

Property Directed Abstract Interpretation

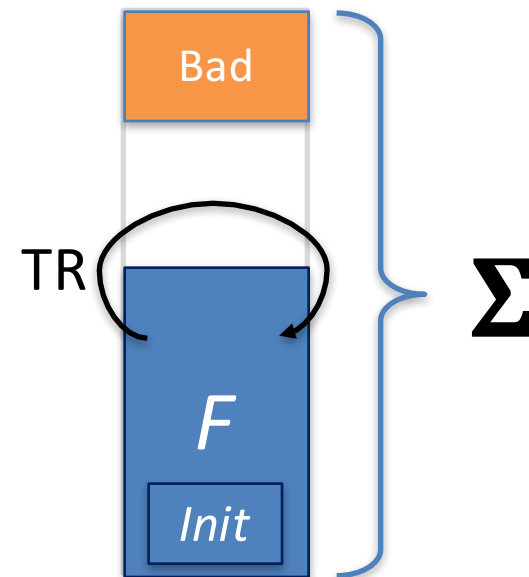
Noam Rinetzky Sharon Shoham

Safety Verification

- Verification problem: ($Init, P, Bad$)
 - $Init \subseteq \Sigma$
 - $TR = TRof(P) \subseteq \Sigma \times \Sigma$
 - $Bad \subseteq \Sigma$
- Can P reach Bad starting from $Init$?
 - Yes (P is **not safe**)
 - No (P is **safe**)

Inductive Invariants

- $F \subseteq \Sigma$ is an **inductive invariant** if:
 - $Init \subseteq F$
 - $TR(F) \subseteq F$
 - $F \cap Bad = \emptyset$
- P is safe $\Leftrightarrow \exists$ inductive invariant



Property Directed Reachability (PDR)

- IC3 [Bradley, VMCAI'11]
- PDR [Een, Mishchenko & Brayton, FMCAD'11]

- IC3/PDR algorithm
 - Infers inductive invariants
 - SAT-based
 - Iterative

Property Directed Reachability (PDR)

- [Bradley, VMCAI'11]
- [Een, Mishchenko & Brayton, FMCAD'11]
- “Dynamic” abstraction
 - Over-approximates bounded executions
 - Abstraction refined as bound grows
 - No spurious cex s.t. $|cex| \leq \text{bound}$
- Output
 - Inductive invariant
 - cex

PDR-based Algorithms

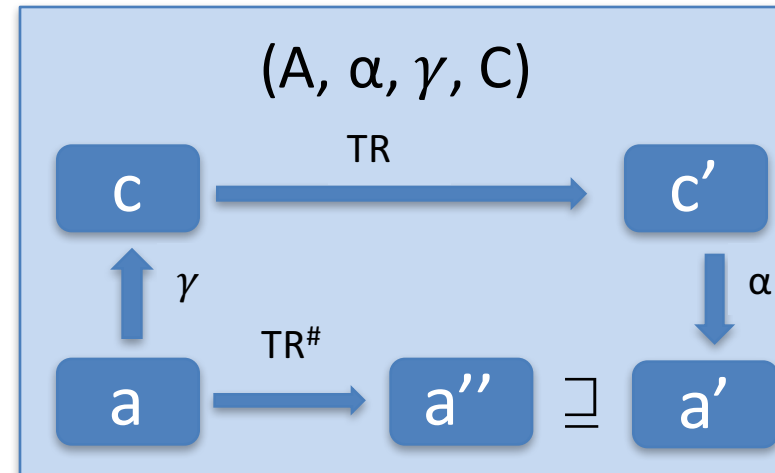
- [Bradley, VMCAI'11]
 - [Een, Mishchenko & Brayton, FMCAD'11]
 - [Cimatti & Griggio, CAV'12]
 - [Hoder & Bjorner, SAT'12]
 - [Bjorner & Gurfinkel, VMCAI'15]
 - [Karbyshev, Bjorner, Itzhaky, R & Shoham, CAV'15]
 - ...
-
- Successfully applied to software & hardware
 - Varied algorithmic details

Our Goal

- Extract essence of PDR
 - Hide algorithmic details
 - Show commonality
 - A unified proof of soundness

Technical Attack

- Abstract Interpretation (AI)
 - Hide algorithmic details
 - Analysis = abstract semantics
 - Over-approximate concrete semantics
 - Sound by construction



- **Our approach:** formulate **PDR** using AI

Main Results

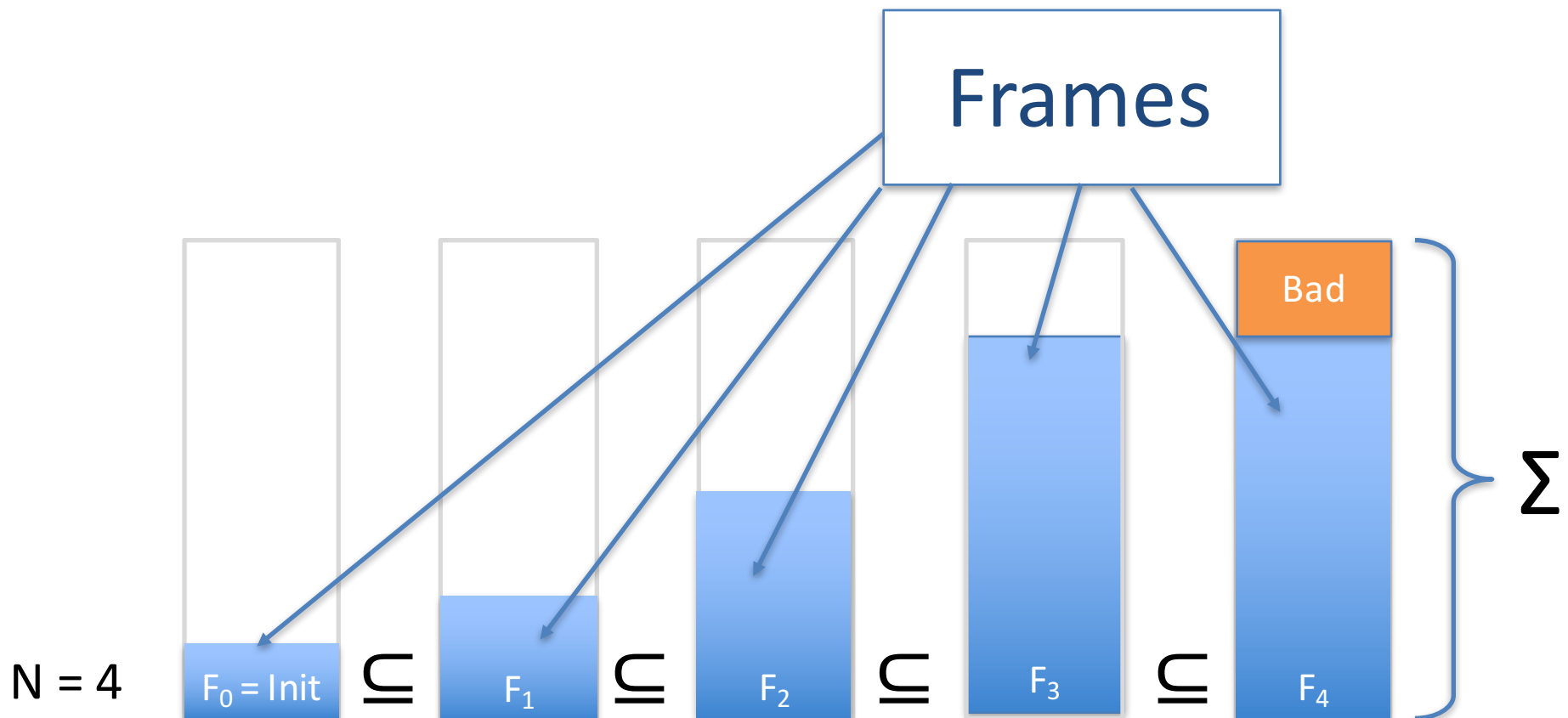
- $\llbracket P \rrbracket_{\wp(\Omega)}^B$: Non-standard operational semantics
 - Can compute any inductive invariant
 - and any counterexample
- PDR algorithms interpret P using $\llbracket P \rrbracket_{\wp(\Omega)}^B$

Plan

- PDR
- $\llbracket P \rrbracket_{\wp(\Omega)}^B$
- PDR as AI using $\llbracket P \rrbracket_{\wp(\Omega)}^B$

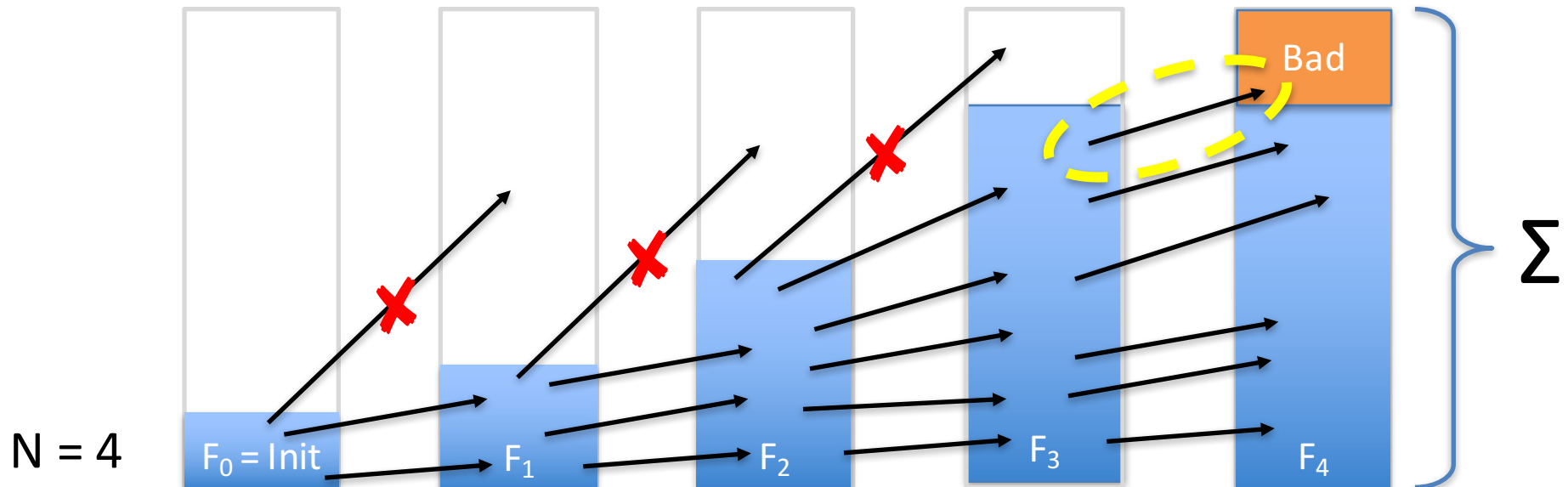
PDR: Intermediate Forward Reachability Sequences

- $\varphi = \langle F_0, \dots, F_N \rangle$



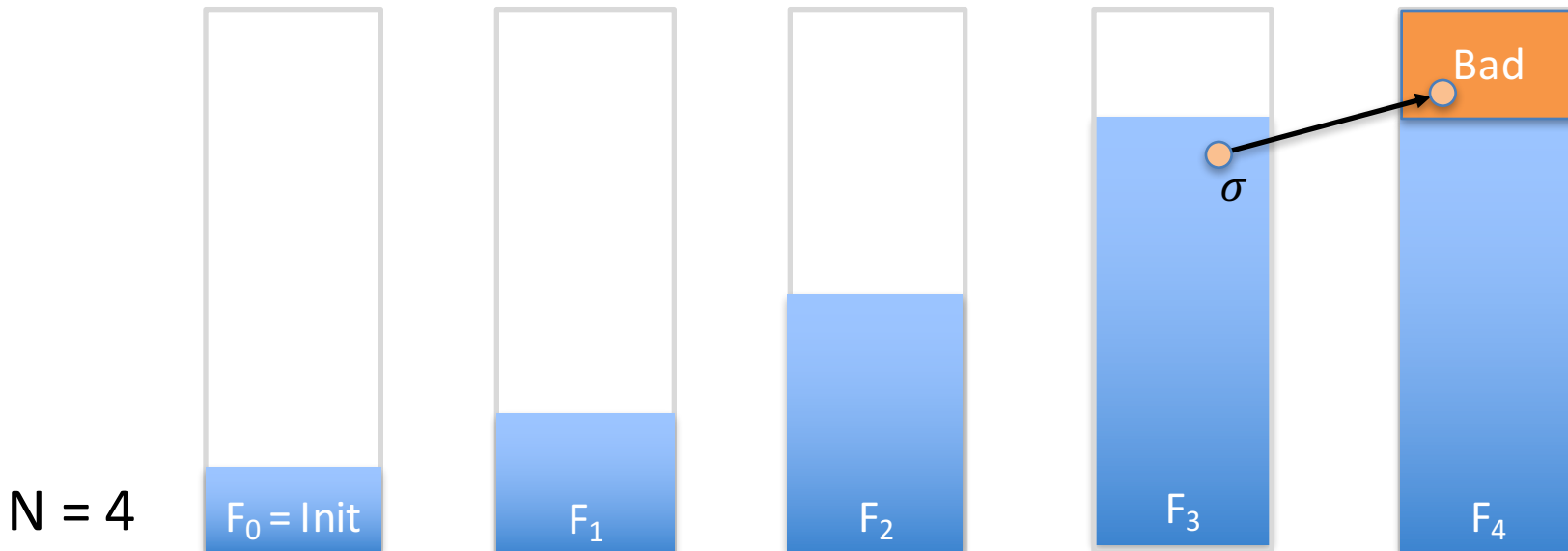
PDR: Intermediate Forward Reachability Sequences

