

Bayesian Inference and Traffic Analysis

Carmela Troncoso
George Danezis

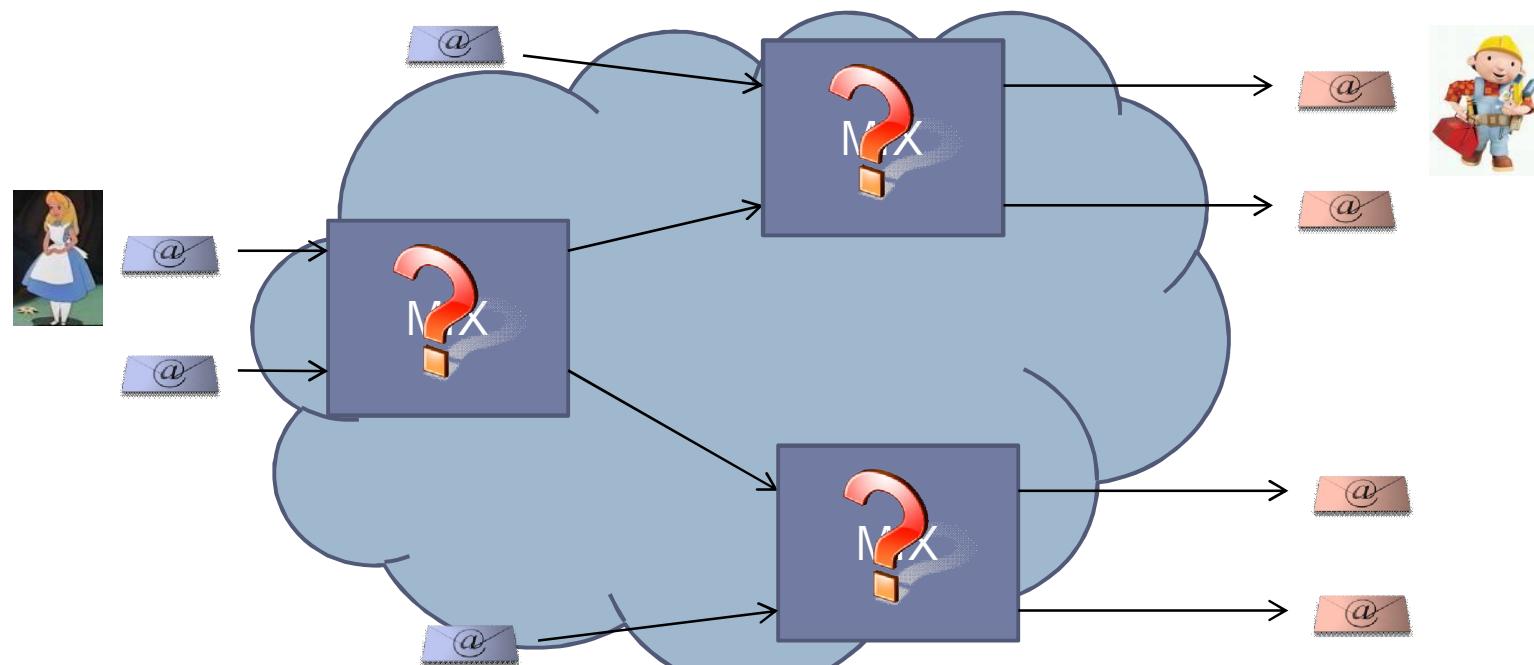
University of Texas at Arlington 16/11/2009
Microsoft Research Cambridge/ KU Leuven(COSIC)

Outline

- ▶ The traffic analysis problem and a bayesian approach
 - ▶ What is this all about
- ▶ Modelling mix networks
 - ▶ The boring part of the talk
- ▶ Markov Chain Monte Carlo methods and traffic analysis
 - ▶ The exciting part of the talk
- ▶ Evaluation and results
 - ▶ It actually works!
- ▶ Conclusions

Mix networks

- ▶ Mixes are combined in networks in order to
 - ▶ Distribute trust (one good mix is enough)
 - ▶ Load balancing (no mix is big enough)

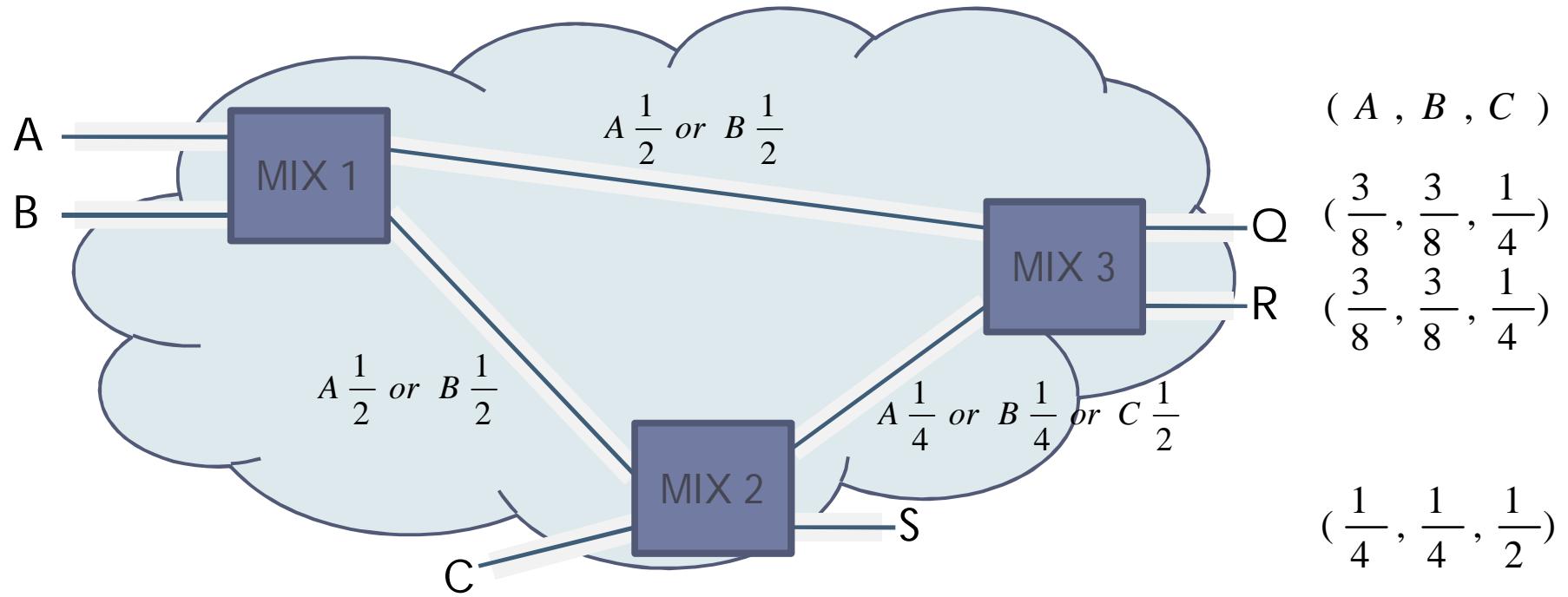


Attacks against mix networks

- ▶ Uncover who speaks to whom
 - ▶ Observe all links (*Global Passive Adversary*)
- ▶ Restricted routes [Dan03]
 - ▶ Messages cannot follow any route
- ▶ Bridging and Fingerprinting [DanSv08]
 - ▶ Users have partial knowledge of the network
- ▶ Long term disclosure attacks:
 - ▶ Exploit persistent patterns
 - ▶ Disclosure Attack [Kes03], Statistical Disclosure Attack [Dan03], Perfect Matching Disclosure Attacks [Tron-et-al08]
- ▶ Based on heuristics and specific models, not generic

