ & \{v \in \sigma(p_1^{\mathcal{B}}, p_2^{\mathcal{B}}) \mid \text{the literal } \neg append(p_1, p_2, p_3) \text{ is in } \Gamma \text{ and} \\ & \quad path2set^{\mathcal{B}}(p_1^{\mathcal{B}}) \cap path2set^{\mathcal{B}}(p_2^{\mathcal{B}}) \neq \emptyset\} \cup \\ & \{v \in \sigma(p_1^{\mathcal{B}} \circ p_2^{\mathcal{B}}, p_3^{\mathcal{B}}) \mid \text{the literal } \neg append(p_1, p_2, p_3) \text{ is in } \Gamma \text{ and} \\ & \quad path2set^{\mathcal{B}}(p_1^{\mathcal{B}}) \cap path2set^{\mathcal{B}}(p_2^{\mathcal{B}}) = \emptyset\} \cup \\ & \{v \in \kappa(m, p, l) \mid firstlocked(m, p, l) \text{ is in } \Gamma\} \\ & \{v \in \xi(m, p) \mid \neg ordList(m, p) \text{ is in } \Gamma\} \end{aligned}$$

$$Y = V_{\text{thid}}^{\mathcal{B}} \cup \{\emptyset\} \cup \{m^{\mathcal{B}}(v).lockid^{\mathcal{B}} \mid m \in V_{\text{mem}} \text{ and } v \in X\}$$

$$Z = V_{\text{elem}}^{\mathcal{B}} \cup \{m^{\mathcal{B}}(v).data^{\mathcal{B}} \mid m \in V_{\text{mem}} \text{ and } v \in X\}$$

PATH definitions

$$app : fseq \times fseq \rightarrow fseq$$
$$app(nil, l) = l$$
$$app(cons(a, l), l') = cons(a, app(l, l'))$$
$$fseq2set : fseq \rightarrow set$$
$$fseq2set(nil) = \emptyset$$
$$fseq2set(cons(a, l)) = \{a\} \cup fseq2set(l)$$
$$ispath : fseq$$
$$ispath(nil)$$
$$ispath(cons(a, nil))$$
$$\{a\} \not\subseteq fseq2set(l) \wedge ispath(l) \rightarrow ispath(cons(a, l))$$
$$last : fseq \rightarrow addr$$
$$last(cons(a, nil)) = a$$
$$l \neq nil \rightarrow last(cons(a, l)) = last(l)$$
$$isreachable : mem \times addr \times addr$$
$$isreachable(m, a, a)$$
$$m[a].next = a' \wedge isreachable(m, a', b) \rightarrow isreachable(m, a, b)$$
$$isreachablep : mem \times addr \times addr \times fseq$$
$$isreachablep(m, a, a, nil)$$
$$m[a].next = a' \wedge isreachablep(m, a', b, p) \rightarrow isreachablep(m, a, b, cons(a, p))$$
$$firstmarked : mem \times fseq \times addr$$
$$firstmarked(m, nil, null)$$
$$p \neq nil \wedge p = cons(j, q) \wedge m[j].lockid \neq \emptyset \rightarrow firstmarked(m, p, j)$$
$$p \neq nil \wedge p = cons(j, q) \wedge m[j].lockid = \emptyset \wedge firstmarked(m, q, i) \rightarrow firstmarked(m, p, i)$$

GAP definitions

$$nil = \epsilon$$

$$cons(a, nil) = [a]$$

$$\left(\begin{array}{l} ispath(p_1) \wedge ispath(p_2) \wedge \\ fseq2set(p_1) \cap fseq2set(p_2) = \emptyset \wedge \\ app(p_1, p_2) = p_3 \end{array} \right) \leftrightarrow append(p_1, p_2, p_3)$$

$$ispath(p) \rightarrow isreachable_{\kappa}(m, a, b, l, p) = reach_{\kappa}(m, a, b, l, p)$$

$$ispath(p) \rightarrow fseq2set(p) = path2set(p)$$

$$isreachable_{\kappa}(m, a, b, l, p) \rightarrow getp_{\kappa}(m, a, b, l) = p$$

$$\neg isreachable_{\kappa}(m, a, b, l, p) \rightarrow getp_{\kappa}(m, a, b, l) = nil$$

$$ispath(p) \wedge firstmarked(m, p, l, i) \leftrightarrow firstlocked(m, p, l) = i$$

$$ispath(p) \wedge ordPath(m, p) \leftrightarrow ordList(m, p)$$