- $\varphi = \langle F_0, \dots, F_N \rangle$
 - $F_i \cap Bad = \emptyset$
 - $F_0 = Init, F_i \subseteq F_{i+1}$
 - $TR(F_i) \subseteq F_{i+1}$ ($i + 1 < N$)



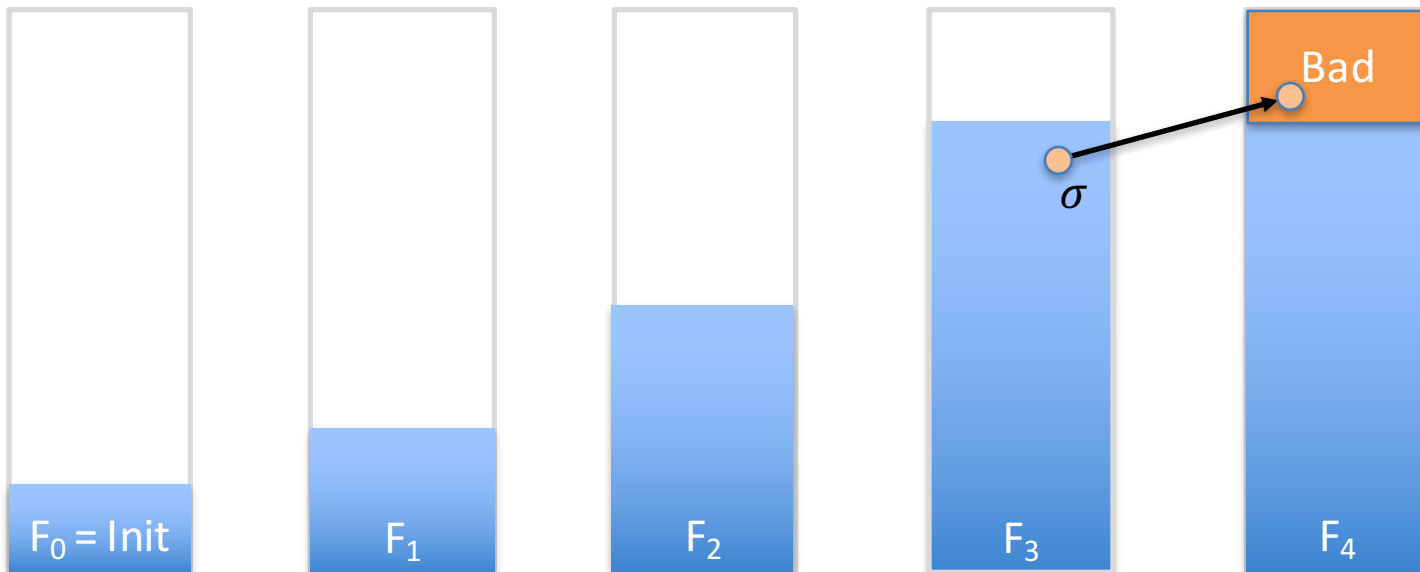
PDR: Obligation Queue

- $\varphi = \langle F_0, \dots, F_N \rangle$
 - $F_i \cap Bad = \emptyset$
 - $F_0 = Init, F_i \subseteq F_{i+1}$
 - $TR(F_i) \subseteq F_{i+1}$ ($i + 1 < N$)
- $Q = [\quad]$



PDR: Queue Initialization

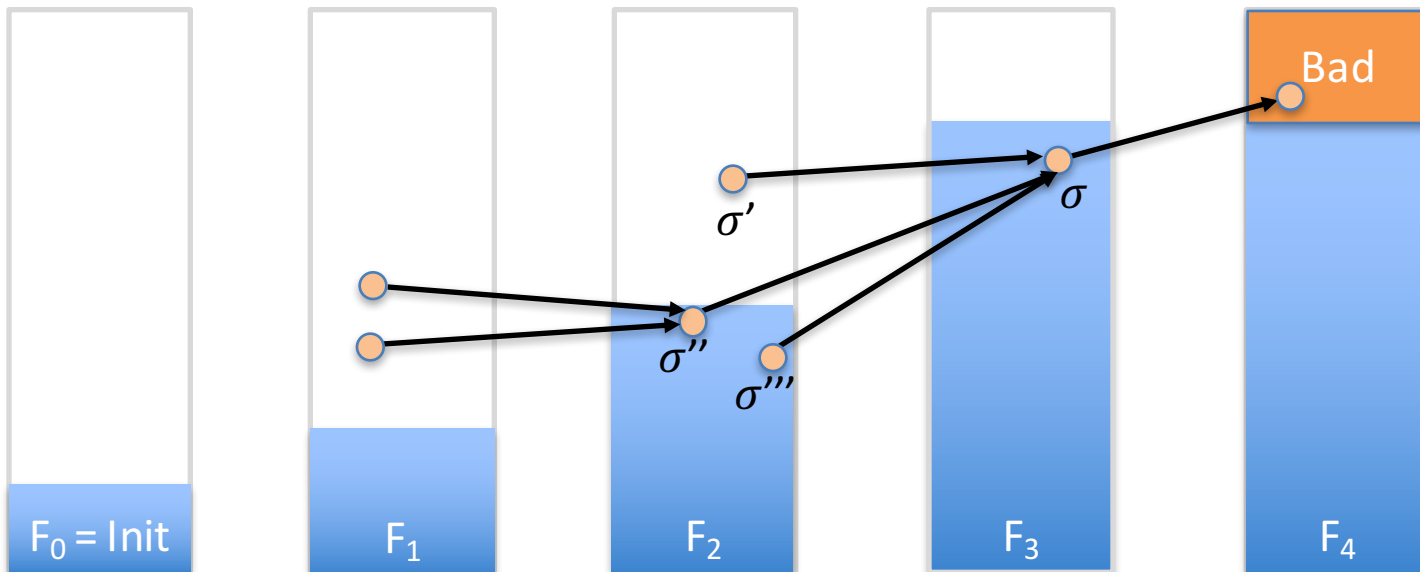
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PDR: Backward Step

- $\varphi = \langle F_0, \dots, F_N \rangle$
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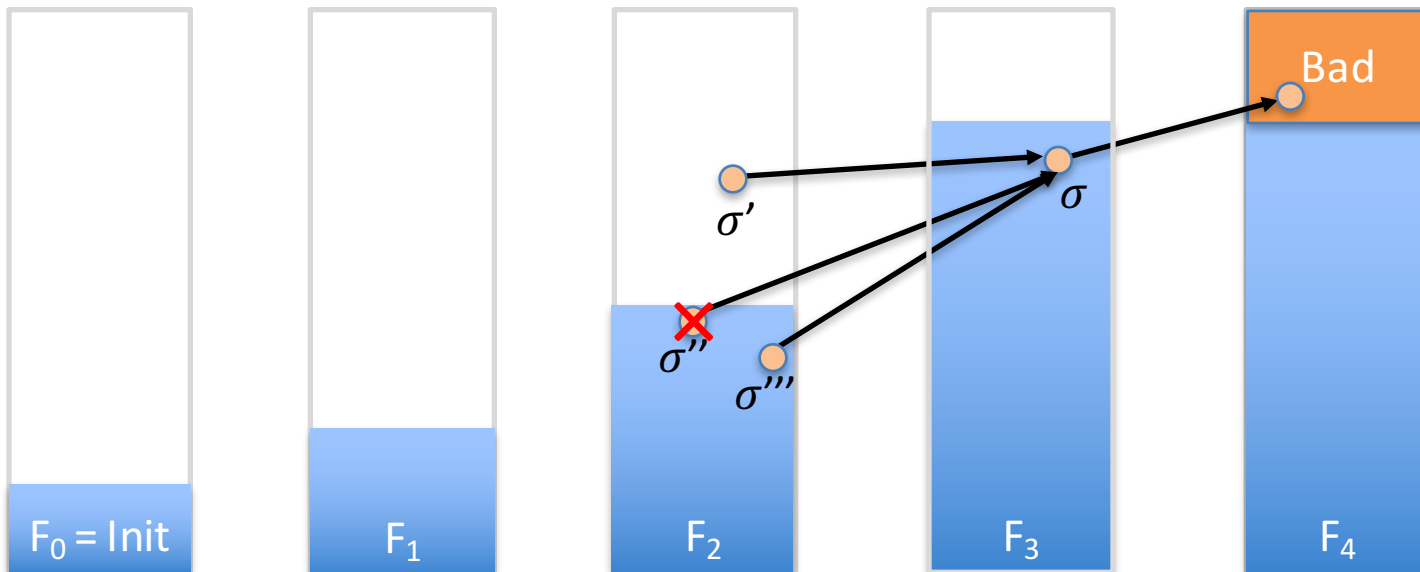


$N = 4$

PDR: Blocking

- $\varphi = \langle F_0, \dots, F_N \rangle$
 - $F_i \cap \text{Bad} = \emptyset$
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 - $\text{TR}(F_i) \subseteq F_{i+1}$ ($i + 1 < N$)

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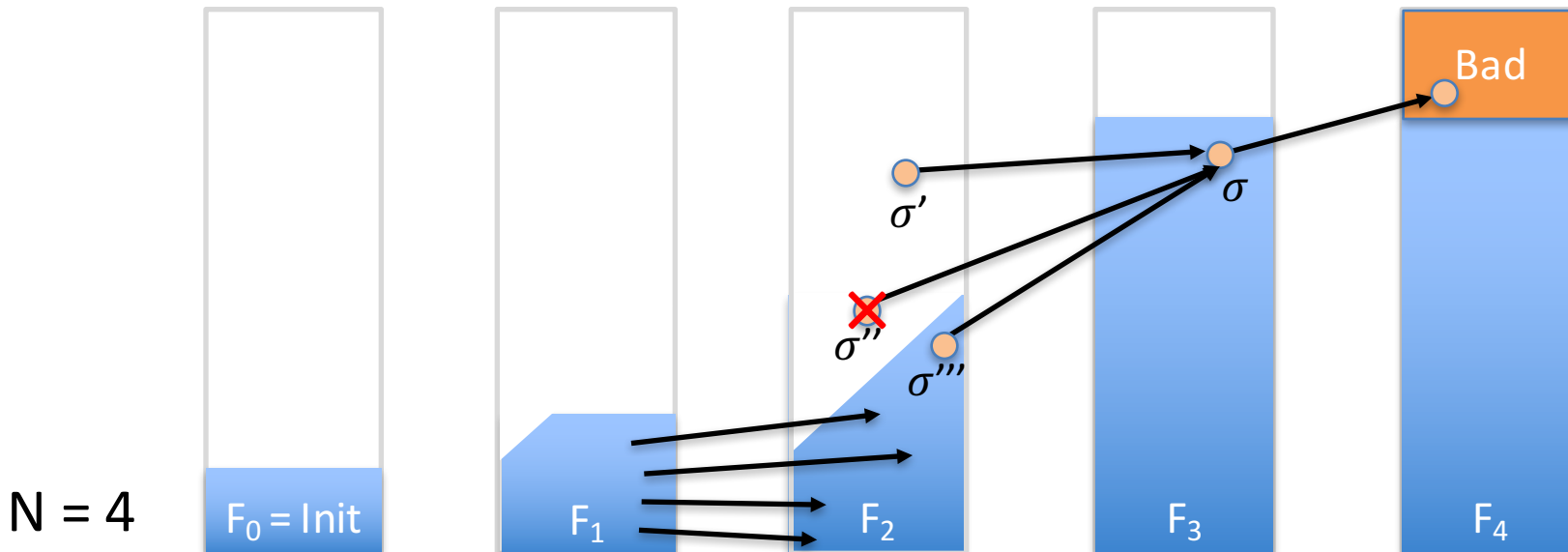


PDR: Generalization

- $\varphi = \langle F_0, \dots, F_N \rangle$
 - $F_i \cap Bad = \emptyset$
 - $F_0 = Init, F_i \subseteq F_{i+1}$
 - $TR(F_i) \subseteq F_{i+1} \quad (i + 1 < N)$

$S = Gen(F_{i-1}, \sigma):$
 $S \cap Init = \emptyset$
 $S \cap TR(F_{i-1}) = \emptyset$

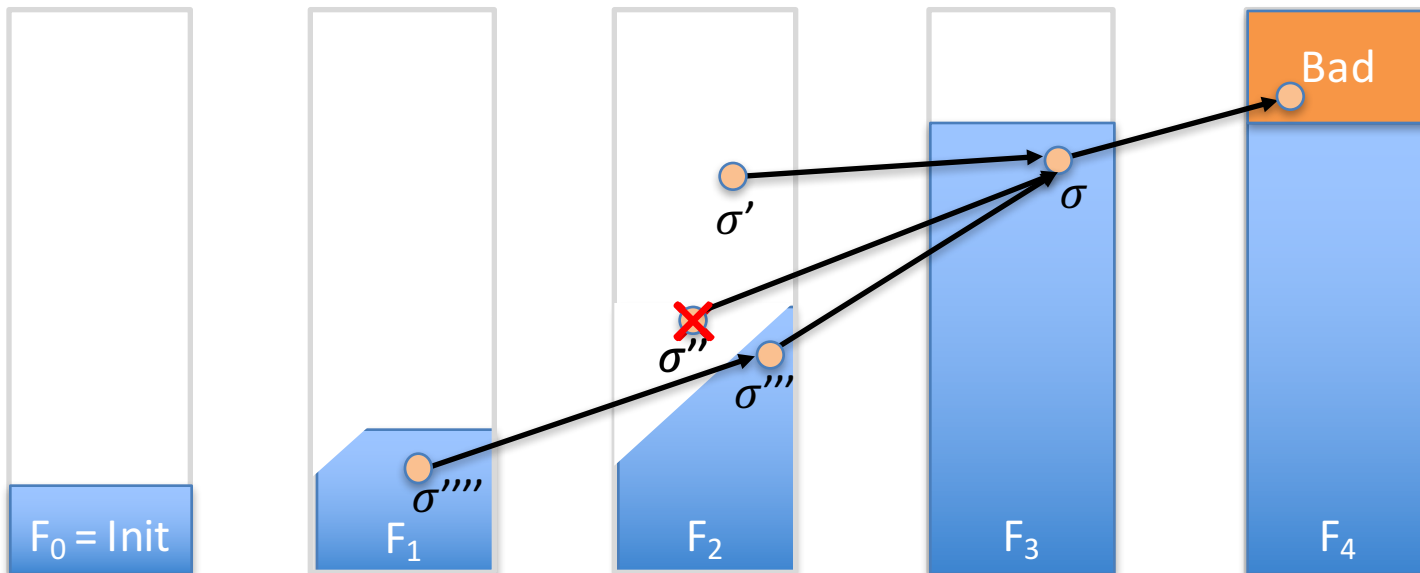
- $Q = [\quad \quad \quad (\sigma, 3)]$



PDR: Backward Step

- $\varphi = \langle F_0, \dots, F_N \rangle$
 - $F_i \cap \text{Bad} = \emptyset$
 - $F_0 = \text{Init}, F_i \subseteq F_{i+1}$
 - $\text{TR}(F_i) \subseteq F_{i+1}$ ($i + 1 < N$)