Mix networks and traffic analysis

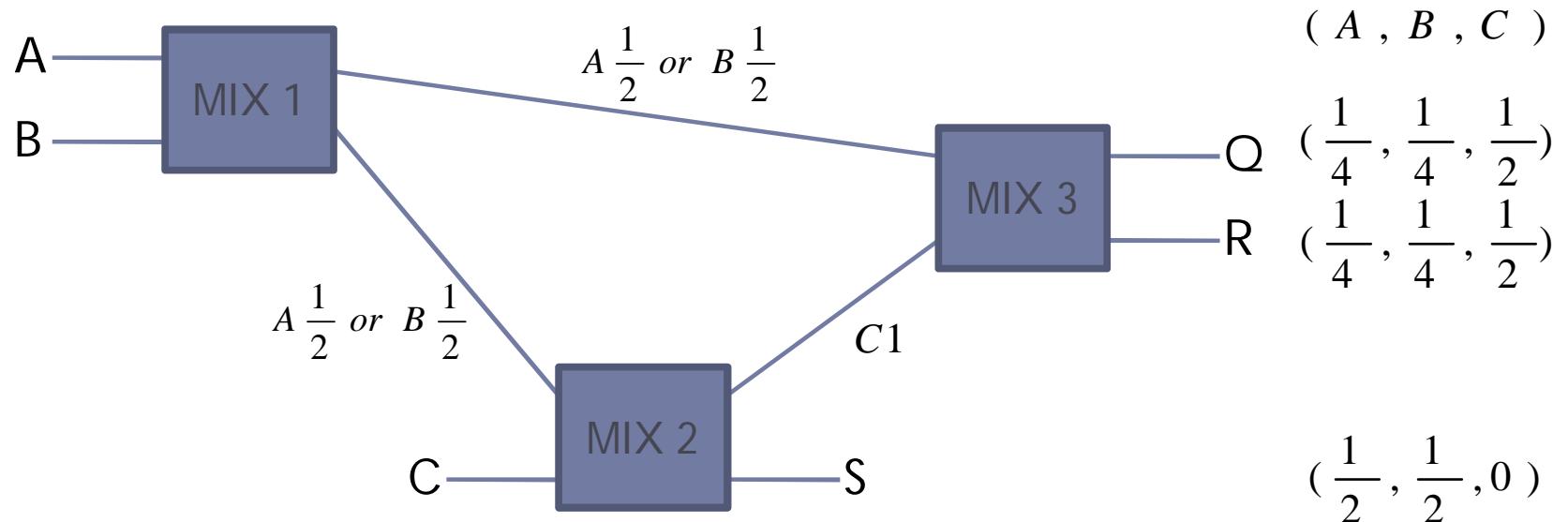
- ▶ Determine probability distributions input-output



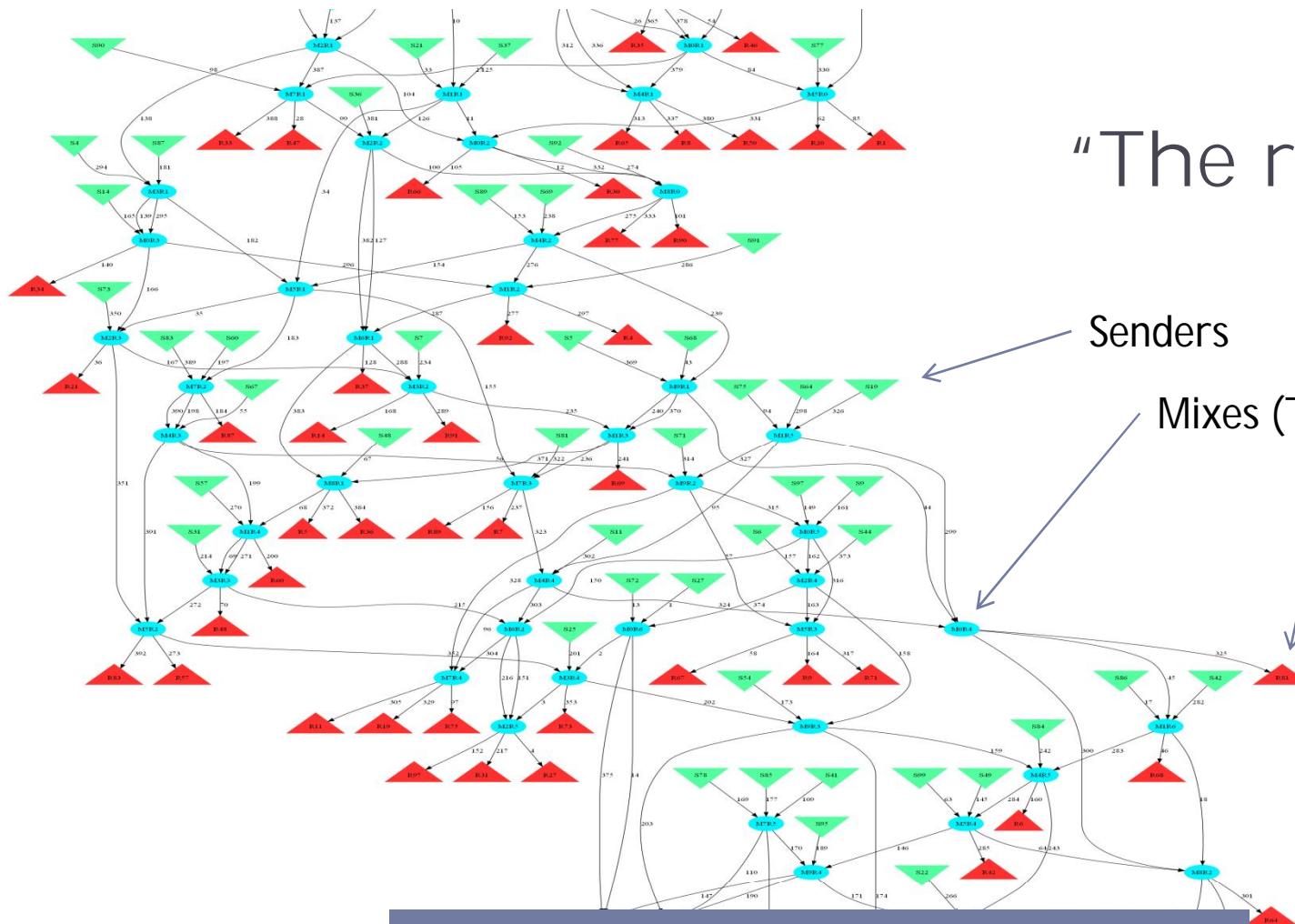
- ▶ Threshold mix: collect t messages, and outputs them changing their appearance and in a random order

Mix networks and traffic analysis

- ▶ Constraints, e.g. length=2



Non trivial given observation!!



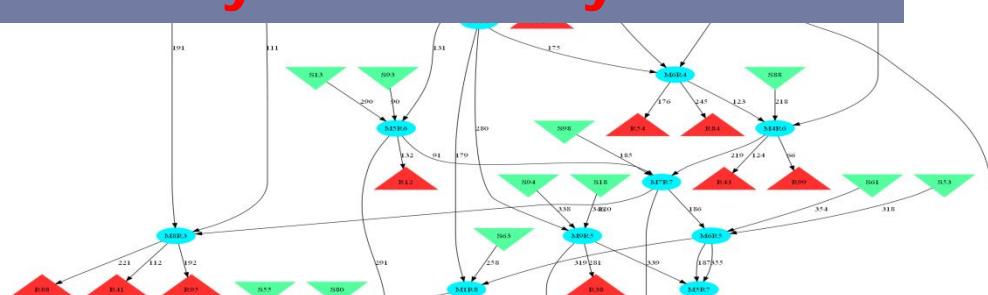
"The real thing"

Senders

Mixes (Threshold = 3)

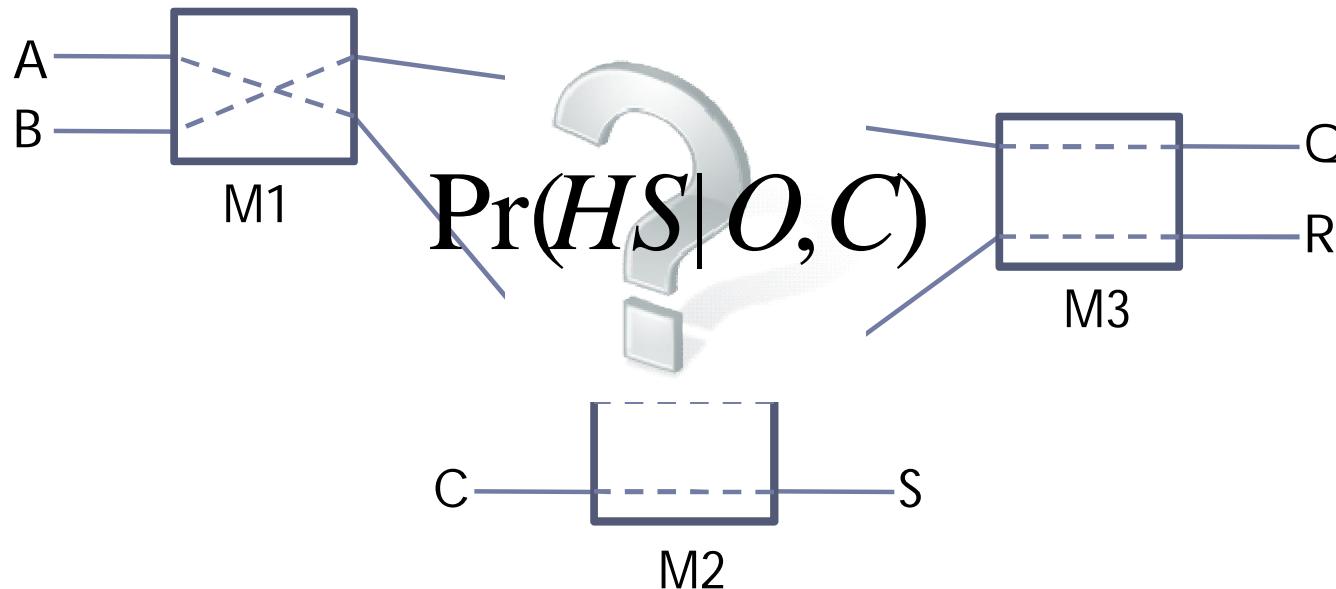
Receivers

**How to compute probabilities
systematically??**



Redefining the traffic analysis problem

- ▶ Find “*hidden state*” of the mixes



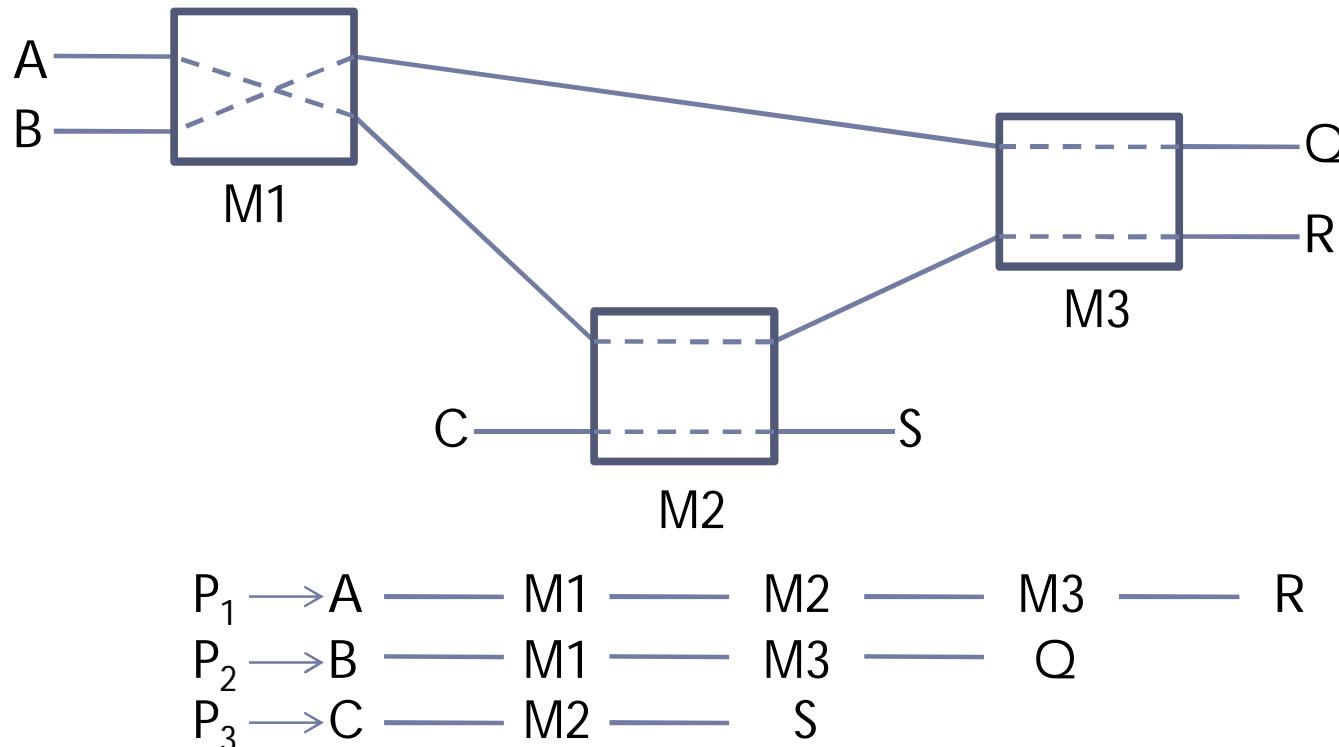
$$\Pr(HS | O, C) = \frac{\Pr(O | HS, C) \cdot \Pr(HS | C)}{\sum_{HS} \Pr(HS, O | C)} = \frac{\Pr(O | HS, C) \cdot K}{Z}$$

Too large to enumerate!!

Pr(*O* | *HS*, *C*) · *K*
Z

Redefining the traffic analysis problem

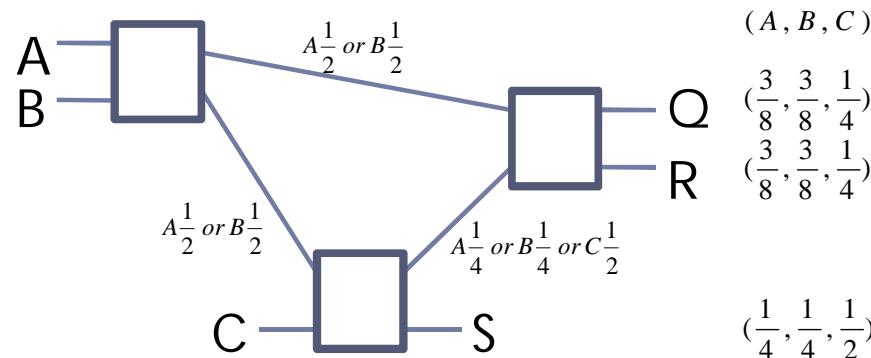
- ▶ “Hidden State” + Observation = Paths



$$\Pr(HS \mid O, C) = \frac{\Pr(O \mid HS, C) \cdot K}{Z} = \frac{\Pr(Paths \mid C)}{Z}$$