- $Q = [\quad (\sigma''''',1) \quad \quad (\sigma,3) \quad]$

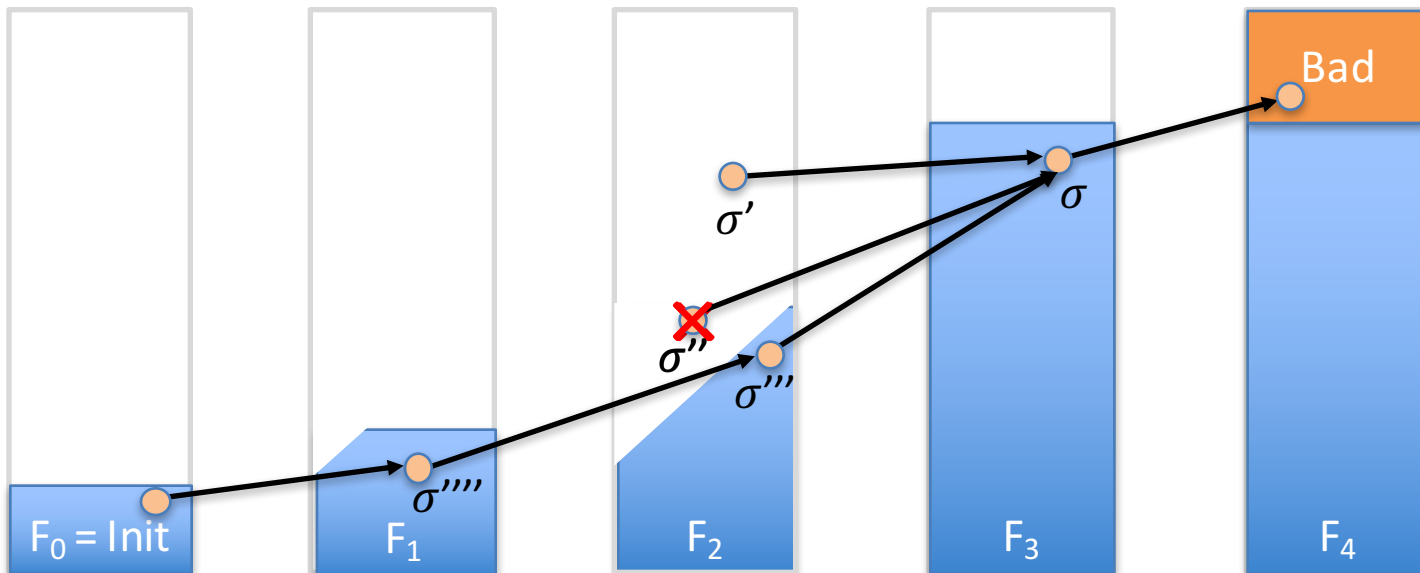


N = 4

PDR: Counterexample

- $\varphi = \langle F_0, \dots, F_N \rangle$
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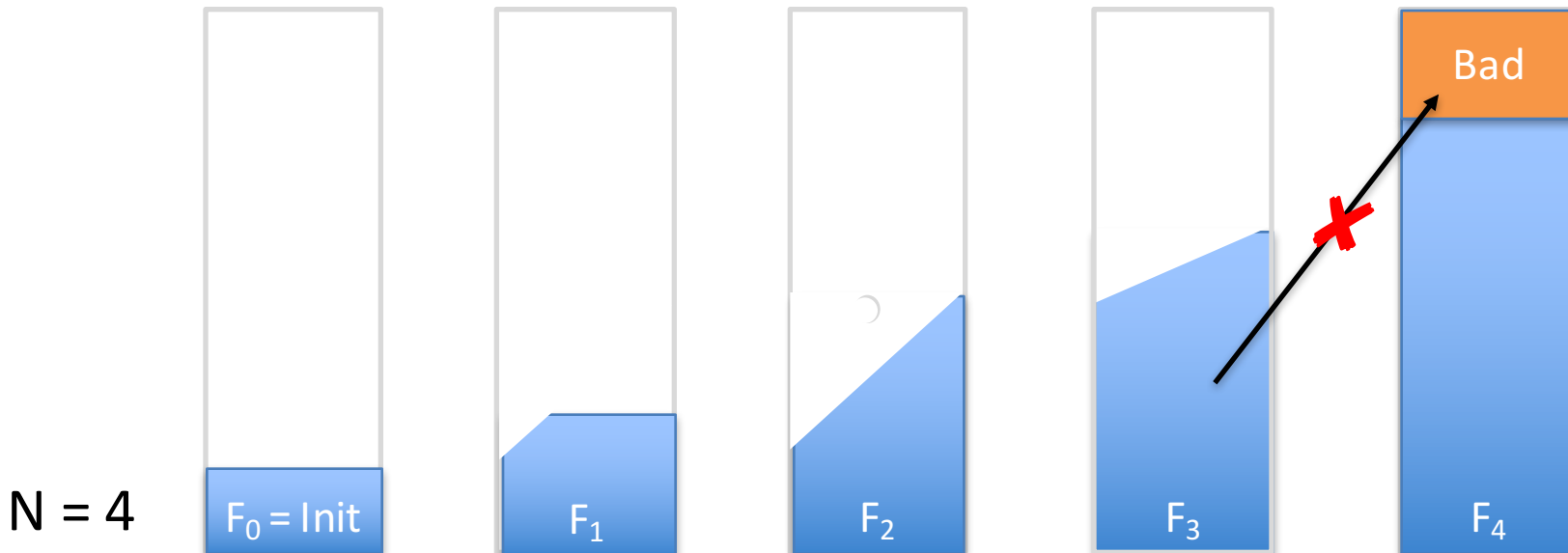
- $Q = [\quad (\sigma''',1) \quad (\sigma''',2) \quad (\sigma,3) \quad]$



PDR: Forward Reachability Sequence

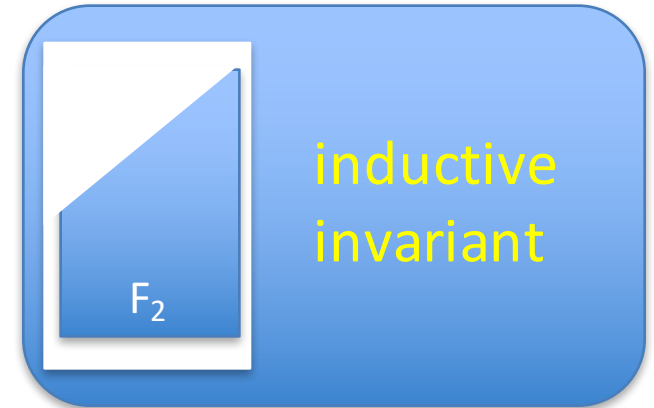
- $\varphi = \langle F_0, \dots, F_N \rangle$
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- $Q = [\quad]$

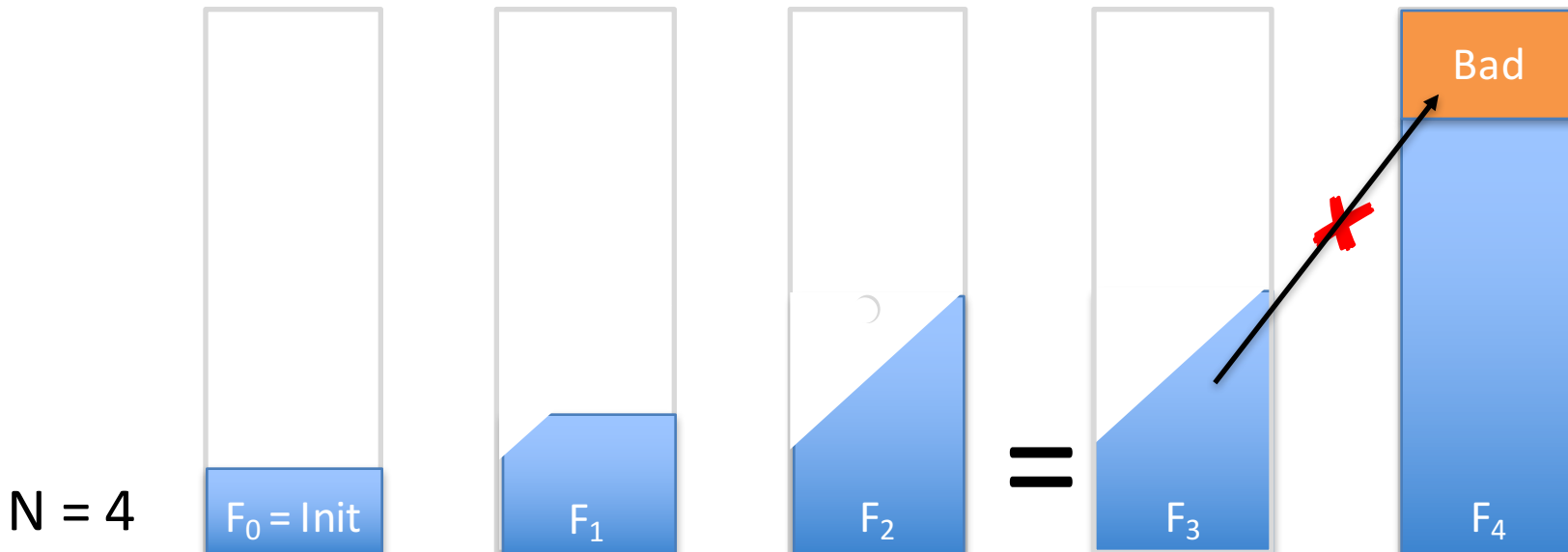


PDR: Fixpoint

- $\varphi = \langle F_0, \dots, F_N \rangle$
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 - $\text{TR}(F_i) \subseteq F_{i+1}$