Sampling to estimate probabilities (I)

- ▶ Actually... we want marginal probabilities $\Pr(A \rightarrow Q | O, C)$



$$\Pr(A \rightarrow Q | O, C) = \frac{\sum_{HS} I_{A \rightarrow Q}(HS_j)}{j}$$

- ▶ But... we cannot obtain them directly

Sampling to estimate probabilities (II)

- ▶ If we obtain samples

$$HS_1, HS_2, HS_3, HS_4, \dots, HS_N \sim \Pr(HS \mid O, C)$$



$(A \rightarrow Q)? \quad 0 \quad 1 \quad 0 \quad 1 \quad \dots \quad 1$

$$\Pr(A \rightarrow Q \mid O, C) \approx \frac{\sum_j I_{A \rightarrow Q}(HS_j)}{N}$$

- ▶ Markov Chain Monte Carlo Methods

$$\Pr(HS \mid O, C) = \frac{\Pr(Paths \mid C)}{Z}$$

How does $\Pr(Paths/C)$ look like?

Modelling mix networks

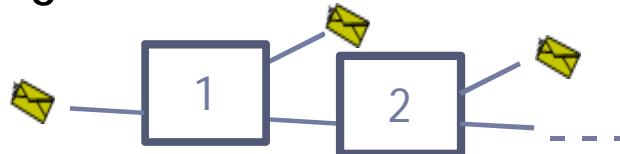
(The boring part of the talk)

Probabilistic model – Basic Constraints

- ▶ Users decide independently

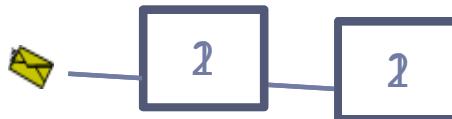
$$\Pr(\text{Paths} \mid C) = \prod_x \Pr(P_x \mid C)$$

- ▶ Length restrictions $\Pr(L = l \mid C)$ with any distribution



- ▶ e.g. uniform (L_{\min}, L_{\max}) $\Pr(L = l \mid C) = \frac{1}{L_{\max} - L_{\min}}$

- ▶ Node choice restrictions

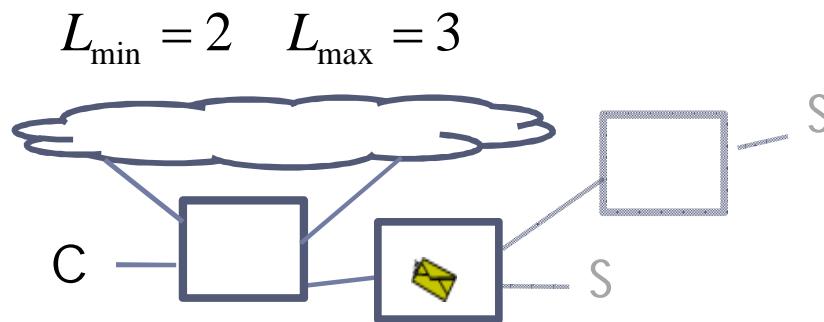


- ▶ Choose 1 out of the N_{mix} node available $\Pr(M_x \mid L = l, C) = \frac{1}{P(N_{\text{mix}}, l)}$
- ▶ Choose a set $I_{\text{set}}(M_x)$

$$\Pr(P_x \mid C) = \Pr(L = l \mid C) \cdot \Pr(M_x \mid L = l, C) \cdot I_{\text{set}}(M_x)$$

Probabilistic model – Basic Constraints

- ▶ Unknown destinations



$$\Pr(P_x | C) = \left[\sum_{l=L_{obs}}^{L_{\max}} \Pr(L = l | C) \cdot \Pr(M_x | L = l, C) \cdot I_{set}(M_x) \right]$$

Probabilistic model – More Constraints

- ▶ Bridging: users can only send through mixes they know

$$\Pr(P_x | C) = \Pr(L = l | C) \cdot \Pr(M_x | L = l, C) \cdot I_{set}(M_x) \cdot I_{bridging}(M_x)$$

- ▶ Non-compliant clients (with probability $p_{\overline{cp}}$)
 - ▶ Do not respect length restrictions $(L_{\min, \overline{cp}}, L_{\max, \overline{cp}})$
 - ▶ Choose l out of the N_{mix} node available, allow repetitions

$$\Pr(M_x | L = l, C, I_{\overline{cp}}(Path)) = \frac{1}{P_r(N_{mix}, l)}$$

$$\Pr(Paths | C) = \prod_x \Pr(P_x | C)$$

$$\Pr(Paths | C) = \left[\prod_{i \in P_{\overline{cp}}} p_{\overline{cp}} \Pr(P_i | C, I_{\overline{cp}}(P_i)) \right] \cdot \left[\prod_{j \in P_{cp}} (1 - p_{\overline{cp}}) \Pr(P_j | C) \right]$$

Probabilistic model – More constraints

- ▶ Social network information
 - ▶ Assuming we know sending profiles $\Pr(\text{Sen}_x \rightarrow \text{Rec}_x)$

$$\Pr(P_x | C) = \Pr(L = l | C) \cdot \Pr(M_x | L = l, C) \cdot I_{\text{set}}(M_x) \cdot \Pr(\text{Sen}_x \rightarrow \text{Rec}_x)$$

- ▶ Other constraints
 - ▶ Unknown origin
 - ▶ Dummies
 - ▶ Other mixing strategies
 - ▶

Markov Chain Monte Carlo methods and traffic analysis

(The exciting part of the talk)

Markov Chain Monte Carlo

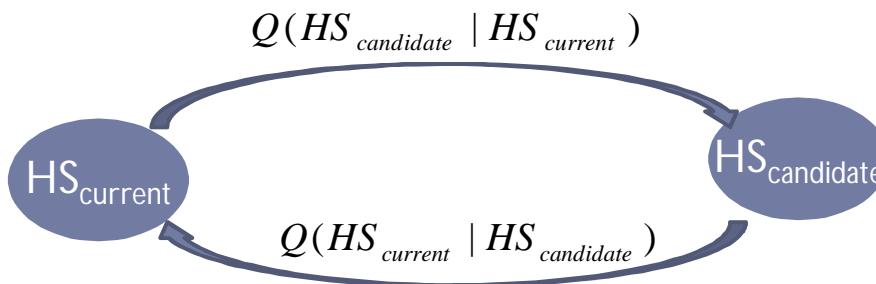
- ▶ Sample from a distribution difficult to sample from directly

$$\Pr(HS | O, C) = \frac{\Pr(O | HS, C) \cdot \Pr(HS | C)}{\sum_{HS} \Pr(HS, O | C)} = \frac{\Pr(O | HS, C) \cdot K}{Z} = \frac{\Pr(Paths | C)}{Z}$$

- ▶ 3 Key advantages:
 - ▶ Requires generative model (we know how to compute it!)
 - ▶ Good estimation of errors
 - ▶ Not false positives and negatives
 - ▶ Systematic

Metropolis Hastings Algorithm

- ▶ Constructs a Markov Chain with stationary distribution $\Pr(HS | O, C)$
 - ▶ Current state \xrightarrow{Q} Candidate state