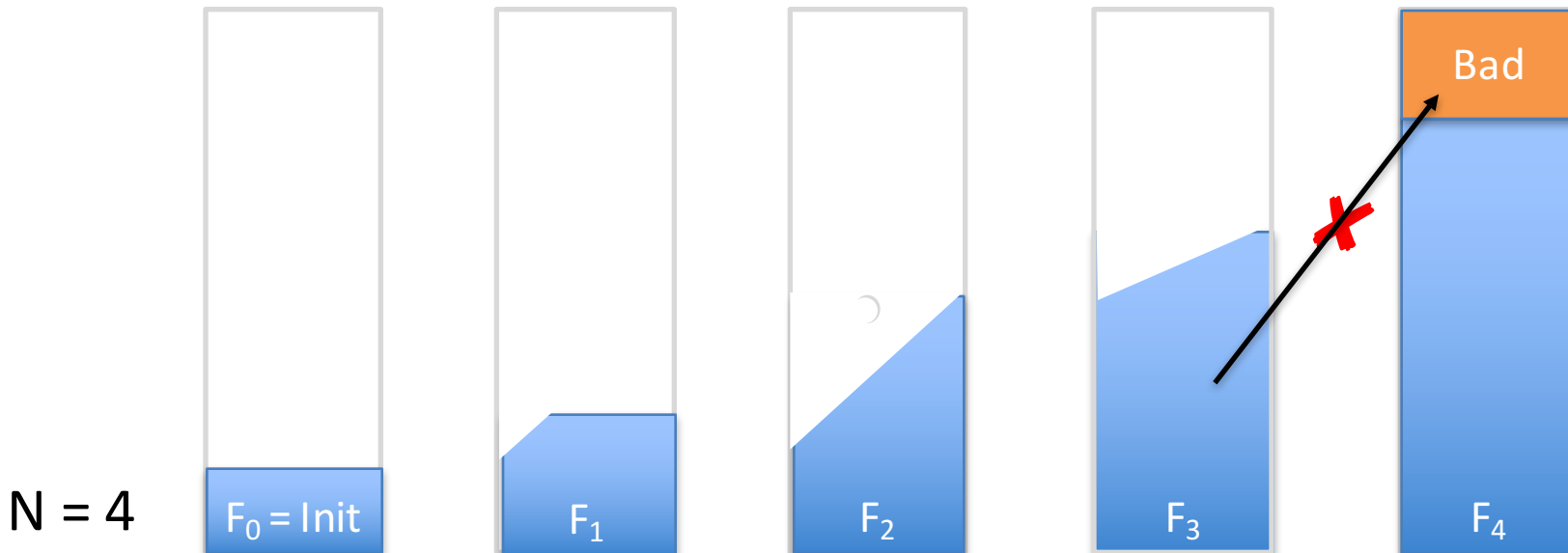
- $Q = [\quad]$



PDR: Unfolding

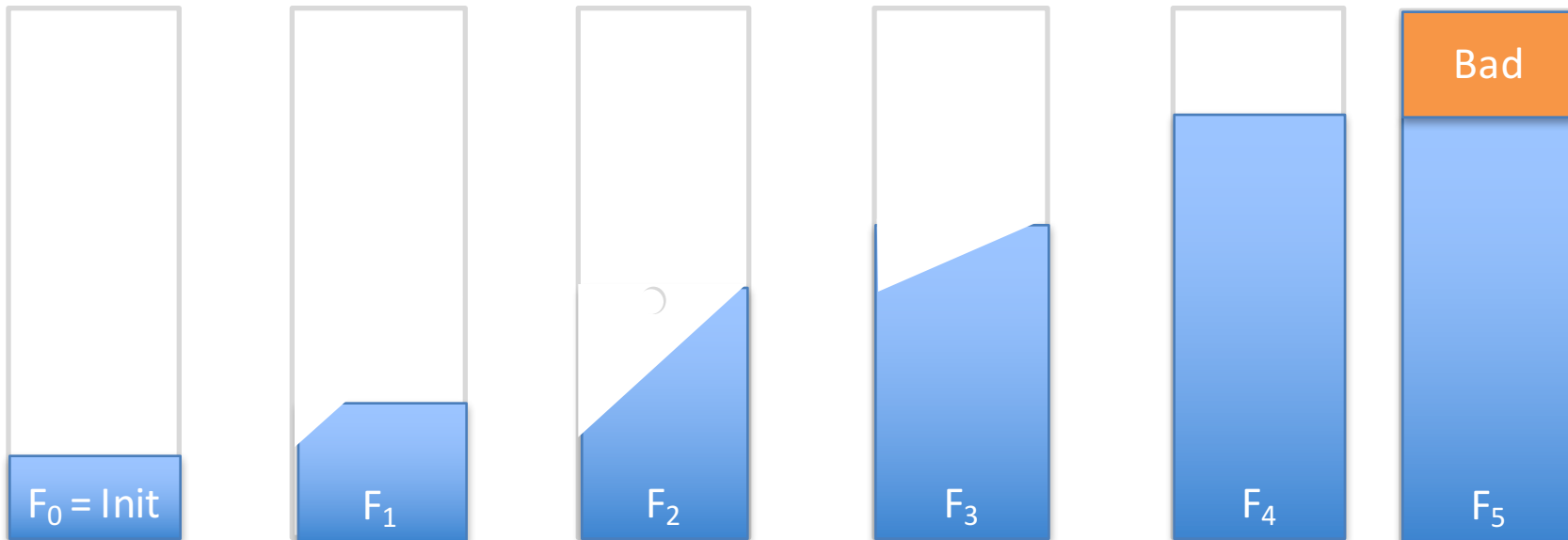
- $\varphi = \langle F_0, \dots, F_N \rangle$
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PDR: Unfolding

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- $Q = [$



PDR Operations

- ✓ Unfolding
- ✓ Queue initialization
- ✓ Backward step
- ✓ Blocking
- ✓ Generalization
- ✓ Termination: Counterexample / Invariant
 - Obligation lifting
 - Inductive generalization
 - Forward propagation
 - Pushing obligation forward

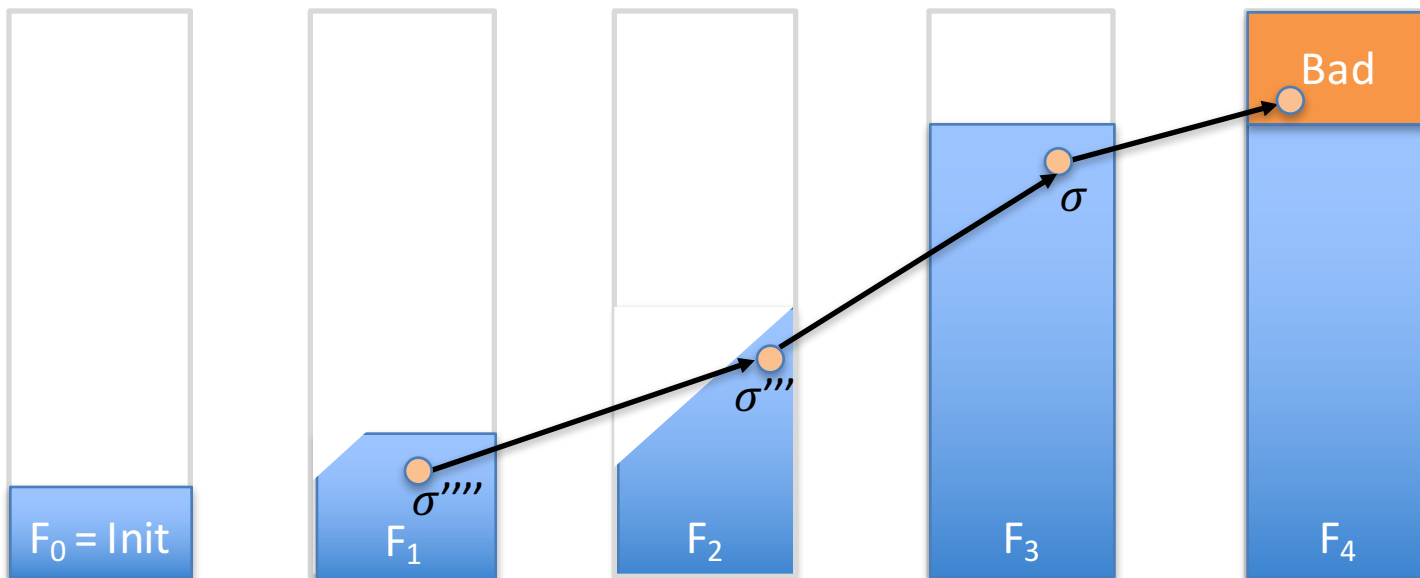
PDR & Abstract Interpretation

- AI & PDR compute inductive invariants
 - AI: Systematic
 - PDR: Specialized
- How can we formulate PDR using AI?
 - Abstractions
 - Transformers

Where to start?

- What concrete semantics does PDR abstract?

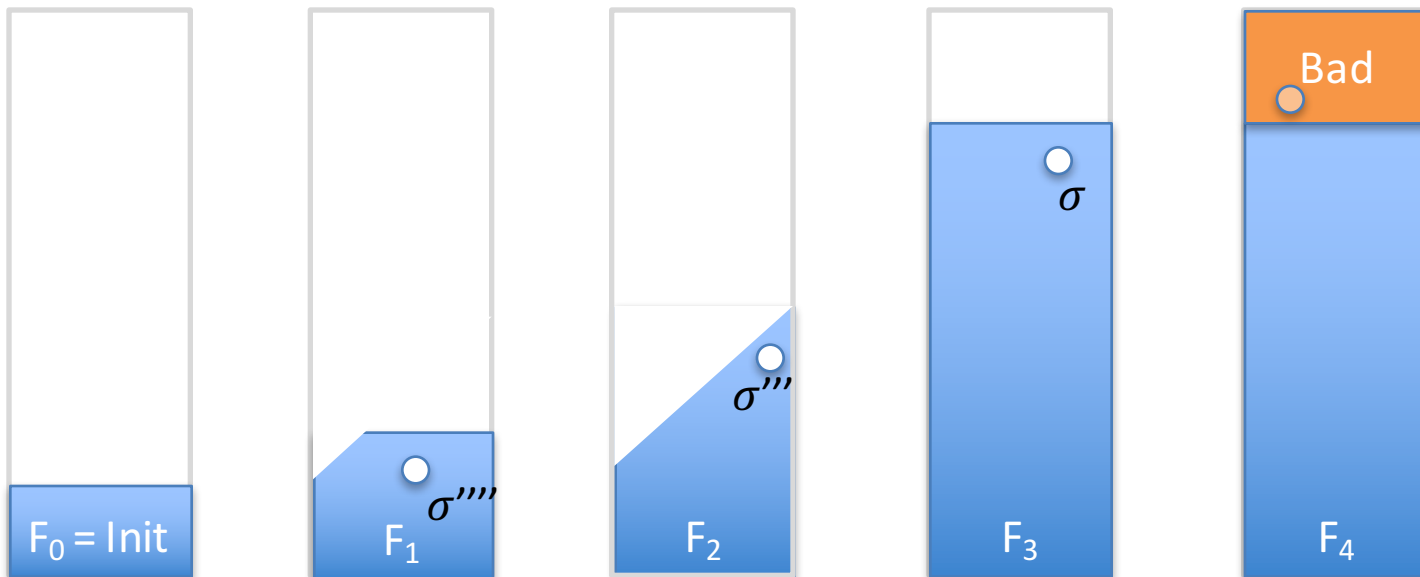
- $Q = [\quad (\sigma''''',1) \quad (\sigma''',2) \quad (\sigma,3)]$



Where to start?

- What concrete semantics does PDR abstracts?

- $Q = [\quad]$



Collecting (Backward) Trace Semantics

- Verification problem: $(Init, P, Bad)$
- $\llbracket P \rrbracket_{\emptyset}^B(\Sigma^*) = \text{evil traces} \subseteq \Sigma^*$
 $= \left\{ \pi \in \Sigma^* \mid \pi_0 \in Bad \wedge \forall i. \pi_i \xrightarrow{\text{TR}^{-1}} \pi_{i+1} \right\}$

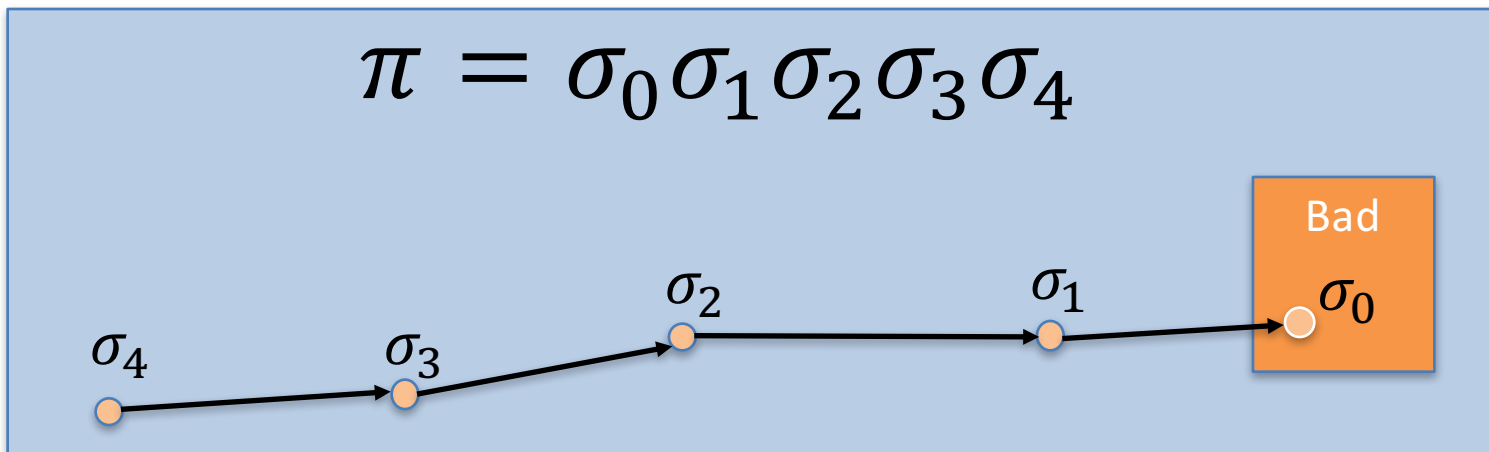
Collecting (Backward) Trace Semantics

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$$\pi = \sigma_0 \sigma_1 \sigma_2 \sigma_3 \sigma_4$$