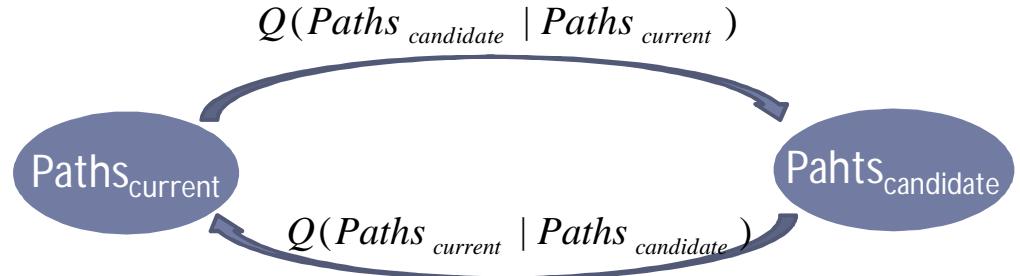


1. Compute $\alpha = \frac{\Pr(HS_{candidate})Q(HS_{candidate} | HS_{current})}{\Pr(HS_{current})Q(HS_{current} | HS_{candidate})}$
2. If $\alpha \geq 1$
 $HS_{current} = HS_{candidate}$ **Go!**
else $u \sim U(0,1)$
if $u \leq \alpha$
 $HS_{current} = HS_{candidate}$ **Go with probability α**
else $HS_{current} = HS_{current}$

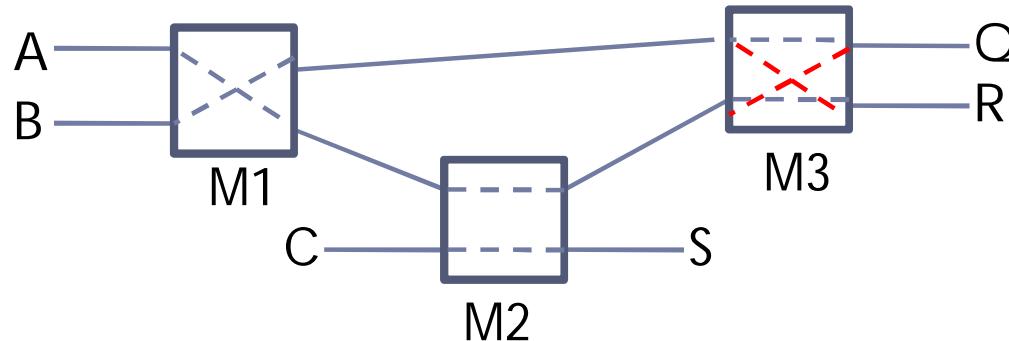
Our sampler: Q transition

$$\Pr(HS | O, C) = \frac{\Pr(Paths | C)}{Z}$$

$$\alpha = \frac{\Pr(Paths_{candidate})Q(Paths_{candidate} | Paths_{current})}{\Pr(Paths_{current})Q(Paths_{current} | Paths_{candidate})}$$



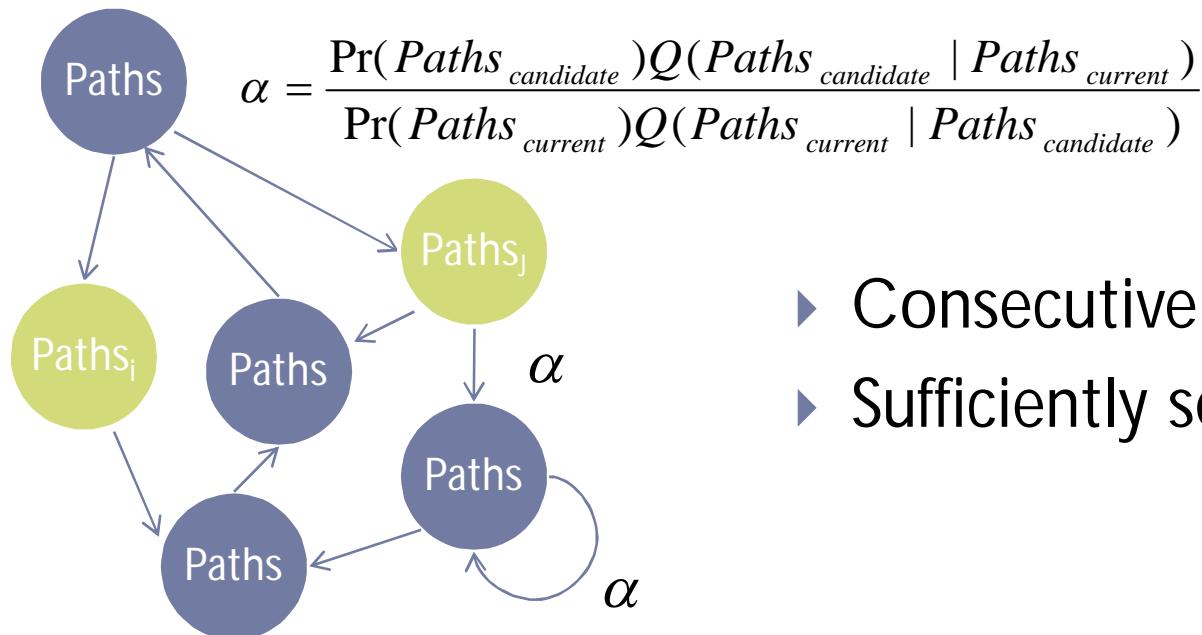
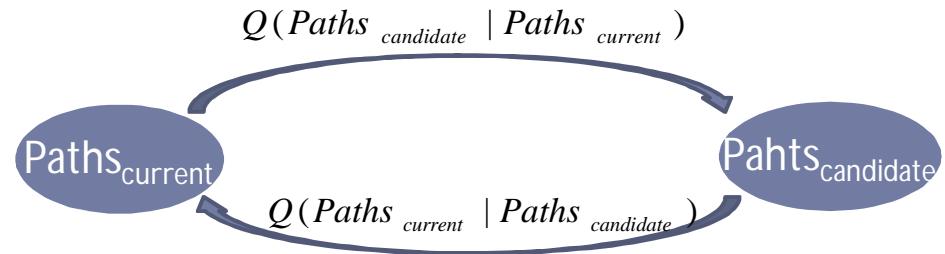
- ▶ Transition Q: swap operation