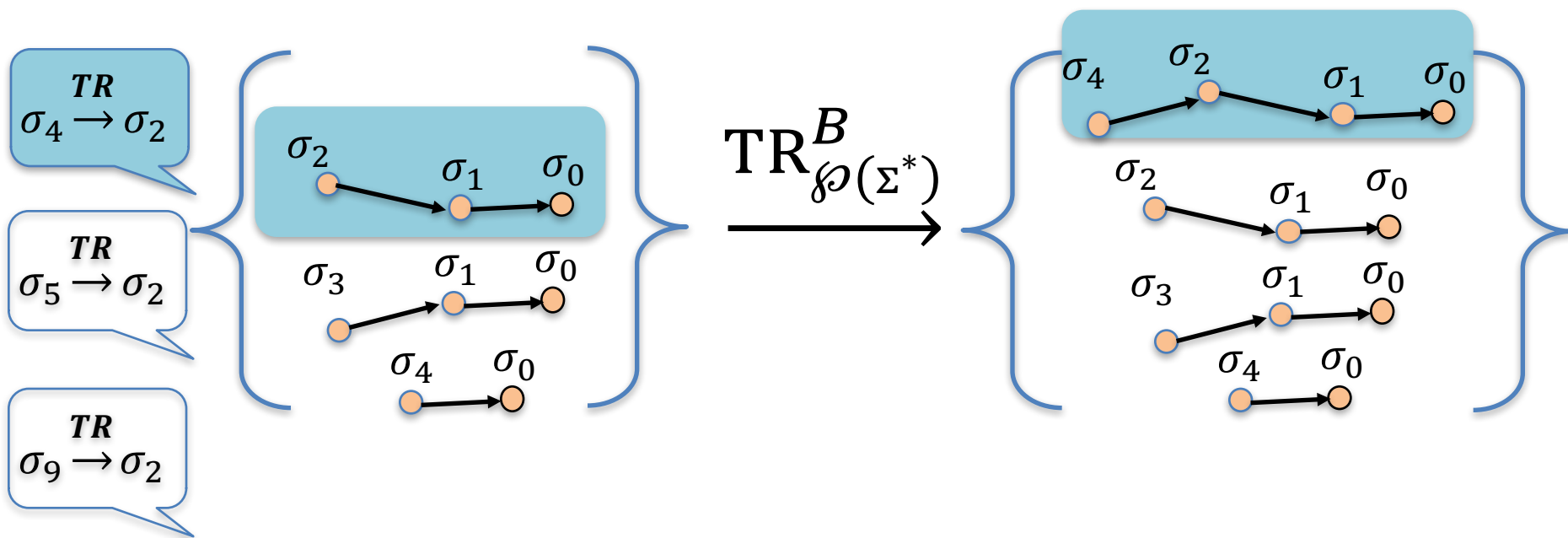
Collecting (Backward) Trace Semantics

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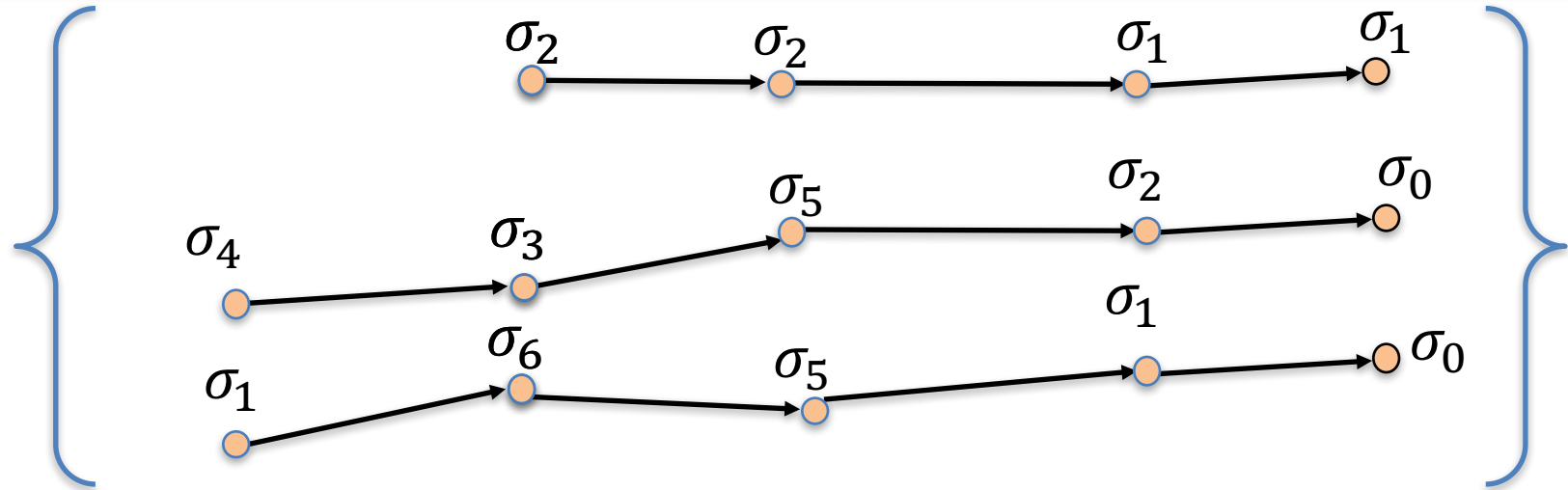


Collecting (Backward) Transitions

- Verification problem: $(Init, P, Bad)$
- $TR_{\wp(\Sigma^*)}^B \subseteq \wp(\Sigma^*) \times \wp(\Sigma^*)$

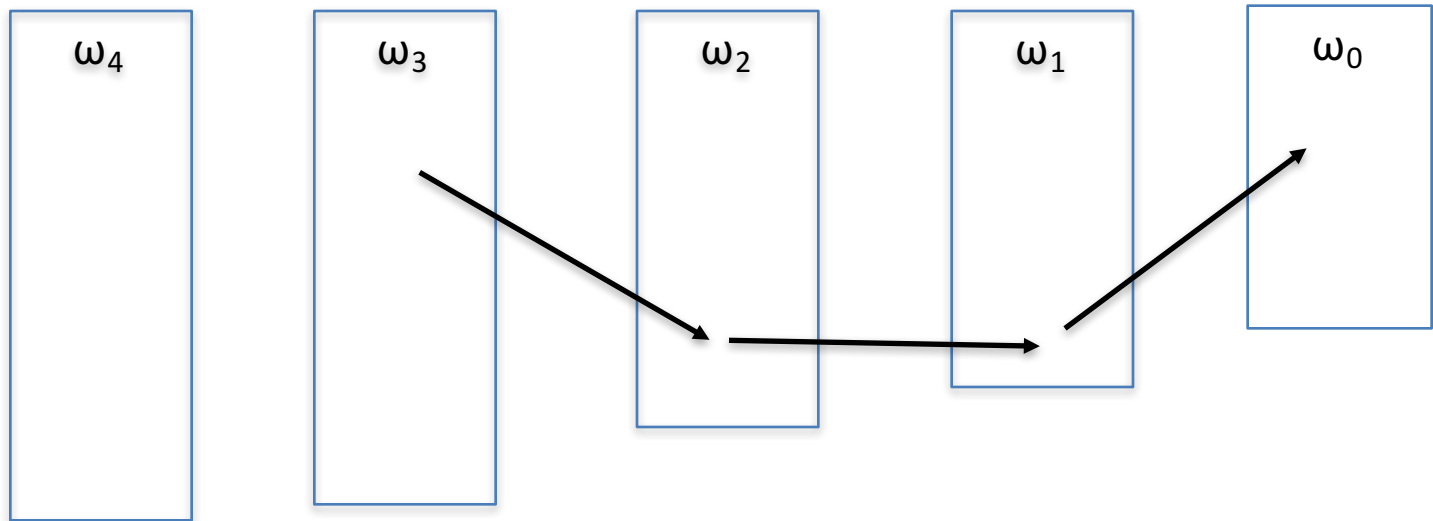
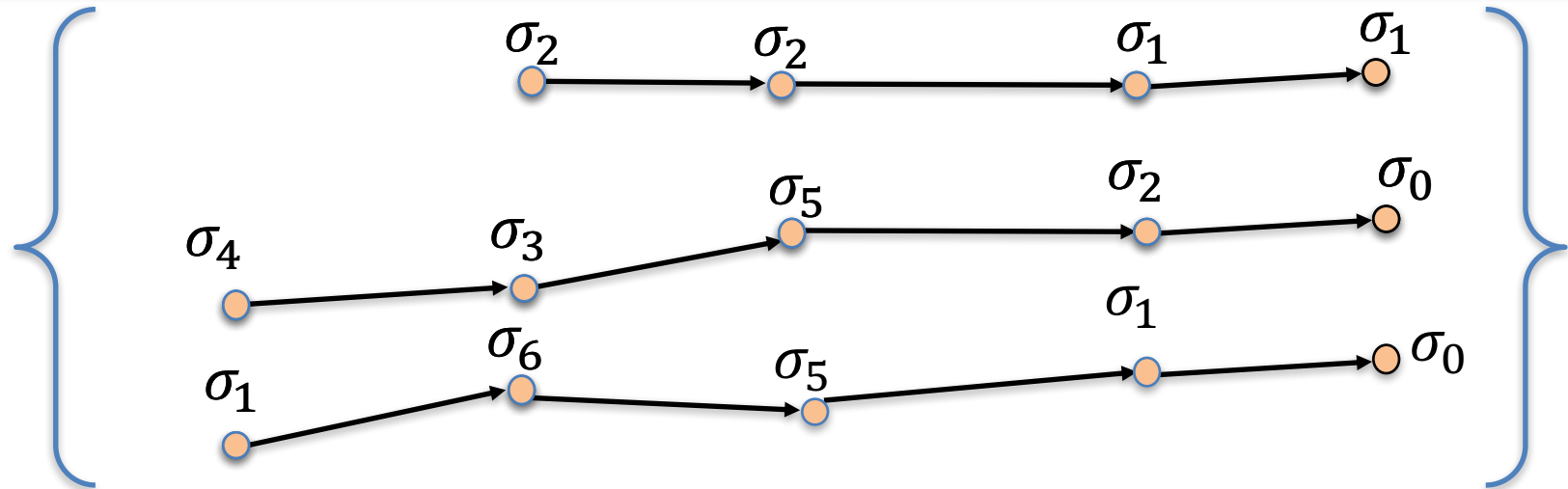


How to abstract?



What would PDR do?

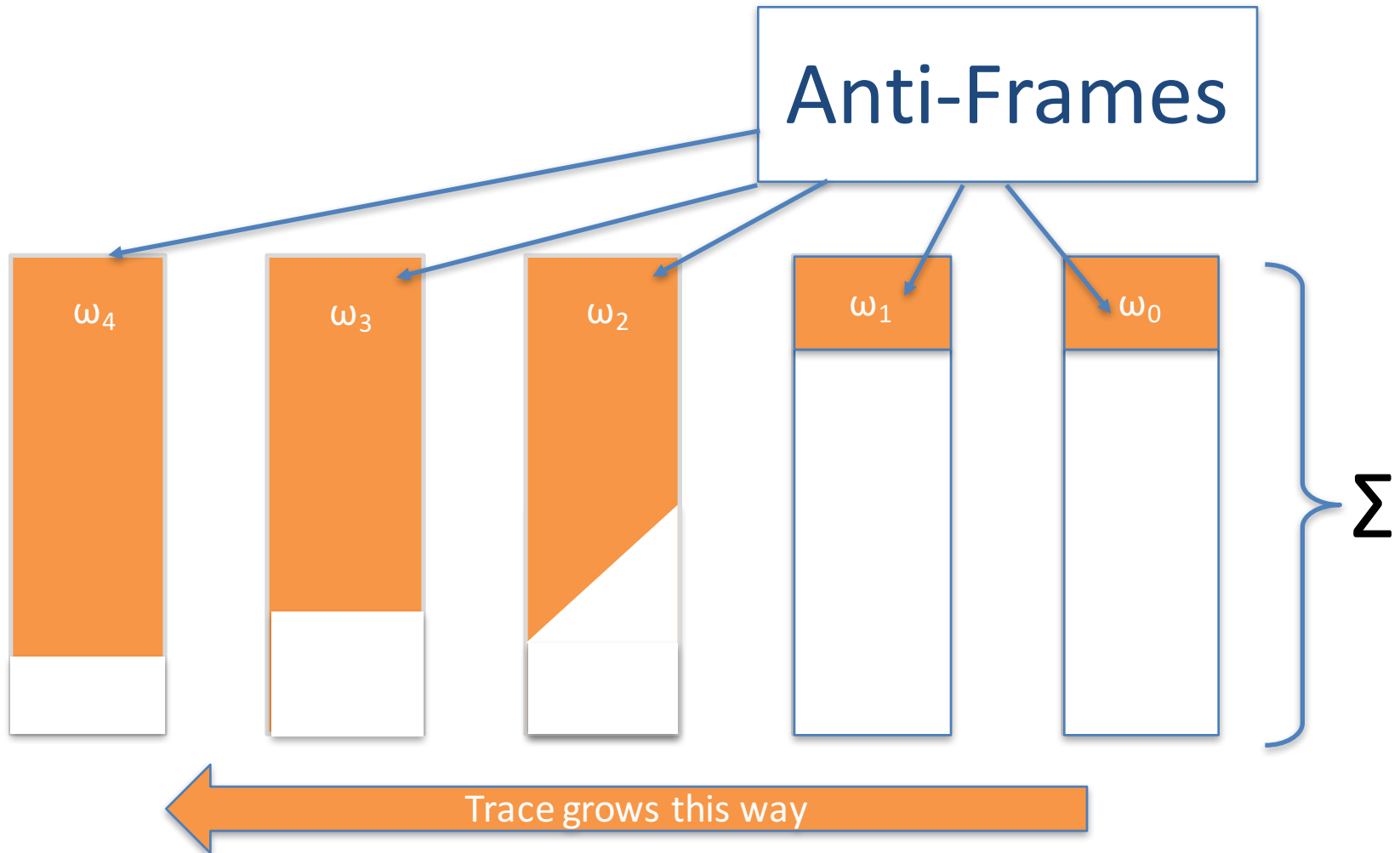
1. Cartesian Abstraction



$$\omega = \omega_0 \omega_1 \omega_2 \omega_3 \omega_4 \in \Omega = \mathcal{P}(\Sigma)^*$$

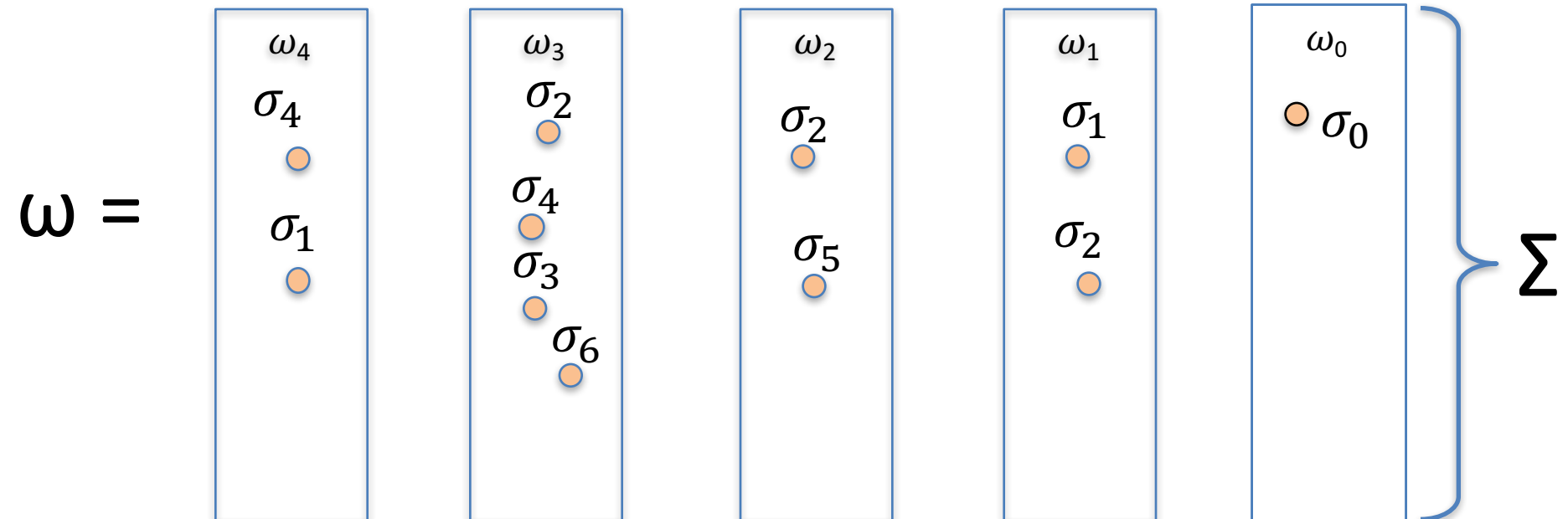
Cartesian Traces

- $\omega = \omega_0\omega_1\omega_2\omega_3\omega_4 \in \Omega = \mathcal{P}(\Sigma)^*$