- ▶ More complicated transitions for non-compliant clients

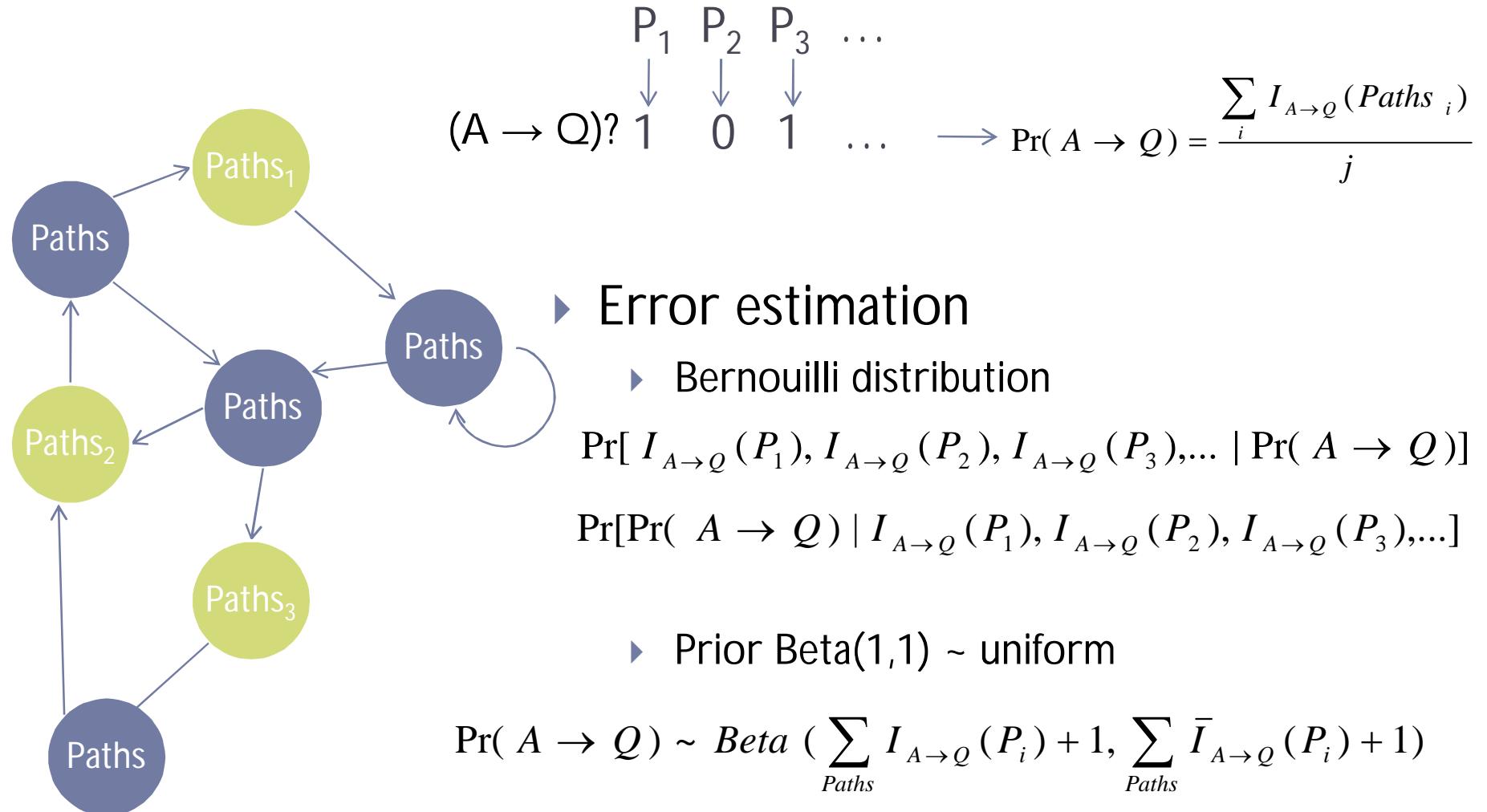
Iterations

$$\Pr(HS | O, C) = \frac{\Pr(Paths | C)}{Z}$$



- ▶ Consecutive samples dependant
- ▶ Sufficiently separated

Sampling error estimation



Evaluation and results

(It actually works!)

Evaluation

Events should happen with the predicted probability

1. Create an instance of a network
2. Run the sampler and obtain P_1, P_2, \dots
3. Choose a target sender and a receiver
4. Predict probability

$$\Pr(\text{Sen} \rightarrow \text{Rec}) \approx \frac{\sum_j I_{\text{Sen} \rightarrow \text{Rec}} (\text{Paths}_j)}{N}$$

5. Check if actually Sen chose Rec as receiver $I_{\text{Sen} \rightarrow \text{Rec}}(\text{network})$
6. Choose new network and go to 2

Example

- ▶ Studying events with $\Pr(\text{Sen} \rightarrow \text{Rec}) = 0.4$

- ▶ Network 1

$$I_{A \rightarrow B}(P_1) = 0; I_{A \rightarrow B}(P_2) = 1; I_{A \rightarrow B}(P_3) = 0; I_{A \rightarrow B}(P_4) = 0; I_{A \rightarrow B}(P_5) = 1$$

$$\Pr(A \rightarrow B) \approx \frac{\sum_j I_{A \rightarrow B}(P_j)}{5} = 0.4; \quad I_{A \rightarrow B}(\text{Network } 1) = 0$$

- ▶ Network 2 $\Pr(X \rightarrow Y) = 0.4; \quad I_{X \rightarrow Y}(\text{Network } 2) = 0$

- ▶ Network 3 $\Pr(X \rightarrow Y) = 0.4; \quad I_{X \rightarrow Y}(\text{Network } 3) = 1$

- ▶ Network 4 $\Pr(X \rightarrow Y) = 0.4; \quad I_{X \rightarrow Y}(\text{Network } 4) = 1$

- ▶ Network 5 $\Pr(X \rightarrow Y) = 0.4; \quad I_{X \rightarrow Y}(\text{Network } 5) = 0$

$$\Pr_{\text{sampled}}(X \rightarrow Y) = 0.4$$

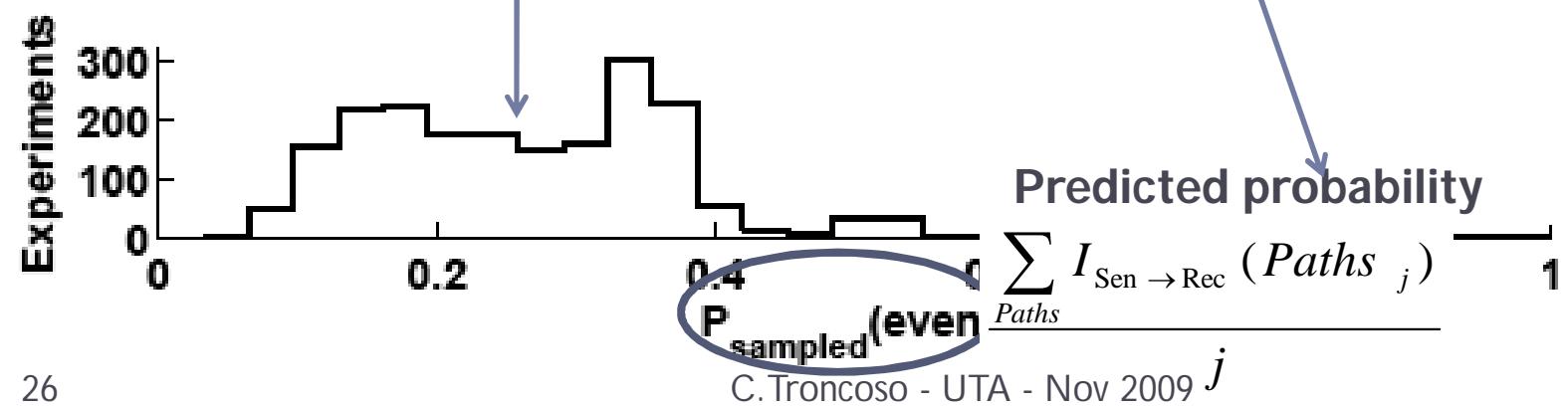
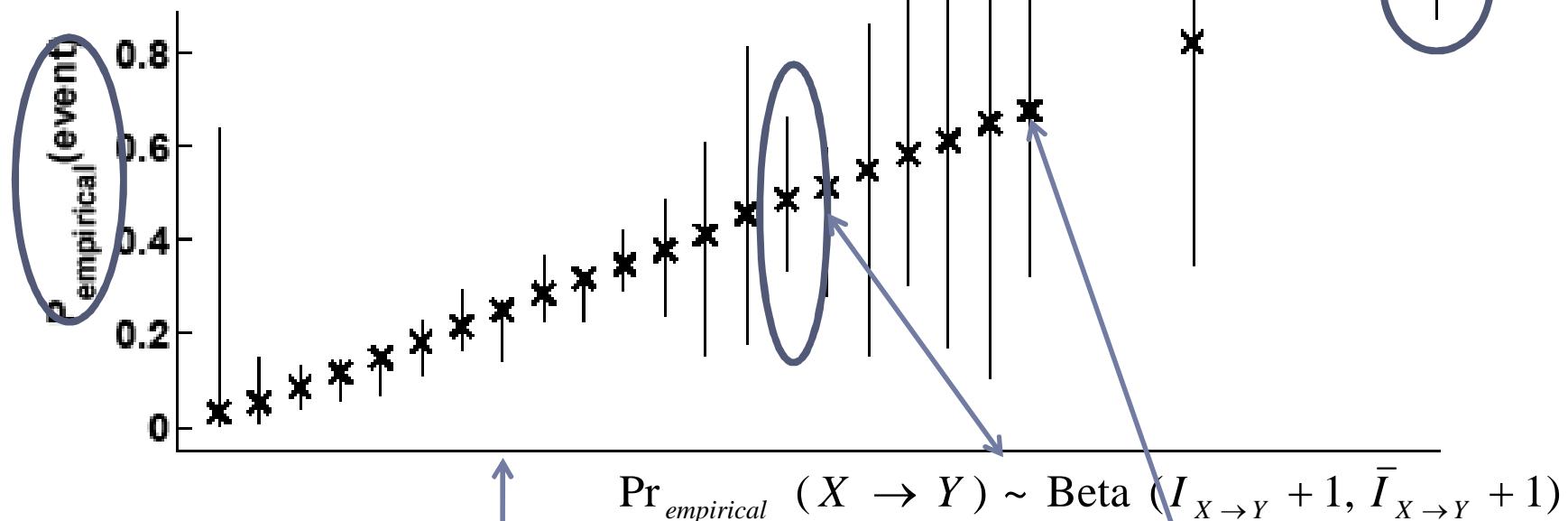
$$\Pr_{\text{empirical}}(X \rightarrow Y) \sim \text{Beta}(2+1, 3+1)$$