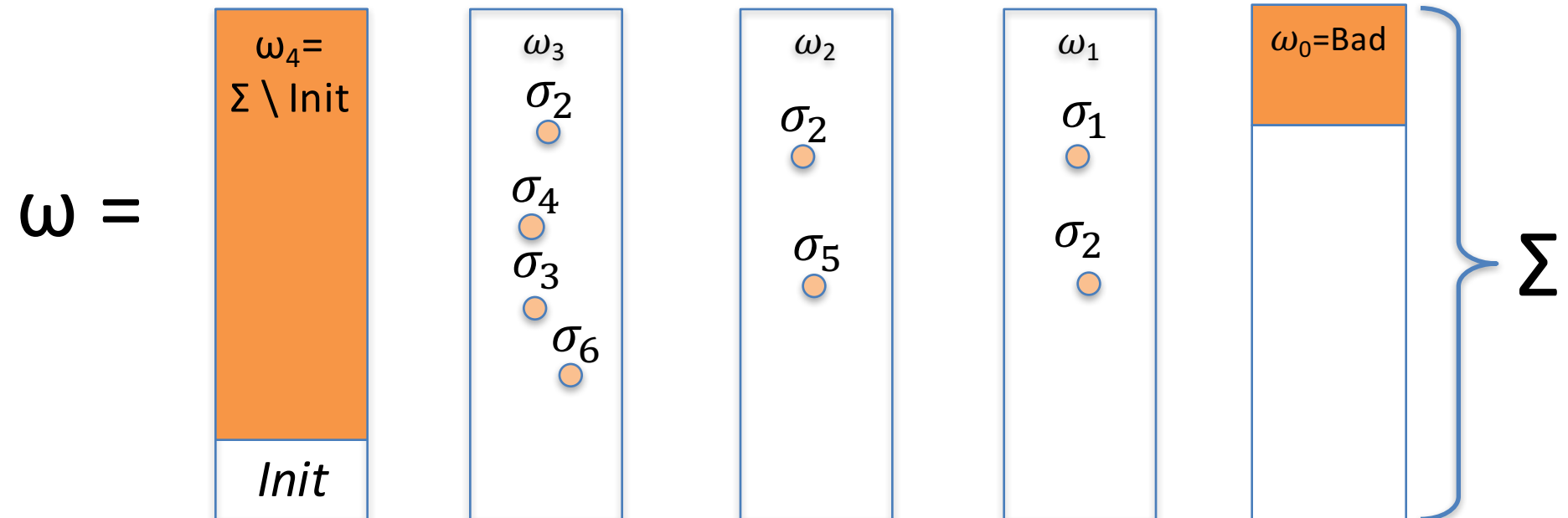
2. Init-Sensitive Abstraction

- Cartesian abstraction allows to capture only states occurring in evil traces



2. Init-Sensitive Abstraction

- $\omega = \text{Bad} \text{ } \Sigma \setminus \text{Init}$



3. Bound-Sensitive Abstraction

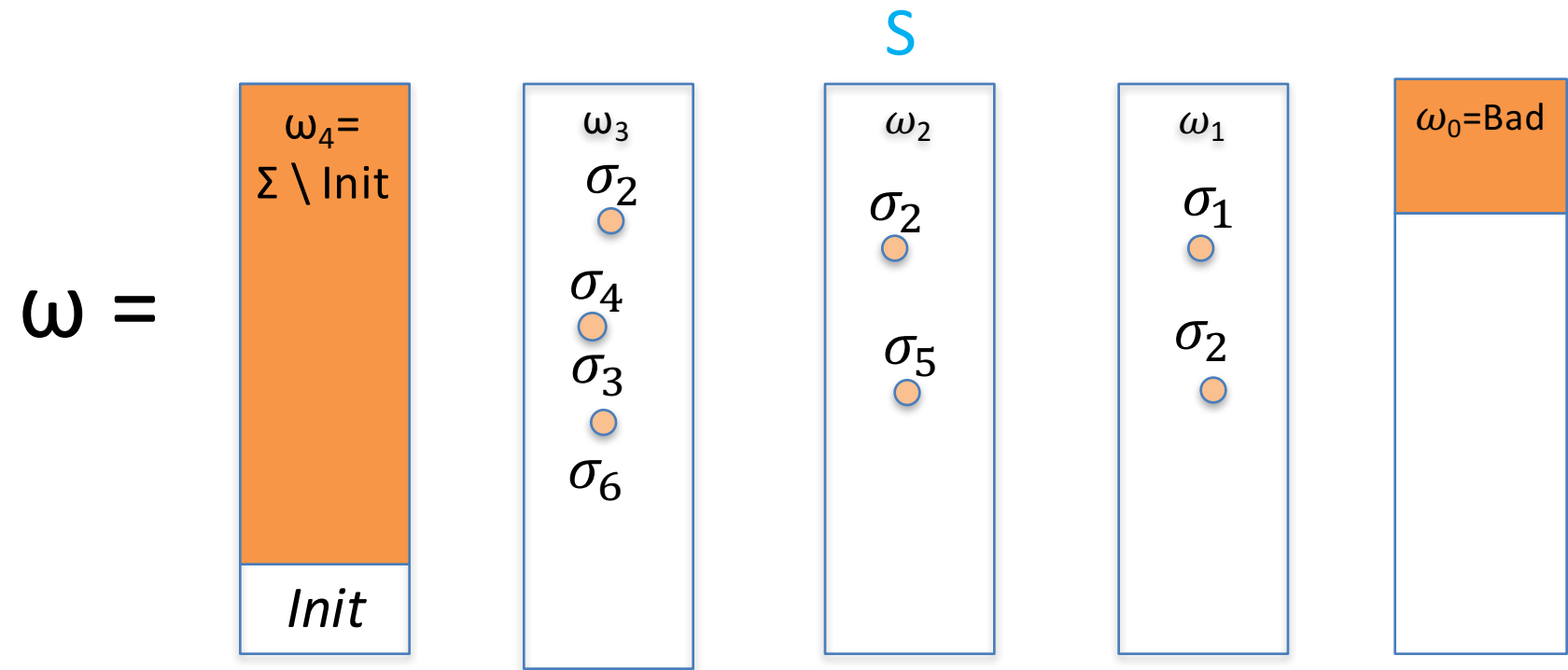
- PDR refines the abstraction as the bound grows
- The semantics maintain a set of cartesian traces
- $\llbracket P \rrbracket_{\wp(\Omega)}^B \in \wp(\Omega)$

What about Transformers?

Backward Transitions

- $TR_{\Omega}^B \subseteq \Omega \times \Omega$

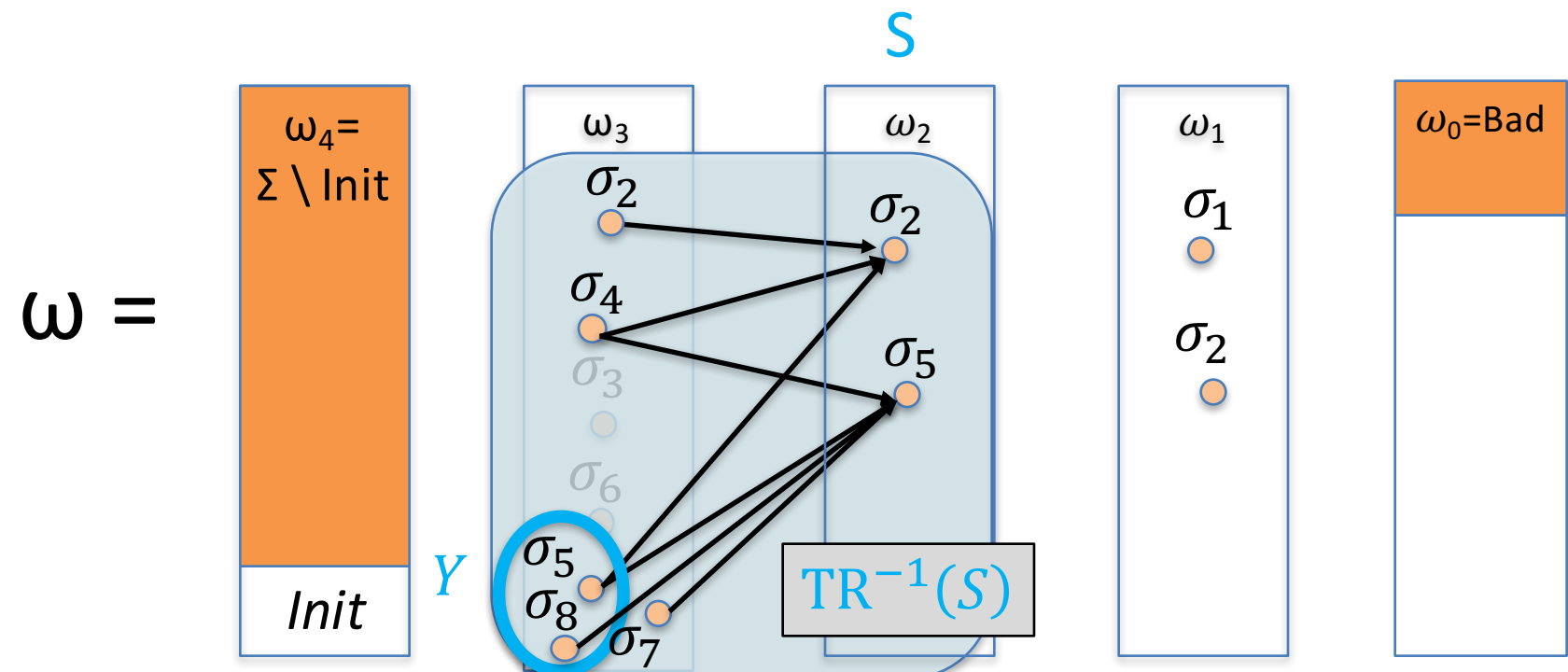
- $\omega \xrightarrow{TR_{\Omega}^B} \omega'$



Backward Transitions

- $TR_{\Omega}^B \subseteq \Omega \times \Omega$

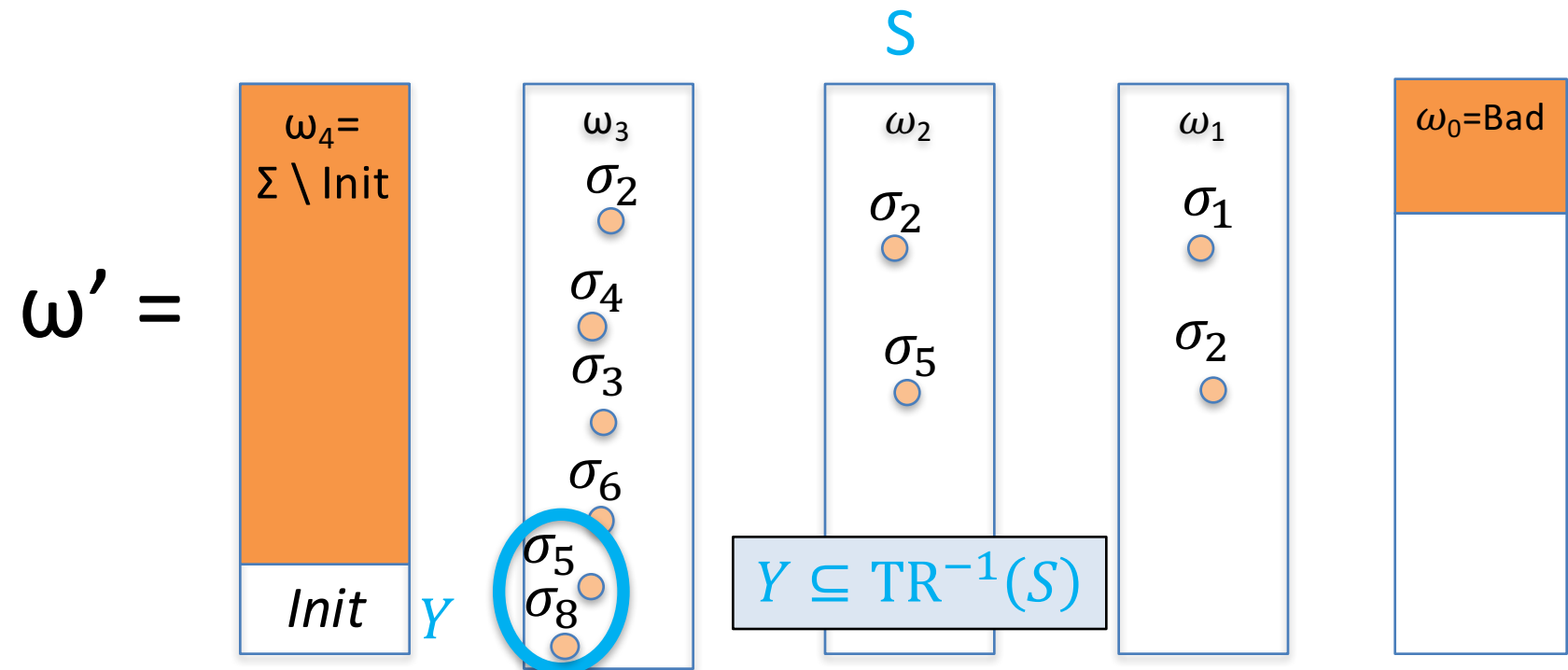
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Backward Transitions