X% Confidence intervals

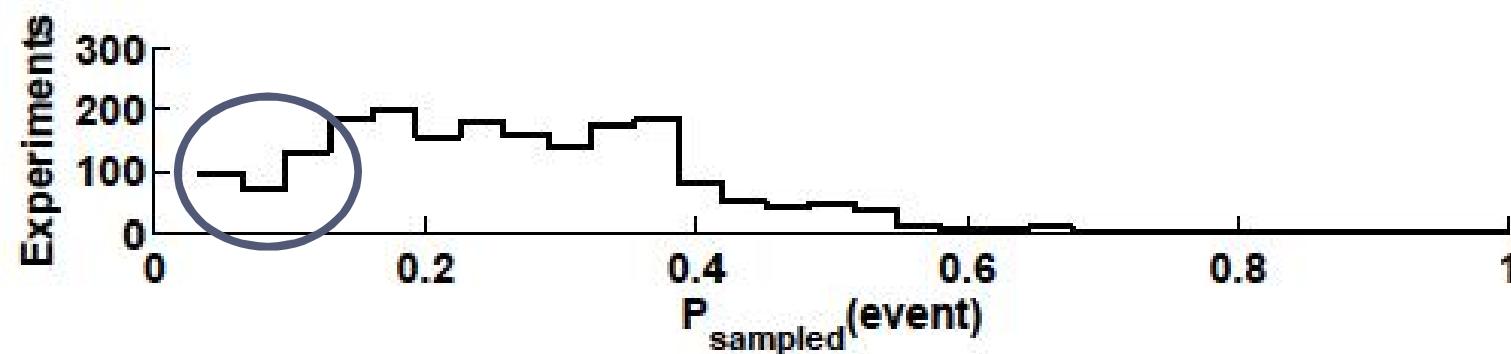
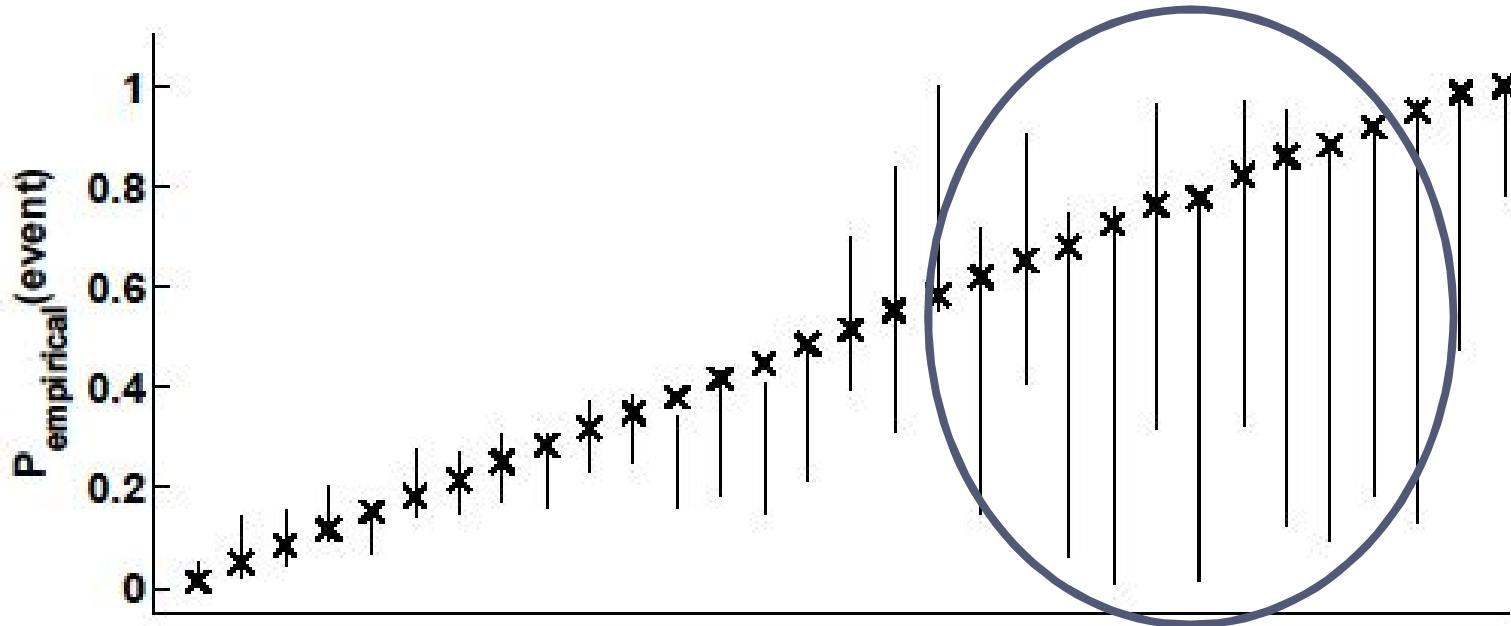
Results – compliant clients – 50 messages

Empirical probability

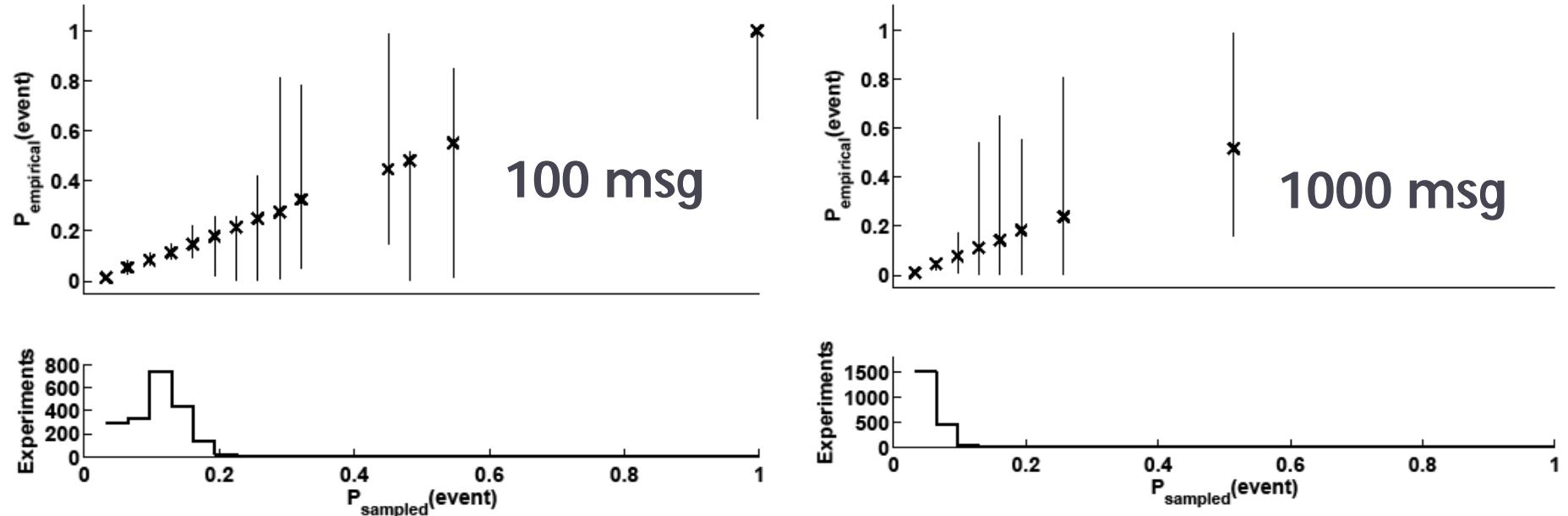
$$E(I_{\text{Sen} \rightarrow \text{Rec}}(\text{network}))$$



Results non compliant – 50 messages



Results – big networks



- ▶ It scales well as networks get larger
- ▶ As expected mix networks offer good protection

Performance – RAM usage

Nmix	t	Nmsg	Samples	RAM(Mb)
3	3	10	500	16
3	3	50	500	18
10	20	50	500	18
10	20	1 000	500	24
10	20	10 000	500	125

- ▶ Size of network and population
- ▶ Results are kept in memory during simulation

Performance – Running time

Nmix	t	Nmsg	iter	Full analysis (min)	One sample(ms)
3	3	10	6011	4.24	509.12
3	3	50	6011	4.80	576.42
5	10	100	7011	5.34	641.28
10	20	1 000	7011	5.97	706.12

- ▶ Operations should be $O(1)$
 - ▶ Writing of the results on a file
 - ▶ Different number of iterations

Applications

- ▶ Evaluation information theoretic metrics for anonymity

$$H = - \sum_{R_i} P(A \rightarrow R_i | O, C) \cdot \log P(A \rightarrow R_i | O, C)$$

- ▶ Estimating probability of arbitrary events
 - ▶ Input message to output message?
 - ▶ Alice speaking to Bob ever?
 - ▶ Two messages having the same sender?
- ▶ Accommodate new constraints
 - ▶ Key to evaluate new mix network proposals

Conclusions

- ▶ Traffic analysis is non trivial when there are constraints
- ▶ Probabilistic model: incorporates most attacks
 - ▶ Non-compliant clients
- ▶ Monte Carlo Markov Chain methods to extract marginal probabilities
 - ▶ Systematic
 - ▶ Only generative model needed
- ▶ Future work:
 - ▶ Model more constraints
 - ▶ Added value?

Time for questions

- ▶ More info
 - ▶ **Vida: How to use Bayesian inference to de-anonymize persistent communications.** George Danezis and Carmela Troncoso. Privacy Enhancing Technologies Symposium 2009
 - ▶ **The Bayesian analysis of mix networks.** Carmela Troncoso and George Danezis. 16th ACM Conference on Computer and Communications Security 2009
 - ▶ **The Application of Bayesian Inference to Traffic analysis.** Carmela Troncoso and George Danezis Microsoft Technical Report

Carmela.Troncoso@esat.kuleuven.be

<http://homes.esat.kuleuven.be/~ctroncos/>

Bayes theorem

$$\Pr(O, HS | C) = \Pr(HS | O, C) \cdot \Pr(O | C)$$

$$\Pr(O, HS | C) = \Pr(O | HS, C) \cdot \Pr(HS | C)$$

$$\Pr(HS | O, C) = \frac{\Pr(O | HS, C) \cdot \Pr(HS | C)}{\Pr(O | C)} = \frac{\Pr(O | HS, C) \cdot \Pr(HS | C)}{\sum_{HS} \Pr(HS, O | C)}$$

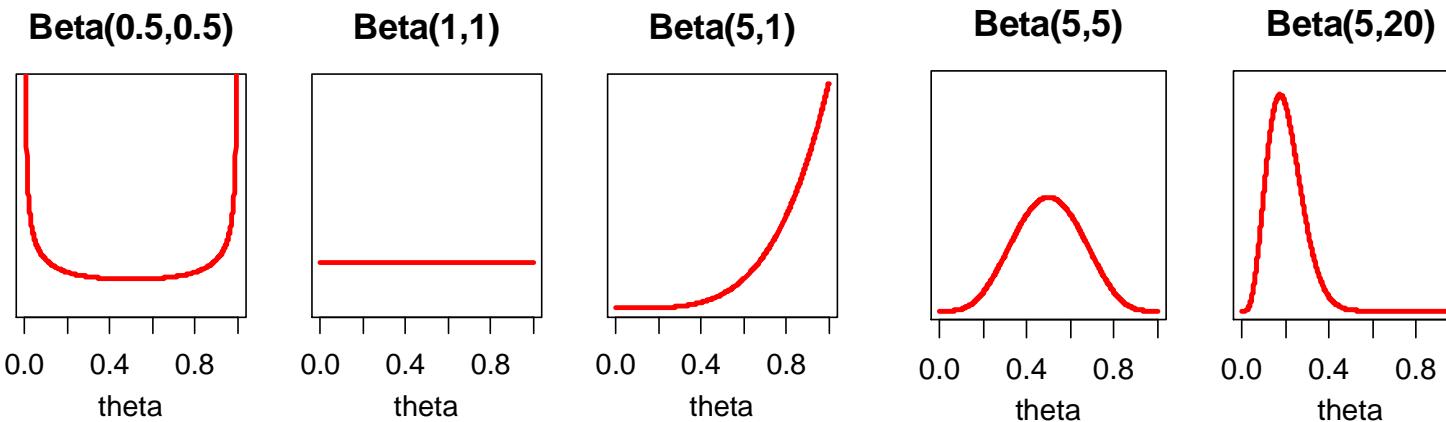
Joint probability:

$$\Pr(X, Y) = \Pr(X | Y) \cdot \Pr(Y) = \Pr(Y | X) \cdot \Pr(X)$$

Error estimation: the Beta function

- ▶ We need to specify the **prior knowledge** $\Pr(\theta)$ ($\Pr(HS | C)$)
 - ▶ expresses our uncertainty
 - ▶ conforms to the nature of the parameter, i.e. is continuous but bounded between 0 and 1
- ▶ A convenient choice is the Beta distribution

$$P(\theta) = \text{Beta}(a, b) = \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} \theta^{a-1} (1-\theta)^{b-1}$$



Error estimation: the Beta function

- ▶ Combining a beta prior with the binomial likelihood gives a posterior distribution

$$p(\theta | \text{total, successes}) = p(\text{successes} | \theta, \text{total}) \cdot p(\theta)$$

$$\propto \theta^{\text{successes}+a-1} (1-\theta)^{\text{total}-\text{successes}+b-1}$$

$$\propto \text{Beta}(\text{successes}+\textcircled{a}, \text{total} - \text{successes} + \textcircled{b})$$

Prior
knowledge