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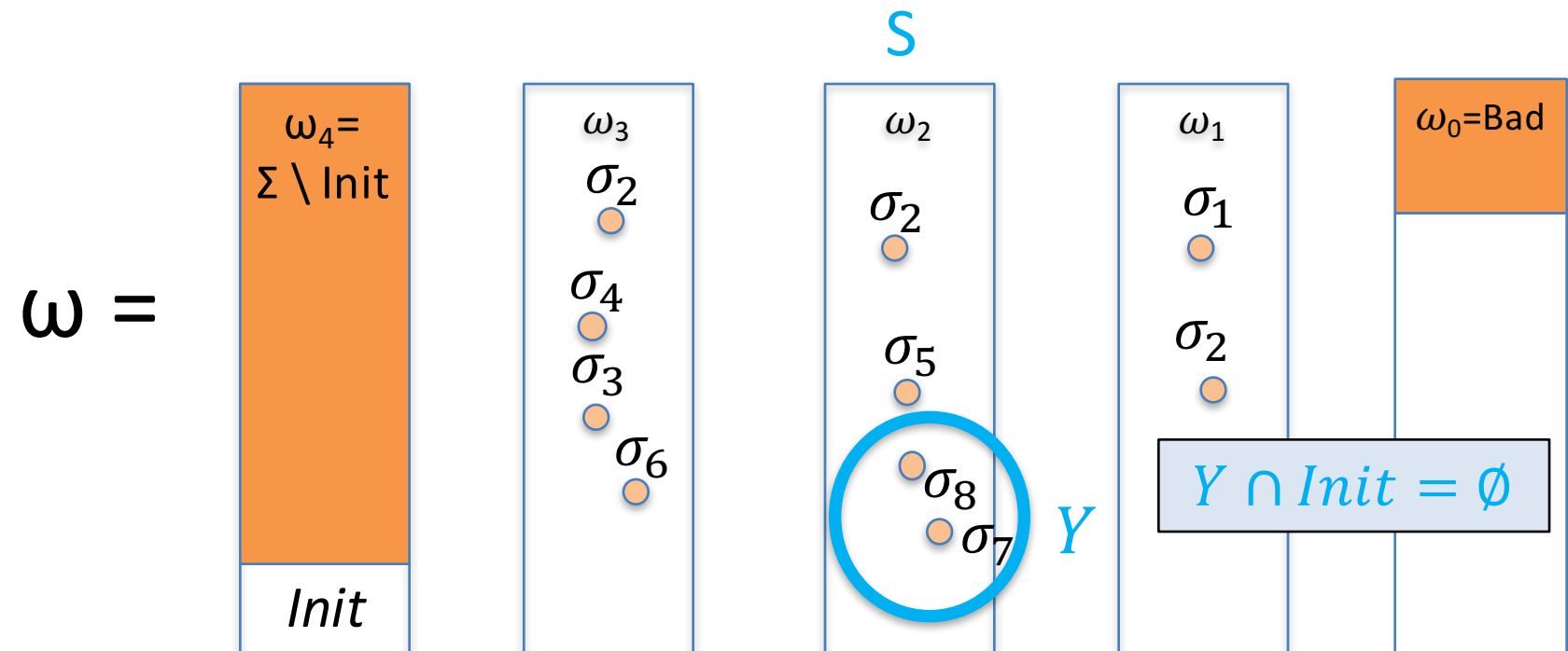
- $\omega \xrightarrow{TR_{\Omega}^B} \omega'$



Generalization Transitions

- $TR_{\Omega}^{Gen} \subseteq \Omega \times \Omega$

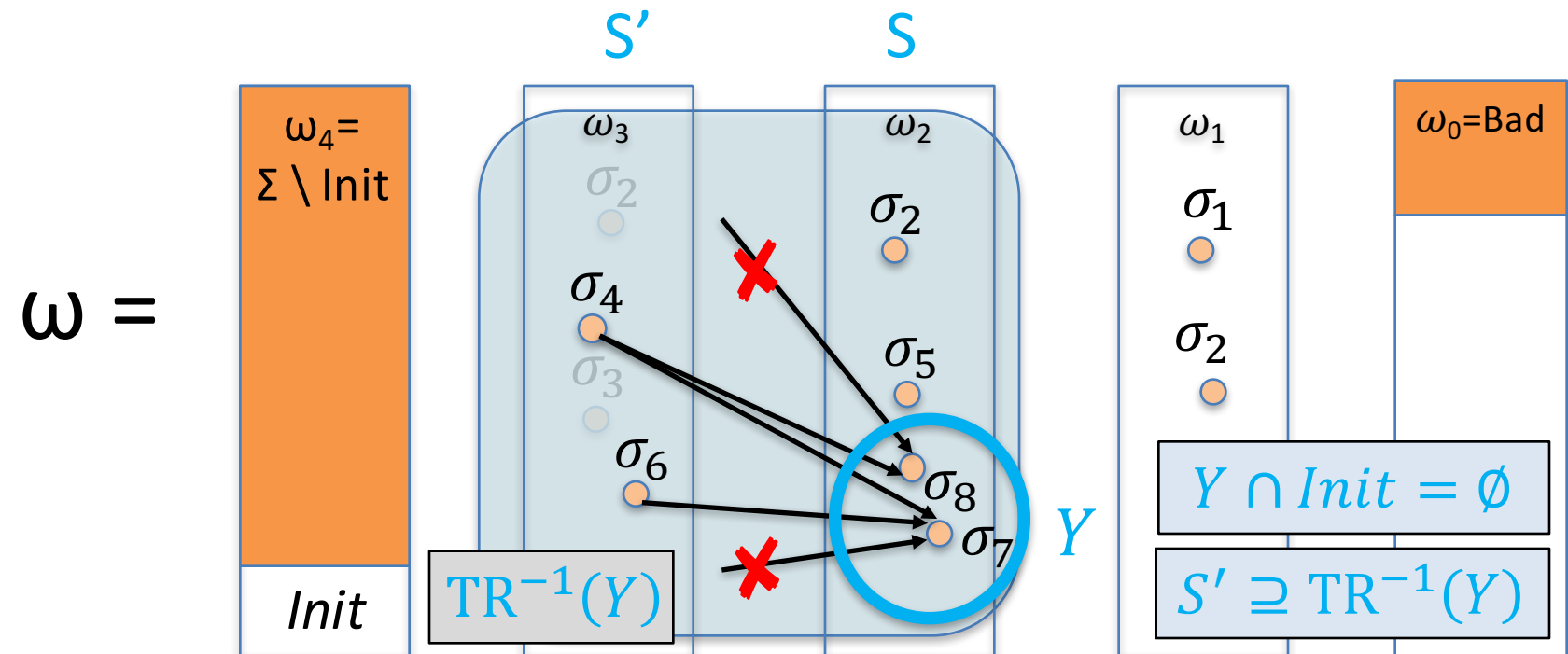
- $\omega \xrightarrow{TR_{\Omega}^{Gen}} \omega'$



Generalization Transitions

- $TR_{\Omega}^{Gen} \subseteq \Omega \times \Omega$

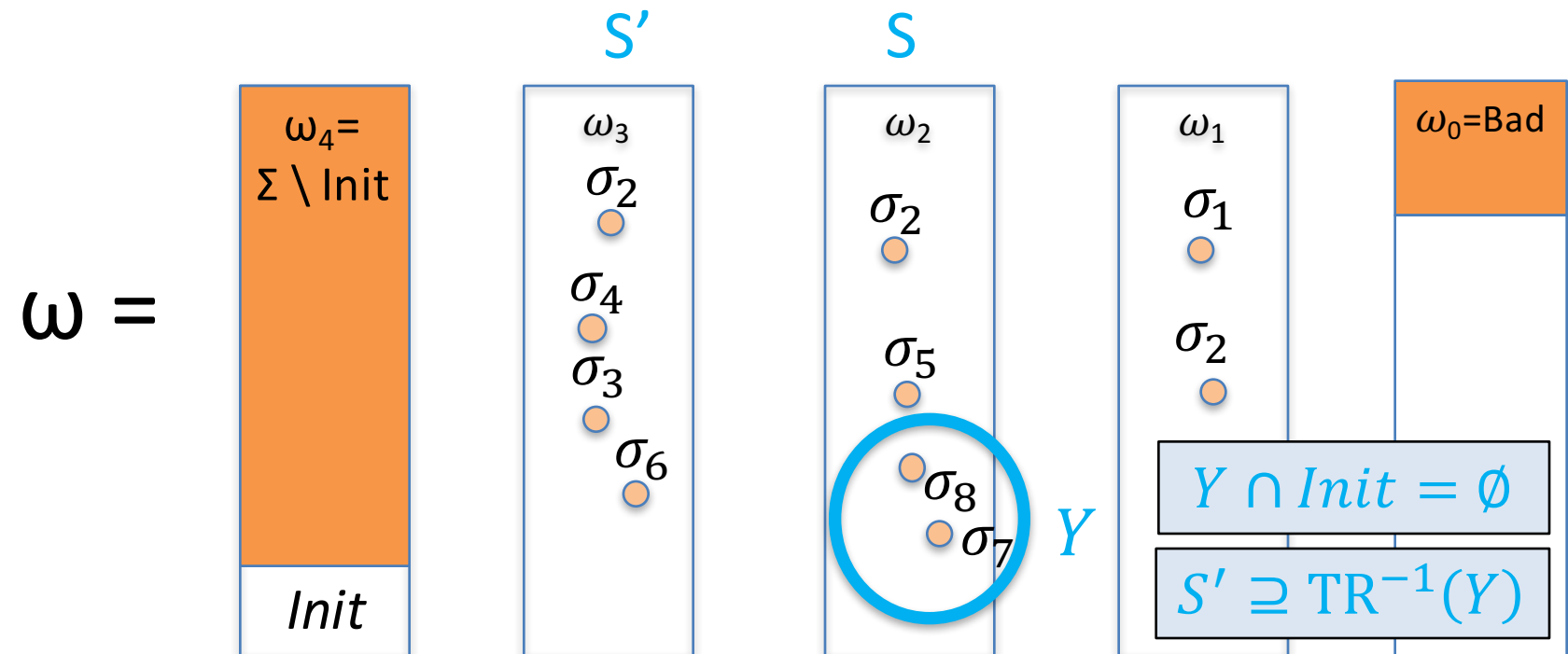
- $\omega \xrightarrow{TR_{\Omega}^{Gen}} \omega'$



Generalization Transitions

- $TR_{\Omega}^{Gen} \subseteq \Omega \times \Omega$

- $\omega \xrightarrow{TR_{\Omega}^{Gen}} \omega'$



Small step collecting property-guided cartesian trace semantics

- $\llbracket P \rrbracket_{\wp(\Omega)}^B \in \wp(\Omega)$

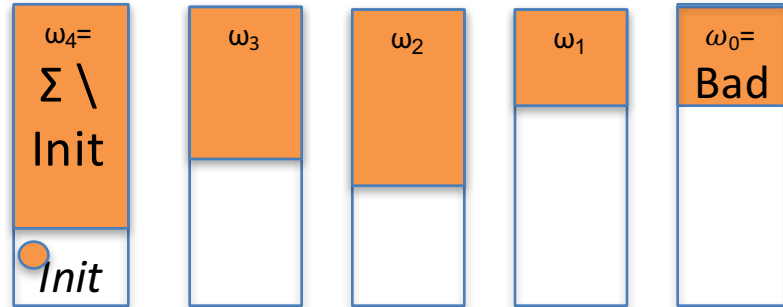
- $\hat{\Omega} = \{ \omega = \text{Bad } \emptyset \dots \emptyset (\Sigma \setminus \text{Init}) \mid 2 \leq |\omega| \}$

$$= \left\{ \begin{array}{|c|} \hline \Sigma \setminus \\ \text{Init} \\ \hline \text{Init} \\ \hline \end{array} \begin{array}{|c|} \hline \text{Bad} \\ \hline \\ \hline \end{array}, \begin{array}{|c|} \hline \Sigma \setminus \\ \text{Init} \\ \hline \text{Init} \\ \hline \end{array} \begin{array}{|c|} \hline \\ \hline \\ \hline \end{array} \begin{array}{|c|} \hline \text{Bad} \\ \hline \\ \hline \end{array}, \begin{array}{|c|} \hline \Sigma \setminus \\ \text{Init} \\ \hline \text{Init} \\ \hline \end{array} \begin{array}{|c|} \hline \\ \hline \\ \hline \end{array} \begin{array}{|c|} \hline \\ \hline \\ \hline \end{array} \begin{array}{|c|} \hline \text{Bad} \\ \hline \\ \hline \end{array}, \dots \right\}$$

- $\llbracket P \rrbracket_{\wp(\Omega)}^B = \{ \omega' \mid \omega \in \hat{\Omega} \wedge \omega \xrightarrow{TR_{\Omega}^B \cup TR_{\Omega}^{Gen(B)}}^* \omega' \}$

Safety

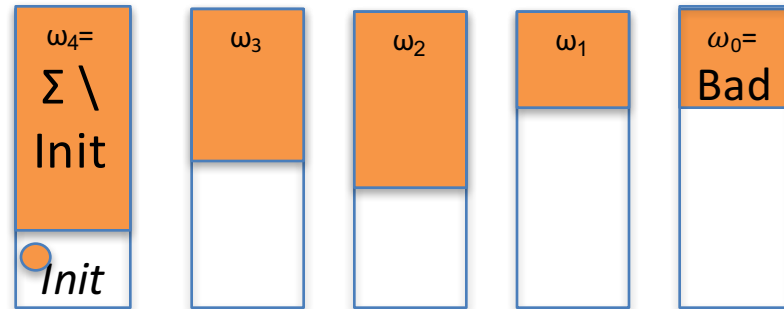
- P is safe iff



$$\notin \llbracket P \rrbracket_{\emptyset}^B(\Omega)$$

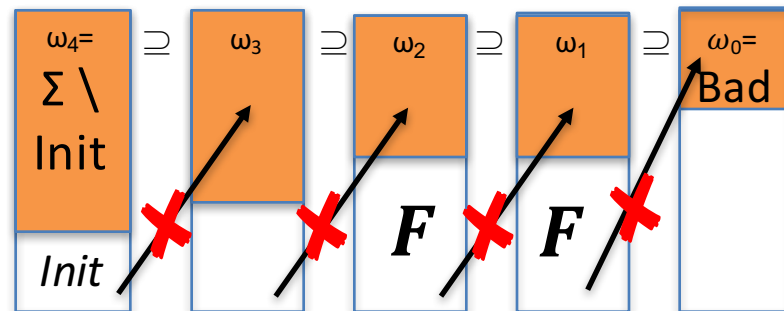
Safety

- P is safe iff



$$\notin \llbracket P \rrbracket_{\emptyset(\Omega)}^B$$

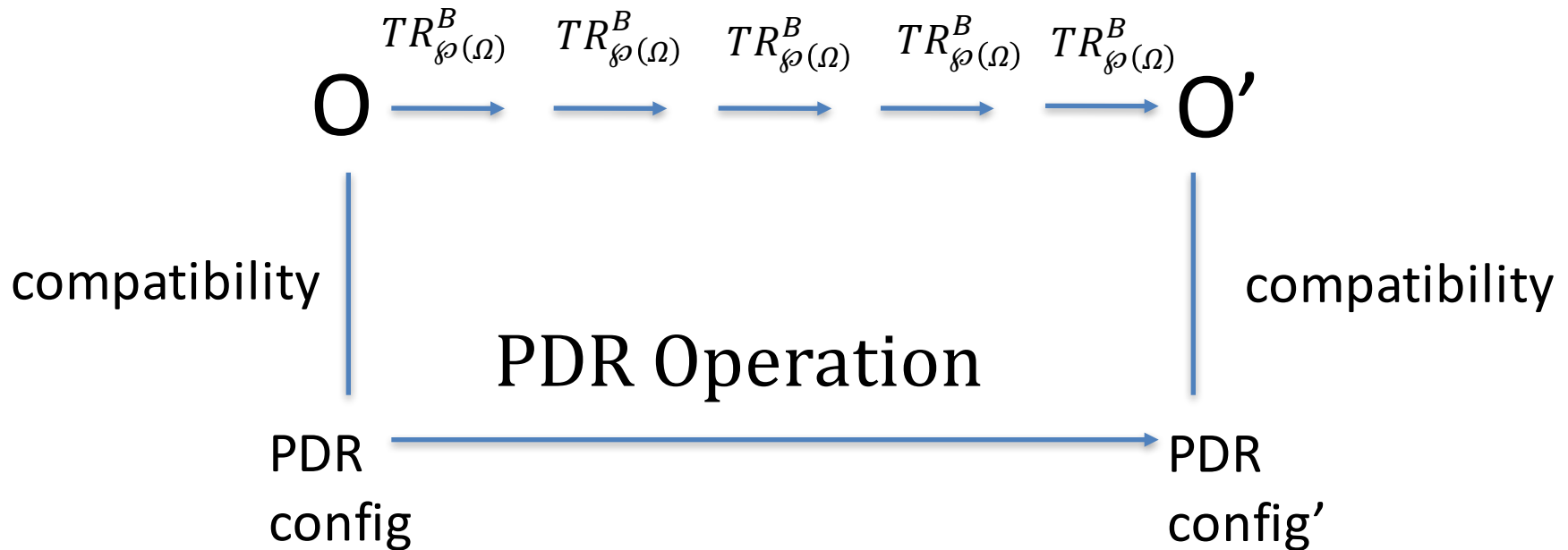
- F is inductive invariant iff



$$\in \llbracket P \rrbracket_{\emptyset(\Omega)}^B$$

PDR as Abstract Interpretation

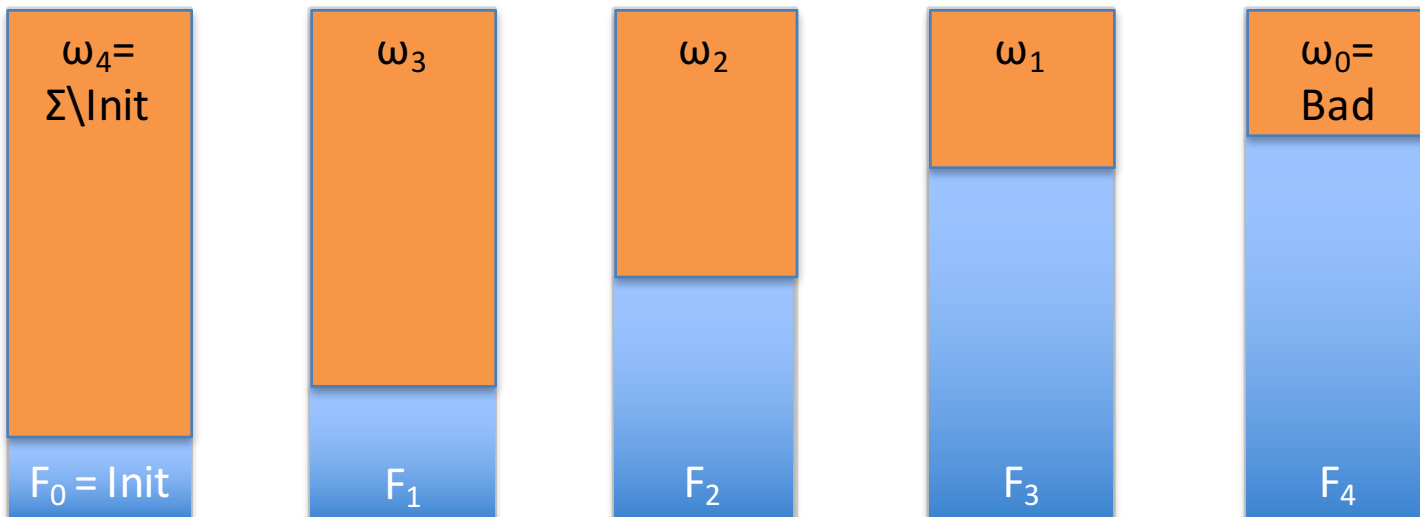
- PDR as interpretation using $\in \llbracket P \rrbracket_{\wp(\Omega)}^B$



Stuttering Simulation

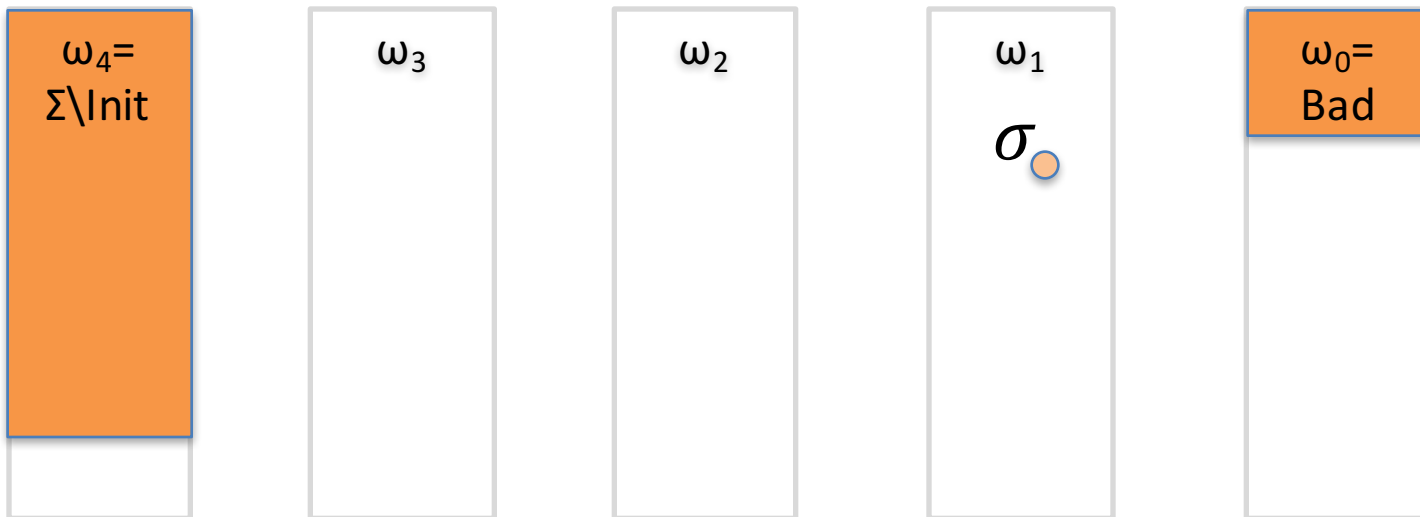
Proof-Compatibility

- An intermediate forward sequence $\langle F_0, \dots, F_N \rangle$ is **proof-compatible** with $\omega \in \Omega$ if
 - $|\omega| = N + 1$
 - $\forall i. F_i = \Sigma \setminus \omega(N - i)$



CEX-Compatibility

- An obligation (σ, i) is **cex-compatible** with $\omega \in \Omega$ if
 - $|\omega| \geq i + 1$
 - $\sigma \in \omega(|\omega| - i - 1)$
- $Q = [\quad (\sigma, 3) \quad]$



Compatibility

- A PDR configuration $\langle N, \langle F_0, \dots, F_N \rangle, q \rangle$ is **compatible** with $O \subseteq \Omega$ if
 - $\exists \omega \in O$ s.t. $\langle F_0, \dots, F_N \rangle$ is proof compatible with ω
 - $\forall (\sigma, i) \in q, \exists$ a cex-compatible $\omega \in O$

PDR as Abstract Interpretation

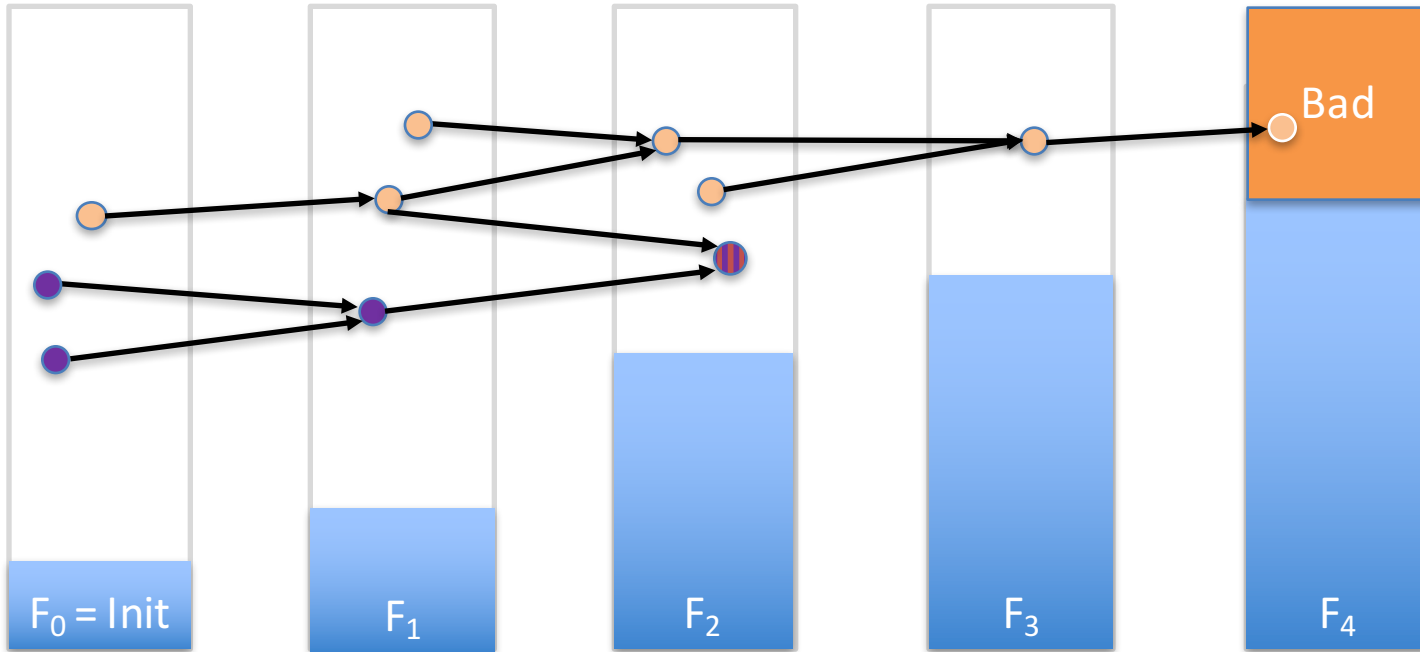
PDR Algorithms interpret the program using $\llbracket P \rrbracket_{\emptyset}^B(\Omega)$

- Stop at
 - Counterexample
 - Inductive invariant

Conclusions

- PDR algorithms can be explained as abstract interpretation using a non standard semantics
 - 2 key operations
- New proof technique for soundness of future PDR algorithms

F_1 is Where the Action Starts



Thank you!